

iE 150

Generator, Mains, and BTB

Data sheet



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1. iE 150 Generator, Mains, and BTB

1.1 About the controllers

1.1.1 About

The iE 150 Generator (Genset), iE 150 Mains, and iE 150 BTB controllers provide flexible protection and control in a wide range of applications.

The iE 150 is a compact, all-in-one controller. Each controller contains all necessary 3-phase measuring circuits.

The values and alarms are shown on the LCD display screen, which is sunlight-readable. Operators can easily control the gensets and breakers from the display units. Alternatively, use the communication options to connect to an HMI/SCADA system. The HMI/SCADA system can then control the plant.

| Controller type | Controls and protects |
|------------------|--|
| iE 150 Generator | <ul style="list-style-type: none">An engine, a generator, and a generator breakerAn engine, generator, generator breaker, and a mains breaker |
| iE 150 Mains | <ul style="list-style-type: none">A mains connection and a mains breakerA mains connection, mains breaker, and a tie breaker |
| iE 150 BTB | A bus tie breaker |

In the simplest applications, you can use one generator controller to control one genset. You can also use generator controllers for CANshare load sharing by multiple gensets (without power management).

Several controllers can work together to make a power management system (PMS). These applications include synchronisation, island operation, and running parallel to mains. The system can automatically start and stop gensets, and open and close breakers. You can also use the controllers in power management systems with other DEIF controllers.

1.1.2 Software versions

The information in this document relates to software version:

| Software | Details | Version |
|----------|------------------------|---------|
| iE 150 | Controller application | 1.35 |

Depending on the controller type, you can use the **Core***, **Sync**, **PM**, or **Premium** software package. The software package determines which functions are supported.

NOTE * If synchronisation is not required, the generator controller can use the **Core** software package (see the **iE 150 Non-sync generator Data sheet**).

1.1.3 Emulation

The controller includes an emulation tool to verify and test the functionality of the application, for example plant modes and logics, breaker handling, mains and generator operation.

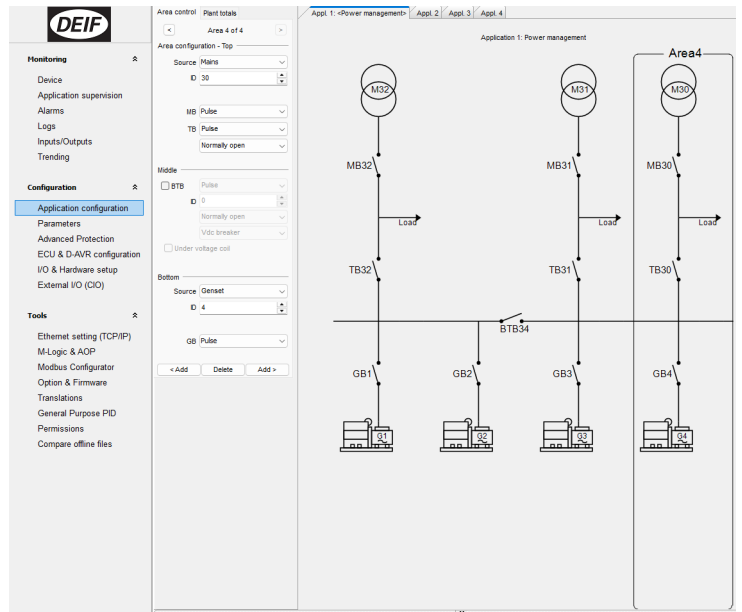
Application emulation is useful for training, customising plant requirements, and for testing basic functionality that needs to be set up or verified.

In a power management system it is possible to control the entire plant, when connected to just one of the controllers.

1.1.4 Easy configuration with the utility software

Set up an application easily with a PC and the utility software. This includes mains feeder handling and operation of the generators.

You can also use the utility software to quickly configure the inputs, outputs, parameters, and settings.



1.2 Functions and features

1.2.1 General controller functions

| AC functions | Sync | PM and Premium |
|--|------------------|------------------|
| Sets of nominal settings | 6 | 6 |
| Select the AC configuration: <ul style="list-style-type: none"> • 3-phase/3-wire • 3-phase/4-wire • 2-phase/3-wire (L1/L2/N or L1/L3/N) • 1-phase/2-wire L1 | ● ● ● ● | ● ● ● ● |
| 100 to 690 V AC (selectable) | ● | ● |
| CT -/1 or -/5 (selectable) | ● | ● |
| 4th current measurement (select one) <ul style="list-style-type: none"> • Mains current (and power) • Tie current (and power) • Neutral current (1 × true RMS) • Ground current (with 3rd harmonic filter) | ● | ● |

| General functions | Sync | PM and Premium |
|---|------------------|------------------|
| Emulation for testing and front load commissioning | ● | ● |
| Built-in test sequences (Simple test, Load test, Full test, and Battery test) | ● | ● |
| PLC logic (M-Logic) | 20 lines | 80 lines |
| Counters, including: <ul style="list-style-type: none"> • Breaker operations • kWh meter (day, week, month, total) • kvarh meter (day, week, month, total) | ● ● ● ● | ● ● ● ● |

| General functions | Sync | PM and Premium |
|--|------|----------------|
| General purpose PID regulators (2 x built-in analogue outputs) | | ● |
| 4 additional analogue outputs (using 2 x IOM 230) | | ● |
| Simple load shedding and adding | | ● |
| Changeable controller type | | ● * |
| Configure and connect AOP-2s (additional operator panel) | 1 | 2 |
| TDU support | | ● |

NOTE * Only for Premium.

| Setting and parameter functions | Sync | PM and Premium |
|--|------|----------------|
| Quick setup (for example, for rental applications) | ● | ● |
| User-defined permission level | ● | ● |
| Password-protected setup | ● | ● |
| Trending with the USW | ● | ● |
| Event logs with password, up to 500 entries | ● | ● |

| Display and language functions | Sync | PM and Premium |
|---|------|----------------|
| Supports multiple languages (including Chinese, Russian, and other languages with special characters) | ● | ● |
| 20 configurable graphical screens | ● | ● |
| Graphical display with six lines | ● | ● |
| Parameters can be changed on the display unit | ● | ● |
| 3 engine function shortcuts | ● | ● |
| 20 configurable shortcut buttons | ● | ● |
| 5 configurable display screen "LED lamps" (on/off/blink) | ● | ● |

| Modbus functions | Sync | PM and Premium |
|--------------------------|------|----------------|
| Modbus RS-485 | ● | ● |
| Modbus TCP/IP | ● | ● |
| Configurable Modbus area | ● | ● |

1.3 Alarms and protections

| Protections | Alarms | ANSI | Operate time | Genset* | Mains | BTB |
|-------------------|--------|------|--------------|---------|-------|-----|
| Reverse power | 3 | 32R | <200 ms | ● | ● | ● |
| Fast over-current | 2 | 50P | <40 ms | ● | ● | ● |
| Over-current | 4 | 50TD | <200 ms | ● | ● | ● |

| Protections | Alarms | ANSI | Operate time | Genset* | Mains | BTB |
|---|-----------|------------------|--------------|---------|-------|-----|
| Voltage dependent over-current | 1 | 50V | | ● | ● | ● |
| Over-voltage | 2 | 59 | <200 ms | ● | ● | ● |
| Under-voltage | 3 | 27P | <200 ms | ● | ● | ● |
| Over-frequency | 3 | 81O | <300 ms | ● | ● | ● |
| Under-frequency | 3 | 81U | <300 ms | ● | ● | ● |
| Unbalance voltage | 1 | 47 | <200 ms | ● | ● | ● |
| Unbalance current | 1 | 46 | <200 ms | ● | ● | ● |
| Under-excitation or reactive power import | 1 | 32RV | <200 ms | ● | | |
| Over-excitation or reactive power export | 1 | 32FV | <200 ms | ● | | |
| Overload** | 5 | 32F | <200 ms | ● | ● | ● |
| Inverse time earth over-current | 1 | 50G | <100 ms | ● | ● | ● |
| Inverse time neutral over-current | 1 | 50N | <100 ms | ● | ● | ● |
| Busbar/mains over-voltage | 3 | 59P | <50 ms | ● | ● | ● |
| Busbar/mains under-voltage | 4 | 27P | <50 ms | ● | ● | ● |
| Busbar/mains over-frequency | 3 | 81O | <50 ms | ● | ● | ● |
| Busbar/mains under-frequency | 3 | 81U | <50 ms | ● | ● | ● |
| Emergency stop | 1 | | <200 ms | ● | | |
| Low auxiliary supply | 1 | 27DC | | ● | ● | ● |
| High auxiliary supply | 1 | 59DC | | ● | ● | ● |
| Generator breaker external trip | 1 | | | ● | | |
| Tie breaker external trip | 1 | | | | ● | ● |
| Mains breaker external trip | 1 | | | | ● | |
| Synchronisation failure alarms | 1/breaker | | | ● | ● | ● |
| Breaker open failure | 1/breaker | 52BF | | ● | ● | ● |
| Breaker close failure | 1/breaker | 52BF | | ● | ● | ● |
| Breaker position failure | 1/breaker | 52BF | | ● | ● | ● |
| Close before excitation failure | 1 | | | ● | | |
| Phase sequence error | 1 | 47 | | ● | ● | ● |
| De-load error | 1 | | | ● | | |
| Hz/V failure | 1 | | | ● | | |
| Not in Auto | 1 | | | ● | ● | ● |
| Vector shift | 1 | 78 | <40 ms | ● | ● | |
| ROCOF df/dt | 1 | 81R | <130 ms | ● | ● | ● |
| Under-voltage and reactive power, U and Q | 2 | | <250 ms | ● | ● | |
| Positive sequence (mains) voltage low | 1 | 27 | <60 ms | ● | ● | |
| Directional over-current | 2 | 67 | <100 ms | ● | ● | |
| Negative sequence voltage high | 1 | 47 | <400 ms | ● | ● | |
| Negative sequence current high | 1 | 46I ₂ | <400 ms | ● | ● | |
| Zero sequence voltage high | 1 | 59U ₀ | <400 ms | ● | ● | |

| Protections | Alarms | ANSI | Operate time | Genset* | Mains | BTB |
|--|--------|------------------|--------------|---------|-------|-----|
| Zero sequence current high | 1 | 50I ₀ | <400 ms | ● | ● | |
| Power-dependent reactive power | 1 | 40 | - | ● | | |
| IEC/IEEE inverse time over-current | 1 | 51 | - | ● | ● | |
| Neutral inverse time over-current (4th CT) | 1 | 51N | - | ● | ● | ● |
| Earth fault inverse time over-current (4th CT) | 1 | 51G | - | ● | ● | ● |
| Neutral over-current (4th CT) | 2 | - | - | ● | ● | ● |
| Earth fault over-current (4th CT) | 2 | - | - | ● | ● | ● |

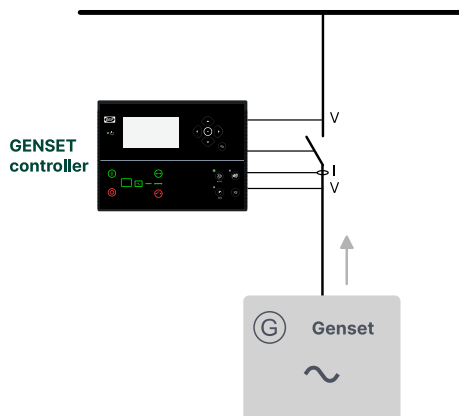
NOTE * See [Generator controller functions](#) for engine protections.

NOTE **You can configure these protections for overload or reverse power.

1.4 Applications

1.4.1 Single generator applications

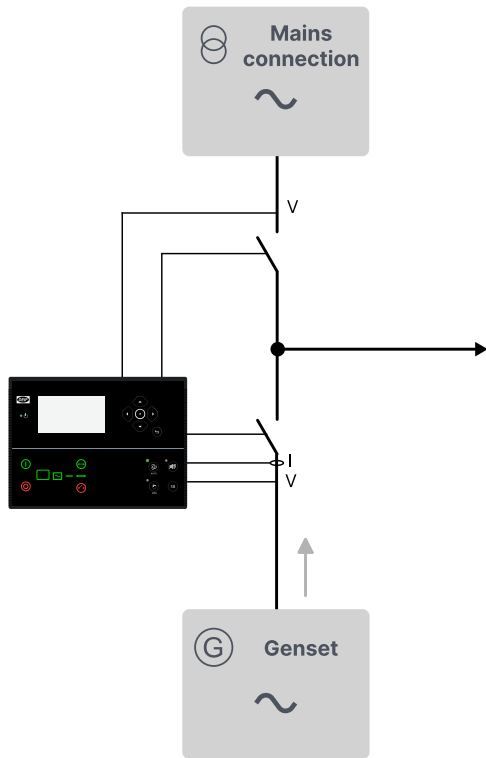
Island mode



Island mode operation is typically used in power plants that are isolated from the national (or local) electricity distribution network. There are two key types of island mode operation:

- Stand-alone generators not connected to the electricity grid.
- Generators connected to the electricity grid in parallel mode. This means that they can generate power independently, and on demand.

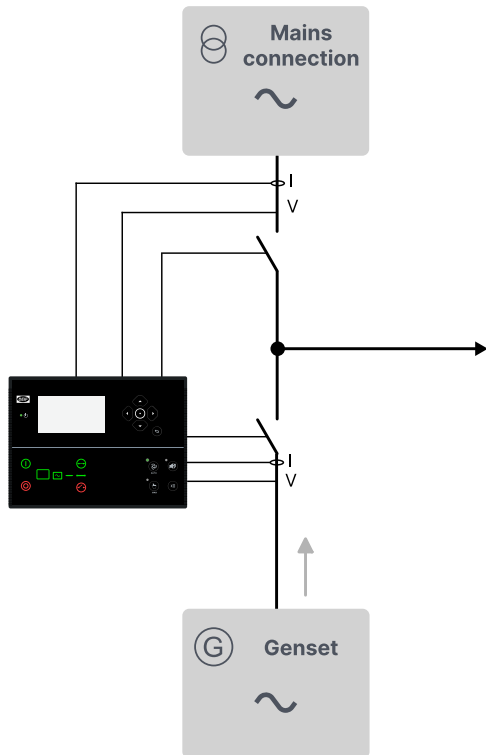
Automatic mains failure (AMF) and fixed power



Automatic Mains Failure (AMF): If there is a significant loss of mains power or a total blackout, the controller automatically changes the supply to the emergency generator. This makes sure that there is power during a mains failure and prevents damage to electrical equipment.

Fixed power: When given a signal, the controller automatically starts the genset and synchronises to the mains. After the generator breaker closes, the controller ramps up the load to the set point level. When the stop command is given, the genset is de-loaded and stopped after the cooling down period.

Peak shaving, load take-over, and mains power export

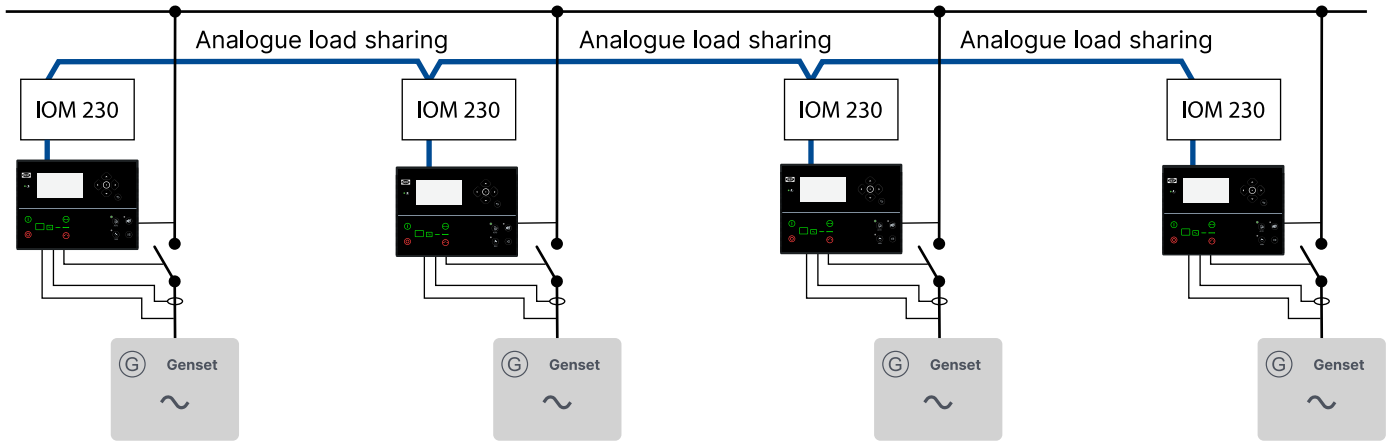


- **Peak shaving:** Power plant where the generator supplies the peak load demand and runs parallel to mains.
- **Load take-over:** Plant mode where the load is moved from mains to generator, for example, during peak demand periods or periods with a risk of power outages.
- **Mains power export:** Power plant with fixed kW set point (excluding increasing load).

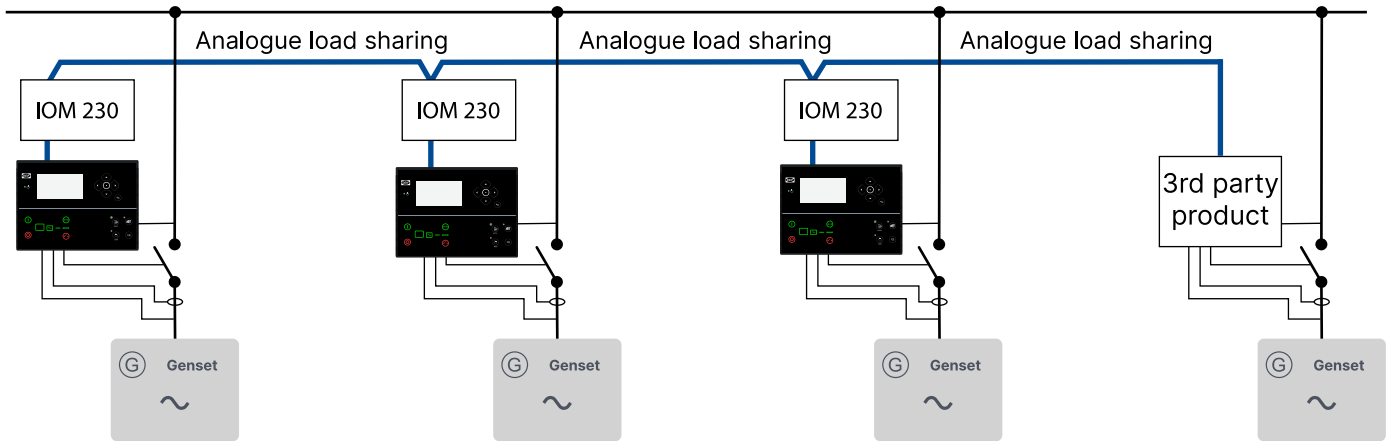
1.4.2 Multiple generator applications

These applications can share the load without using power management. However, the generators do not automatically start, stop, connect, and disconnect.

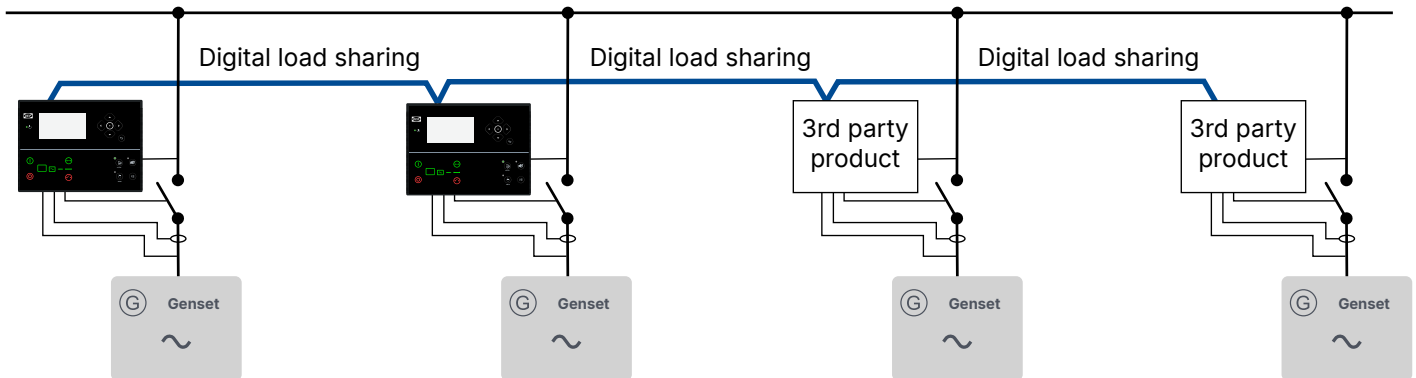
Analogue load sharing (with optional IOM 230 external box)



Analogue load sharing with 3rd party controllers



Multiple single gensets, with third party digital load sharing

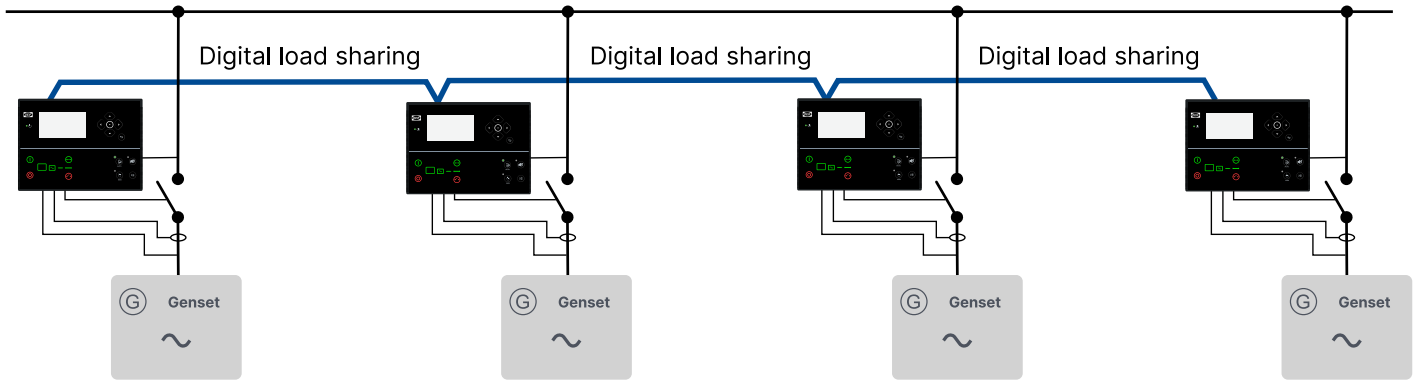


You can have up to 32 iE 150 and third party generator controllers.

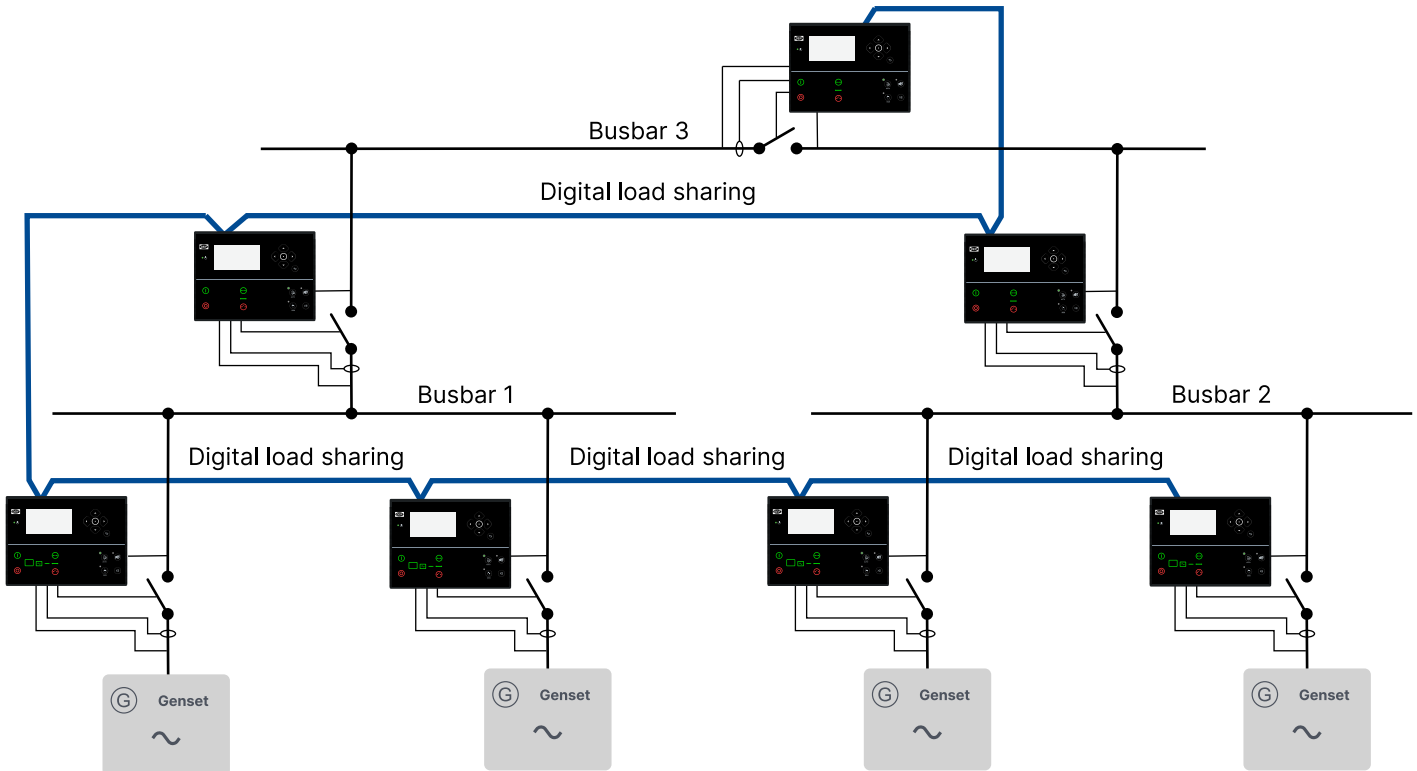
Compatible third party controllers:

- ComAp
- DeepSea MSC7
- SmartGen

Digital load sharing (CANshare) (up to 127 generators)



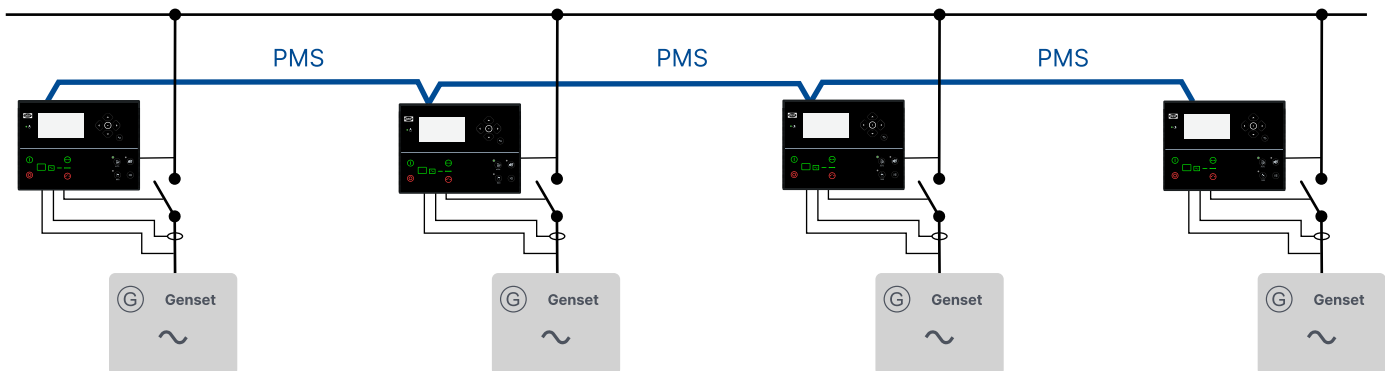
Digital load sharing with bus tie breakers (CANshare) (up to 127 generators, and up to 64 busbars)



1.4.3 Power management applications

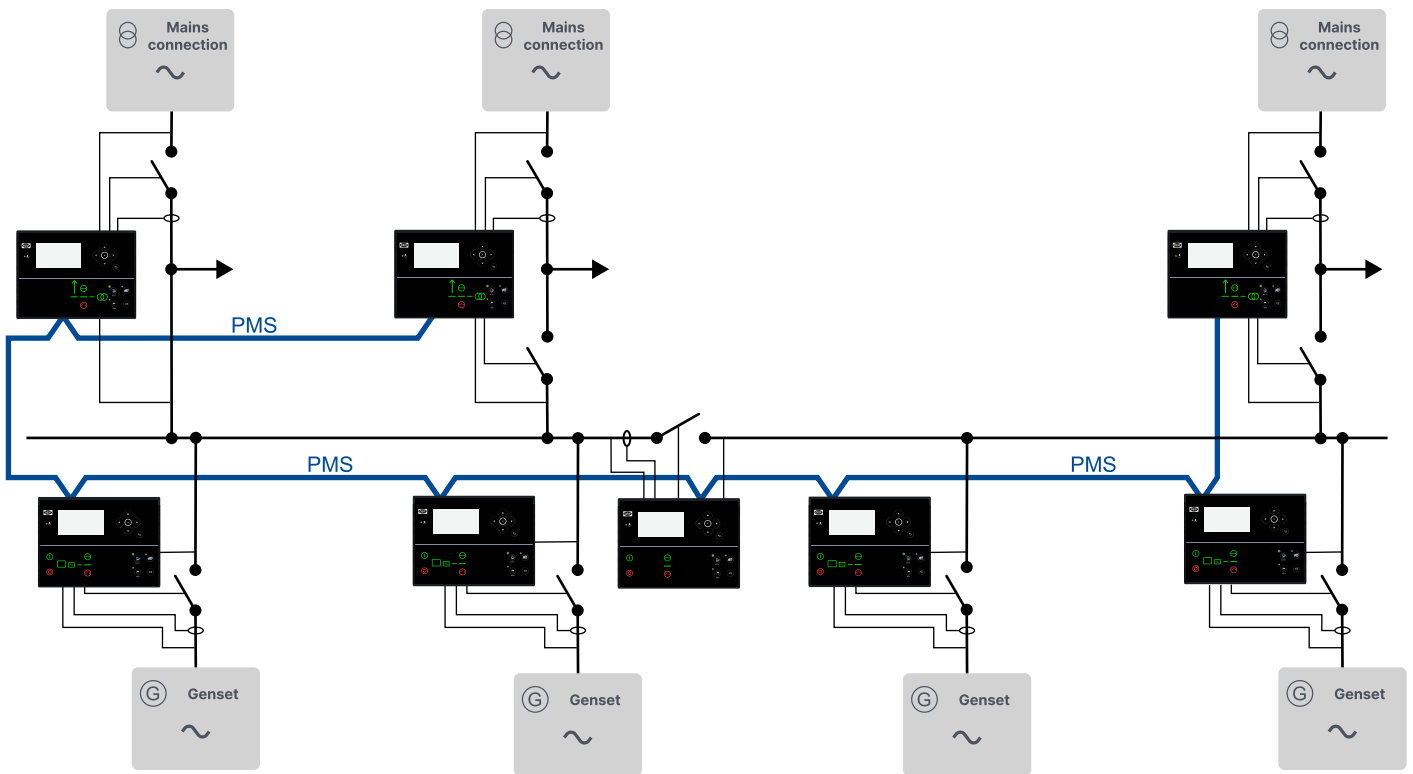
In power management, the controllers have the information that they need to automatically start, stop, connect, and disconnect generators and/or mains. See [Power management](#) for more information.

Island operation in power management

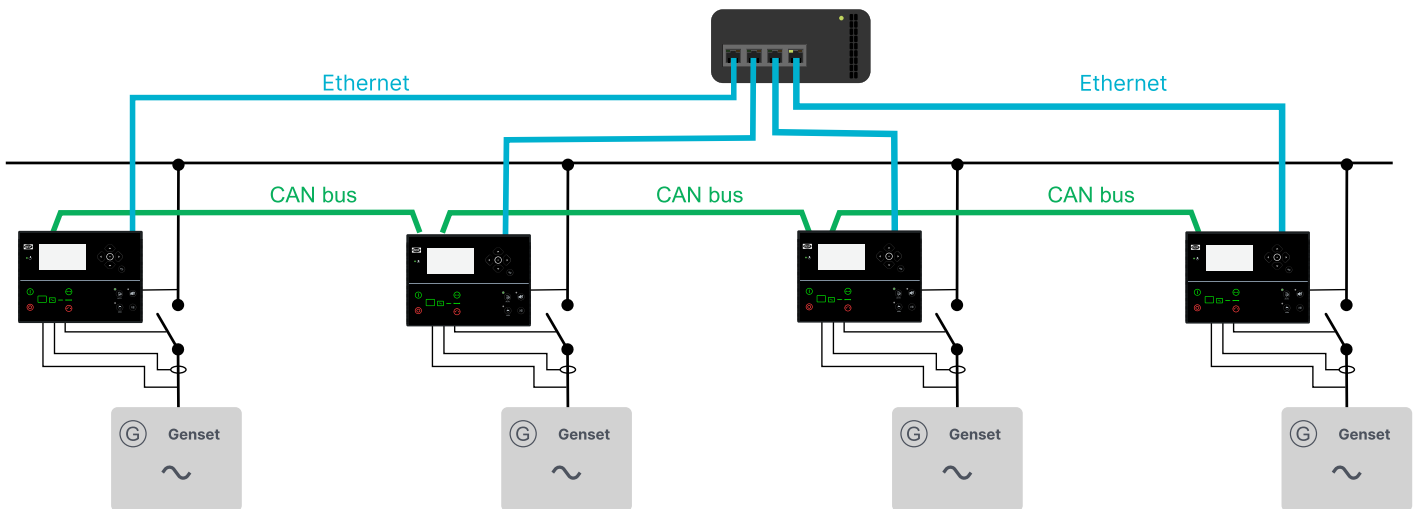


Power plant with synchronising generators. Can also be used in critical power plants with a start signal from an external (ATS) controller.

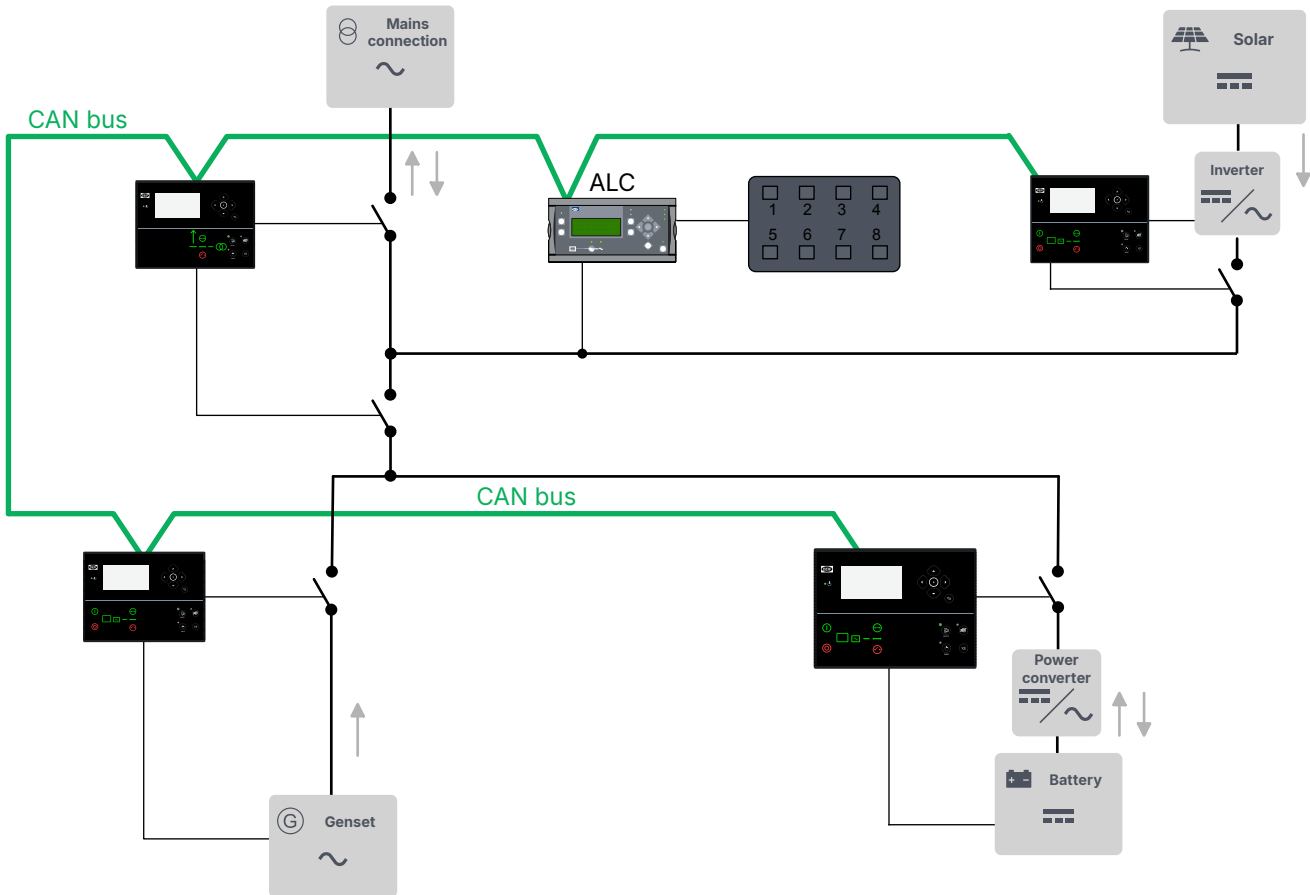
Gensets in power management with three mains and two sections



Using Ethernet backup for power management



iE 150 in power management with solar and battery controllers



NOTE The iE 150 Hybrid genset controller cannot be used in a power management application.

1.5 Power management

1.5.1 Introduction

The power management system automatically supplies the power that is necessary for the load efficiently, safely and reliably.

The power management system:

- Automatically starts and stops generators
- Automatically closes and opens breakers
- Optimises the fuel consumption
- Balances the loads in the system
- Deploys plant logic
- Makes sure that the system is safe

You can monitor the complete power management system from a graphical supervision page in the utility software. You can also see running status, hours in operation, breaker status, the condition of the mains and busbars, fuel consumption, and so on.

Multi-master system

The power management system is a multi-master system, for increased reliability. In a multi-master system all vital data is transmitted between the controllers, so that all the controller know the power management status (calculations and position) in the application. As a result, the application does not have a single master controller.

Busbar sections

The plant can be divided by one to eight bus tie breakers. This makes it possible to run different sections of the plant in different plant modes. For example, you can use this to test a section, or to divide the load into primary and secondary loads.

1.5.2 Power management plant modes

The plant modes are configurable and can be changed at any time. All modes can be combined with Automatic Mains Failure mode (AMF). You can use the controllers for the following applications:

| Standard plant modes | Applications |
|-------------------------|--|
| Island mode | Power plant with synchronising generators. |
| Automatic Mains Failure | Critical power/emergency standby plants, black start generator. |
| Fixed power | Power plant with fixed kW set point (including building load). |
| Peak shaving | Power plant where generator supplies peak load demand paralleled to the mains. |
| Load take-over | Plant mode where the load is moved from mains to generator. For example, peak demand periods, or periods with a risk of power outages. |
| Mains power export | Power plant with fixed kW set point (excluding building load). |

1.5.3 Power management features

| Power management features | Sync | PM and Premium |
|---|------|----------------|
| Power management operation*: | | |
| • Number of generator controllers | 16 | 32 |
| • Number of mains controllers | 8 | 32 |
| • Number of BTB controllers | 8 | 8 |
| • Number of solar controllers | 16 | 16 |
| • Number of battery (BESS) controllers | 16 | 16 |
| • Number of load controllers (ALC-4) | 8 | 8 |
| Load controller support (compatible with ALC-4) | | ● |
| Genset load-dependent start and stop | ● | ● |
| EasyConnect | ● | ● |
| Asymmetrical genset load sharing | | ● |
| Secured mode | | ● |
| Genset priority selection: | | |
| • Manual | ● | ● |
| • Running hours | ● | ● |
| • Fuel optimisation | | ● |
| Safety stop of genset | ● | ● |
| PLC-controlled power management possible | ● | ● |
| Redundant PMS via Ethernet | | ● |

* Restrictions on controllers

| ID 1 to 24 | ID 25 to 32 | ID 33 to 40 |
|------------------|--------------------|----------------------|
| Genset (1 to 32) | | |
| Mains (1 to 32) | | |
| | Solar (25 to 40) | |
| | Battery (25 to 40) | |
| | ALC-4 (25 to 40) | |
| | | BTB (33-40) |
| | | External BTB (33-40) |

Alternatives to power management

iE 150 PMS lite: For simple load sharing and power management over CANshare, for up to 256 generators and/or BTBs. Only for generators - other power sources are not possible. You can also use AGC 150 PMS lite and AGC-4 Mk II generator controllers for PMS lite. See the **iE 150 PMS lite Data sheet**.

iE 150 Hybrid genset: For a system that includes gensets, up to 16 inverters, and a mains connection. If there is a mains, there can be one genset. If there is no mains, there can be up to two synchronising gensets, or up to four non-synchronising gensets. See the **iE 150 Hybrid genset Data sheet**.

Open PMS: Used to add solar, storage, and/or mains controllers to brownfield sites that have genset and/or mains controllers from other suppliers. You can use iE 150 Generator controllers as external gensets.

1.6 Compatible products

1.6.1 Touch display unit: TDU

TDU is a pre-programmed touch screen display (www.deif.com/products/tdu-series). The TDU can be used for these controllers:

- iE 150 Generator, Mains, and BTB
- iE 150 Solar and Storage
- AGC 150 Generator, Mains, and BTB
- ASC 150 Solar and Storage
- AGC-4 Mk II Generator, Mains, and BTB
- ASC-4 Solar and Battery
- AGC-4 Generator, Mains, and BTB

1.6.2 Power management

You can use these controllers together in a power management system:

- **iE 150 Generator** (www.deif.com/documentation/ie-150)
- **iE 150 Mains** (www.deif.com/documentation/ie-150)
- **iE 150 BTB** (www.deif.com/documentation/ie-150)
- **iE 150 Battery** (www.deif.com/documentation/ie-150)
- **iE 150 Solar** (www.deif.com/documentation/ie-150)
- **AGC 150 Generator** (www.deif.com/products/agc-150-generator)
- **AGC 150 Mains** (www.deif.com/products/agc-150-mains)

- **AGC 150 BTB** (www.deif.com/products/agc-150-btb)
- **ASC 150 Solar** (www.deif.com/products/asc-150-solar)
- **ASC 150 Storage** (www.deif.com/products/asc-150-storage)
- **AGC-4 Mk II Genset, Mains, BTB, Group, and Plant** (www.deif.com/products/agc-4-mk-ii)
- **AGC-4 Genset, Mains, BTB, Group, and Plant** (www.deif.com/products/agc-4)
- **ASC-4 Solar** (www.deif.com/products/asc-4-solar)
- **ASC-4 Battery** (www.deif.com/products/asc-4-battery)
- **ALC-4 (Automatic Load Controller)** (www.deif.com/products/alc-4)

1.6.3 Open PMS

You can use these controllers together in an open power management system:

- **iE 150 Battery, Solar, Mains** (www.deif.com/products/ie-150)
- **ASC 150 Solar** (www.deif.com/products/asc-150-solar)
- **ASC 150 Storage** (www.deif.com/products/asc-150-storage)
- **AGC 150 Mains** (www.deif.com/products/agc-150-mains)
- **ASC-4 Solar** (www.deif.com/products/asc-4-solar)
- **ASC-4 Battery** (www.deif.com/products/asc-4-battery)
- **AGC-4 Mk II Mains** (www.deif.com/products/agc-4-mk-ii)

You can also use **iE 150 Generator**, **AGC 150 Generator**, **AGC-4 Mk II Genset**, and/or **AGC-4 Genset** as external gensets. That is, the genset controllers are not part of the open PMS. They can send their power measurements to the open PMS controllers over CAN bus.

1.6.4 Remote monitoring service: Insight

Insight is a responsive remote monitoring service (www.deif.com/products/insight). It includes real-time genset data, a customisable dashboard, GPS tracking, equipment and user management, email and/or SMS alerts, and cloud data management.

1.6.5 Digital voltage controllers

DVC 350 is a digital AVR designed for alternators with SHUNT, AREP, or PMG excitation. The DVC 350 monitors and regulates the alternator output voltage. The controller can control the DVC 350 features and receive fault information directly with the CAN bus communication. For more information, see www.deif.com/products/dvc-350

DVC 550 is an advanced digital AVR designed for alternators with SHUNT, AREP, or PMG excitation. The DVC 550 monitors and regulates the alternator output voltage. The controller can control all the DVC 550 features and receive fault information directly with the CAN bus communication. For more information, see www.deif.com/products/dvc-550

1.6.6 Additional inputs and outputs

The controller uses CAN bus communication with these:

- **CIO 116** is a remote input expansion module. See www.deif.com/products/cio-116
- **CIO 208** is a remote output expansion module. See www.deif.com/products/cio-208
- **CIO 308** is a remote I/O module. See www.deif.com/products/cio-308
- **IOM 220** and **IOM 230** each have two analogue outputs. These can be used for governor and AVR regulation, or general PID control. See www.deif.com/products/iom-200230

1.6.7 Additional operator panel, AOP-2

The controller uses CAN bus communication to the additional operator panel (AOP-2). Configure the controller using M-Logic. On the AOP-2, the operator can then:

- Use the buttons to send commands to the controller.
- See LEDs light up to show statuses and/or alarms.

You can configure and connect two AOP-2s if the controller has the premium software package.

1.6.8 Remote display: iE 150

The remote display is an iE 150 that only has a power supply and an Ethernet connection to an iE 150 controller. The remote display allows the operator to see the controller's operating data, as well as operate the controller remotely.

1.6.9 Shutdown unit, SDU 104

The SDU 104 is a safety device for the protection of engines. The unit keeps the engine running if the main controller fails. The unit can also safely shut down the engine.

See www.deif.com/products/sdu-104

1.6.10 Other equipment

DEIF has a wide variety of other equipment that is compatible. Here are some examples:

- **Synchrosopes**
 - **CSQ-3** (www.deif.com/products/csq-3)
- **Battery chargers/power supplies**
 - **DBC-1** (www.deif.com/products/dbc-1)
- **Current transformers**
 - **ASK** (www.deif.com/products/ask-asr)
 - **KBU** (www.deif.com/products/kbu)
- **Transducers**
 - **MTR-4** (www.deif.com/products/mtr-4)

1.6.11 Controller types

| Parameter | Setting | Controller type | Minimum software |
|-----------|----------------------|---|------------------|
| 9101 | Genset unit | Non-sync generator controller | Core |
| | Genset unit | Generator controller | Sync |
| | Mains unit | Mains controller | Sync |
| | Bus Tie Breaker unit | BTB controller | Sync |
| | Genset Hybrid unit | Hybrid Genset-Solar controller | Core |
| | Engine Drive unit | Engine drive controller | Core |
| | Remote display unit | Remote display | None |
| | Battery unit | Battery storage controller | Premium |
| | Solar unit | Solar controller | Premium |
| | ATS unit | Automatic transfer switch (open transition) | Core |
| | ATS unit | Automatic transfer switch (closed transition) | Sync |
| | Genset PMS lite unit | PMS lite controller | Sync |

Software packages and controller types

The controller software package determines which functions the controller can use.

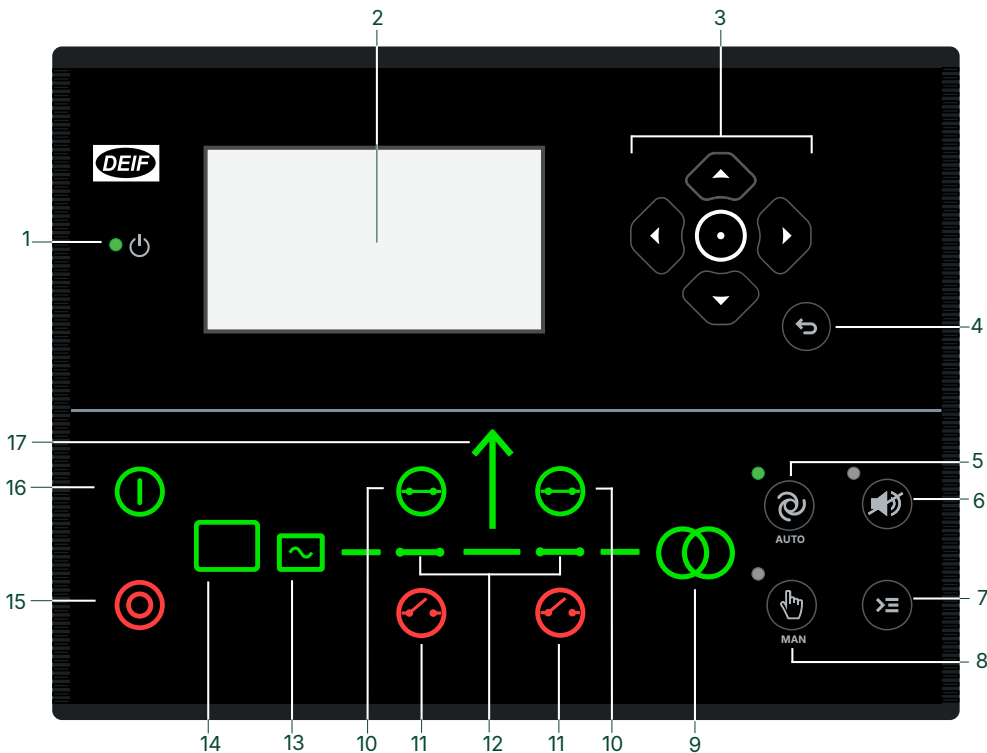
- **Core**
 - You can change the controller type to any other controller that uses **Core**.
 - **Core** software only supports non-synchronisation applications.
- **Sync**
 - You cannot change the controller type.
 - **Sync** software supports synchronisation applications.
- **PM** (power management)
 - You cannot change the controller type.
- **Premium**
 - You can change the controller type to any other controller type.
 - All functions are supported.







You can select the controller type under `Basic settings > Controller settings > Type`.





NOTE For the iE 150 Marine controllers, see www.deif.com/products/ie-150-marine.

2. iE 150 Generator controller

2.1 Display layout



| No. | Name | Function |
|-----|---|---|
| 1 | Power | Green: The controller power is ON. OFF: The controller power is OFF. |
| 2 | Display screen | Resolution: 240 x 128 px. Viewing area: 88.50 x 51.40 mm. Six lines, each with 25 characters. |
| 3 | Navigation | Move the selector up, down, left, and right on the screen. |
| |  Enter button | Go to the Menu system. Confirm the selection on the screen. |
| 4 |  Back button | Go to the previous page. |
| 5 |  AUTO mode | Use to switch to AUTO mode. The controller automatically starts and stops (and connects and disconnects) gensets. No operator actions are needed. The controllers use the power management configuration to automatically select the power management action. |
| 6 |  Silence horn | Stops an alarm horn (if configured) and enters the Alarm menu. |
| 7 |  Shortcut menu | Access the Engine and General shortcuts, Jump menu, Mode selection, Test, and Lamp test. |
| 8 |  MANUAL mode | Use to switch to MANUAL mode. The operator or an external signal can start, stop, connect, or disconnect the genset. The generator controller cannot automatically perform these actions. The controller automatically synchronises before closing a breaker, and automatically deloads before opening a breaker. |
| 9 | Mains symbol | Green: Mains voltage and frequency are OK. The controller can synchronise and close the breaker. Red: Mains voltage and/or frequency are not OK. |

| No. | Name | Function |
|-----|---|---|
| 10 |  Close breaker | Push to close the breaker. |
| 11 |  Open breaker | Push to open the breaker. |
| 12 | Breaker symbols | Green: Breaker is closed. Green flashing: Synchronising or deloading. Red: Breaker failure. |
| 13 | Generator | Green: Generator voltage and frequency are OK. The controller can synchronise and close the breaker. Green flashing: Generator voltage and frequency are OK, but the V&Hz OK timer is still running. The controller cannot close the breaker. Red: Generator voltage and/or frequency are not OK. |
| 14 | Engine | Green: There is running feedback. Green flashing: The engine is getting ready. Red: The engine is not running, or there is no running feedback. |
| 15 |  Stop | Stops the genset if MANUAL or NoReg is selected. |
| 16 |  Start | Starts the genset if MANUAL or NoReg is selected. |
| 17 | Load symbol | OFF: Power management application. Green: The supply voltage and frequency are OK. Red: Supply voltage/frequency failure. |

2.2 Generator controller functions

Genset functions

| Synchronising functions | Sync | PM and Premium |
|-------------------------|------|----------------|
| Synchronising (dynamic) | ● | ● |
| Synchronising (static) | | ● |
| CBE (run up sync) | | ● |
| Short-time parallel | ● | ● |

| Generator functions | Sync | PM and Premium |
|---|------|----------------|
| Built-in analogue AVR control | ● | ● |
| External analogue AVR control via IOM 230 | ● | ● |
| Digital AVR control: Remote configuration, DVC - DEIF | ● | ● |
| Digital AVR control: Voltage biasing and remote configuration, DVC 550 - DEIF | ● | ● |
| Digital AVR control: Voltage biasing, Nidec D550 | ● | ● |
| Digital AVR control: Voltage biasing and remote configuration, Nidec D550 | | ● |
| Step-up transformer (with phase angle compensation) | | ● |
| Communication with KWG ISO5 isolation monitor (CAN bus) | ● | ● |

| Advanced AC protections | Sync | PM and Premium |
|--|------|----------------|
| Vector shift | | ● |
| ROCOF (df/dt) | | ● |
| Under-voltage and reactive power, U and Q | | ● |
| Average busbar over-voltage | | ● |
| AC directional over-current protection | | ● |
| Negative sequence current (ANSI 46I ₂) | | ● |
| Negative sequence voltage (ANSI 47) | | ● |
| Zero sequence current (ANSI 51I ₀) | | ● |
| Zero sequence voltage (ANSI 59U ₀) | | ● |
| Power-dependent reactive power (ANSI 40) | | ● |
| Inverse time over-current (ANSI 51) | | ● |
| Grid support (frequency-dependent droop) | | ● |
| Ground relay | | ● |

| 4th current transformer measurement | Sync | PM and Premium |
|-------------------------------------|------|----------------|
| High current alarms | 2 | 2 |
| High reverse alarms | 2 | 2 |
| High power alarms | 2 | 2 |

| Additional genset modes | Sync | PM and Premium |
|-------------------------|------|----------------|
| Ventilation | ● | ● |
| Dry alternator | ● | ● |

| Load sharing | Sync | PM and Premium |
|---|------|----------------|
| Equal load sharing via power management | ● | ● |
| Analogue load sharing (with IOM 230) | ● | ● |
| Digital load sharing (CANshare) | ● | ● |
| 3rd party load sharing | ● | ● |

Engine functions

| Start and stop functions | Sync | PM and Premium |
|------------------------------------|------|----------------|
| Engine start and stop sequences | ● | ● |
| Temperature-dependent cooling down | ● | ● |
| Time-based cooling down | ● | ● |
| Configurable crank and run coil | ● | ● |

| Regulation functions | Sync | PM and Premium |
|---|------|----------------|
| Governor regulation using: <ul style="list-style-type: none"> Engine communication Built-in analogue control External analogue control using IOM 230 Relays | ● | ● |
| Manual speed control using: <ul style="list-style-type: none"> Digital inputs Display screen menu (by the operator) Analogue input Modbus Configured set point | ● | ● |
| Speed sensing using CAN, MPU, or frequency | ● | ● |
| Derate engine | | ● |
| Ventilation fan control | | ● |
| Power ramp up and down | ● | ● |

| Engine protections | Alarms | ANSI | Operate time |
|-------------------------------|----------|------|--------------|
| Overspeed | 2 | 12 | <400 ms |
| Crank failure | 1 | 48 | |
| Running feedback error | 1 | 34 | |
| MPU wire break | 1 | - | |
| Start failure | 1 | 48 | |
| Stop failure | 1 | - | |
| Stop coil, wire break alarm | 1 | - | |
| Engine heater | 1 | 26 | |
| Max. ventilation/radiator fan | 1 | - | |
| Fuel fill check | 1 | - | |
| Maintenance alarms | Multiple | | |

| Other engine functions | Sync | PM and Premium |
|--|------|----------------|
| Fuel usage monitoring | ● | ● |
| Fuel pump monitoring, logic, and refill | ● | ● |
| Diesel exhaust fluid monitoring, logic, and refill | ● | ● |
| Generic fluid monitoring, logic, and refill | ● | ● |

2.3 Supported ECUs and engines

The controller can communicate with the following ECUs and engines.

| Manufacturer | ECUs | Engines | Tier 4/Stage V | Controller setting Engine I/F [7561] |
|---------------|--|--|----------------|---|
| Generic J1939 | Any ECU that uses J1939 | Any engine that uses J1939 | ● | Generic J1939 |
| ANGLE | - | - | - | ANGLE |
| Baudouin | CPCB IV | - | - | Baudouin CPCB IV |
| Baudouin | WOODWARD PG+ | - | - | Baudouin Gas |
| Baudouin | Wise 10B | - | - | Baudouin Wise10B |
| Baudouin | Wise 15 | - | ● | Baudouin Wise15 |
| Bosch | EDC17 | - | - | Bosch EDC17CV54TMTL |
| Caterpillar | ADEM3 | C4.4, C6.6, C9, C15, C18, C32, 3500, 3600 | - | Caterpillar ADEM3 |
| Caterpillar | ADEM4 | C4.4, C6.6, C9, C15, C18, C32, 3500, 3600 | - | Caterpillar ADEM4 |
| Caterpillar | ADEM5 | - | - | Caterpillar ADEM5 |
| Caterpillar | ADEM6 | - | - | Caterpillar ADEM6 |
| Caterpillar | ADEM3, ADEM4 | C4.4, C6.6, C9, C15, C18, C32, 3500, 3600 | - | Caterpillar Generic* |
| Caterpillar | - | - | - | Caterpillar with C7.1 AT |
| Cummins | CM 500 | QSL, QSB5, QSX15 and 7, QSM11, QSK 19/23/50/60 | - | Cummins CM500 |
| Cummins | CM 558 | QSL, QSB5, QSX15 and 7, QSM11, QSK 19/23/50/60 | - | Cummins CM558 |
| Cummins | CM 570 | QSL, QSB5, QSX15 and 7, QSM11, QSK 19/23/50/60 | - | Cummins CM570 |
| Cummins | Cummins CM 570 Industrial | - | ● | Cummins CM570 Industrial |
| Cummins | CM 850 | QSL, QSB5, QSX15 and 7, QSM11, QSK 19/23/50/60 | - | Cummins CM850 |
| Cummins | CM 2150 | QSL, QSB5, QSX15 and 7, QSM11, QSK 19/23/50/60 | ● | Cummins CM2150 |
| Cummins | CM 2250 | QSL, QSB5, QSX15 and 7, QSM11, QSK 19/23/50/60 | ● | Cummins CM2250 |
| Cummins | CM 2350 | - | ● | Cummins CM2350 |
| Cummins | CM 2350 Industrial | - | ● | Cummins CM2350 Industrial |
| Cummins | CM 2358 | - | ● | Cummins CM2358 |
| Cummins | CM 2850 | - | ● | Cummins CM2850 |
| Cummins | CM 2880 | - | ● | Cummins CM2880 |
| Cummins | CM 2880 Industrial | - | ● | Cummins CM2880 Industrial |
| Cummins | CM 500, CM 558, CM 570, CM 850, CM 2150, and CM 2250 | QSL, QSB5, QSX15 and 7, QSM11, QSK 19/23/50/60 | ECU-dependent | Cummins Generic* |
| Cummins | - | Industrial | - | Cummins Generic Industrial |
| Cummins | - | KTA19 | - | Cummins KTA19 |

| Manufacturer | ECUs | Engines | Tier 4/Stage V | Controller setting Engine I/F [7561] |
|----------------|---------------------------------|--|----------------|---|
| Cummins | PGI | - | ● | Cummins PGI |
| Detroit Diesel | DDEC III | Series 50, 60, and 2000 | - | DDEC III |
| Detroit Diesel | DDEC IV | Series 50, 60, and 2000 | - | DDEC IV |
| Detroit Diesel | DDEC III, DDEC IV | Series 50, 60, and 2000 | - | DDEC Generic* |
| Deutz | EMR2 | - | - | Deutz EMR 2 |
| Deutz | EMR3 | - | - | Deutz EMR 3 |
| Deutz | EMR4 | - | - | Deutz EMR 4 |
| Deutz | EMR4 Stage V | - | ● | Deutz EMR 4 Stage V |
| Deutz | EMR5 | - | - | Deutz EMR 5 |
| Deutz | EMR5 Stage V | - | ● | Deutz EMR 5 Stage V |
| Deutz | EMR 2, EMR 3 | - | - | Deutz EMR Generic* |
| Doosan | EDC17 | - | - | Doosan G2 EDC17 |
| Doosan | MD1 | - | ● | Doosan MD1 |
| Doosan | G2 EDC17 | - | ● | Doosan stage 5 |
| FPT Industrial | EDC17 | - | - | FPT EDC17CV41 |
| FPT Industrial | Bosch MD1 | - | ● | FPT stage V |
| Guascor | GCS-e ECU | - | - | Guascor GCS |
| Hatz Diesel | - | 3/4H50 TICD | ● | Hatz |
| Hatz Diesel | EDC17 | - | - | Hatz EDC17 |
| Isuzu | ECM | 4JJ1X, 4JJ1T, 6WG1X FT-4 | - | Isuzu |
| Iveco | CURSORS | - | - | Iveco CURSOR |
| Iveco | EDC7 (Bosch MS6.2), | - | - | Iveco EDC7 |
| Iveco | CURSORS, NEF, EDC7, VECTOR 8 | - | ●** | Iveco Generic* |
| Iveco | NEF | - | - | Iveco NEF |
| Iveco | Bosch MD1 | - | ● | Iveco Stage V |
| Iveco | Iveco NEF67 | - | ● | Iveco Stage V NEF67 |
| Iveco | VECTOR 8 | - | - | Iveco Vector8 |
| JCB | - | ECOMAX DCM3.3+ | ● | JCB |
| JCB | - | P745 & P740 DieselMax Stage V Version 7 | ● | JCB 430/448 Stage V |
| Jichai | JC15D-ECU22 | - | - | JC15D Weifu*** |
| Jichai | JC15D WYS | - | - | JC15D WYS |
| Jichai | JC190 | - | - | JC190 |
| Jichai | JC15T JG | - | - | Jichai JC15T JG |
| Jing Guan | - | Gas | - | Jing Guan |
| John Deere | JDEC | PowerTech M, E, and Plus | ● | John Deere |
| John Deere | FOCUS controls (version 2.1) | - | ● | John Deere Stage V |

| Manufacturer | ECUs | Engines | Tier 4/Stage V | Controller setting Engine I/F [7561] |
|------------------------|---|--|-------------------|---|
| Kingbang | | | ● | Kingbang |
| Kohler | ECU2-HD | KD62V12 | ● | Kohler KD62V12 |
| Kohler | - | KDI 3404 | - | Kohler KDI 3404 |
| Kubota | KORD3 | - | ● | Kubota Stage V |
| MAN | EDC17 | - | | MAN EDC17 |
| MAN | EMC 2.0 | - | - | MAN EMC Step 2.0 |
| MAN | EMC 2.5 | - | - | MAN EMC Step 2.5 |
| MAN | EMC 2.0, EMC 2.5 | - | - | MAN Generic* |
| MTU | MDEC module M.201 | - | | MDEC 2000/4000 M.201 |
| MTU | MDEC module M.302 | Series 2000 and 4000 | - | MDEC 2000/4000 M.302 |
| MTU | MDEC module M.303 | Series 2000 and 4000 | - | MDEC 2000/4000 M.303 |
| MTU | MDEC module M.304 | - | | MDEC 2000/4000 M.304 |
| MTU | ADEC | Series 2000 (ECU7), Series 4000 (ECU7), and MTU PX | - | MTU ADEC |
| MTU | ADEC, ECU7 without SAM module (software module 501) | Series 2000 and 4000 | - | MTU ADEC module 501 |
| MTU | ECU7 with SAM module | Series 2000 (ECU7), Series 4000 (ECU7), and MTU PX | - | MTU ECU7 with SAM |
| MTU | ECU8 | - | - | MTU ECU8 |
| MTU | ECU9 | - | ● | MTU ECU9 |
| MTU | ECU9 EMINOX | - | ● | MTU ECU9 EMINOX |
| MTU | J1939 Smart Connect, ECU8, ECU9 | Series 1600 | ● (ECU9 or later) | MTU J1939 Smart Connect |
| Perkins | ADEM3 | - | - | Perkins ADEM3 |
| Perkins | ADEM4 | - | - | Perkins ADEM4 |
| Perkins | CPCB IV | | | Perkins CPCB IV |
| Perkins | EDC17 | - | - | Perkins EDC17C49 |
| Perkins | ADEM3, ADEM4 | Series 850, 1100, 1200, 1300, 2300, 2500, and 2800 | - | Perkins Generic* |
| Perkins | - | Series 400 and 1200 | ● | Perkins Stage V |
| Perkins | - | Series 400 Model IQ IR IW IY IF | ● | Perkins StV 400 |
| Perkins | - | Series 1200F Model MT, MU, MV, MW, BM, and BN | ● | Perkins StV 1200 |
| Perkins | - | Series 1200J Model SU, VM | ● | Perkins StV 120xJ (SU/VM) |
| PSI/Power Solutions | - | PSI/Power Solutions | ● | PSI/Power Solutions |
| QiYao | - | - | - | QiYao Gas |

| Manufacturer | ECUs | Engines | Tier 4/Stage V | Controller setting Engine I/F [7561] |
|---------------|--------------------------|--|---------------------------|---|
| Scania | EMS | - | - | Scania EMS |
| Scania | EMS S6 (KWP2000) | Dx9x, Dx12x, Dx16x | - | Scania EMS 2 S6 |
| Scania | EMS 2 S8 | DC9, DC13, DC16 | ● | Scania EMS 2 S8 |
| Scania | EMS S6 (KWP2000) | Dx9x, Dx12x, Dx16x industrial engines | - | Scania S6 Industrial |
| Scania | EMS 2 S8 | DC9, DC13, DC16 industrial engines | ● | Scania S8 Industrial |
| SDEC | F20 | - | - | SDEC F20 |
| SDEC | F31 | - | - | SDEC F31 |
| SDEC | F36 | - | - | SDEC F36 |
| SDEC | F45 | - | - | SDEV F45 |
| Steyr | EDC17 | - | - | Steyr EDC17 |
| VECV | E694 | - | - | VECV E694 |
| Volvo Penta | CPCB4 | | | Volvo Penta CPCB4 |
| Volvo Penta | D12 marine | - | - | Volvo Penta D12 |
| Volvo Penta | EDC3 | - | - | Volvo Penta EDC3 |
| Volvo Penta | EDC4 | - | - | Volvo Penta EDC4 |
| Volvo Penta | EMS, EMS2.0 to EMS2.3 | D6, D7, D9, D12, D16 (GE and AUX variants only) | ● (ECU v 2.3 or later) | Volvo Penta EMS2 |
| Volvo Penta | EMS2.3 | - | ● | Volvo Penta EMS2.3 |
| Volvo Penta | EMS2.4 | - | ● | Volvo Penta EMS2.4 |
| Volvo Penta | EDC3, EDC4 | TAD4x, TAD5x, TAD6x, TAD7x | - | Volvo Penta Generic* |
| Weichai | - | - | - | Weichai Baudouin E6 Gas |
| Weichai | WOODWARD PG+ | Diesel | ● | Weichai Diesel |
| Weichai | WOODWARD PG+ | Gas | ● | Weichai Gas |
| Weichai | Wise 10B | - | ● | Weichai Wise10B |
| Weichai | Wise 15 | - | ● | Weichai Wise15 |
| Weichai | Wise 13 | - | - | Wise13 |
| Weichai | Wise 18B | - | ● | Wise18B |
| Xichai | - | - | - | Xichai Gas |
| YANMAR | EDC17 | - | - | YANMAR EDC17 |
| YANMAR | - | Gas 4G | - | YANMAR gas 4G |
| YANMAR | - | TN, TNV | ● | YANMAR Stage V |
| YANMAR | X11 | | | YANMAR X11 |
| Yuchai United | YC-ECU-A | | | YC-ECU-A |
| Yuchai United | YCGCU (Version 4.2) | Diesel | ● | Yuchai United Diesel |
| Yuchai United | YCGCU (Version 4.2) | Gas | ● | Yuchai United Gas |
| Yuchai United | YC-BCR | - | - | Yuchai YC-BCR |

| Manufacturer | ECUs | Engines | Tier 4/Stage V | Controller setting Engine I/F [7561] |
|---------------|--------|---------|----------------|---|
| Yuchai United | YC-ECU | - | - | Yuchai YC-ECU |
| Yunnei | | | | Yunnei |

NOTE * Generic protocols are included for backward compatibility.

NOTE ** If supported by the ECU and engine.

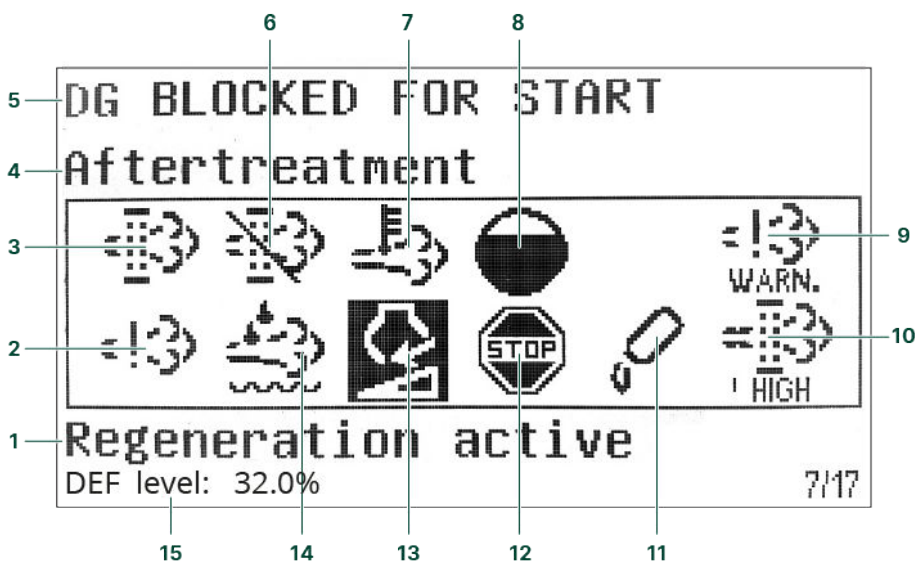
NOTE *** Previously *Jichai*.

Other EIC protocols: Contact DEIF.

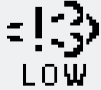

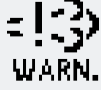








2.4 Exhaust after-treatment (Tier 4/Stage V)

The controller meets the Tier 4 (Final)/Stage V requirements. Use the display to monitor and control the engine and the exhaust after-treatment system.

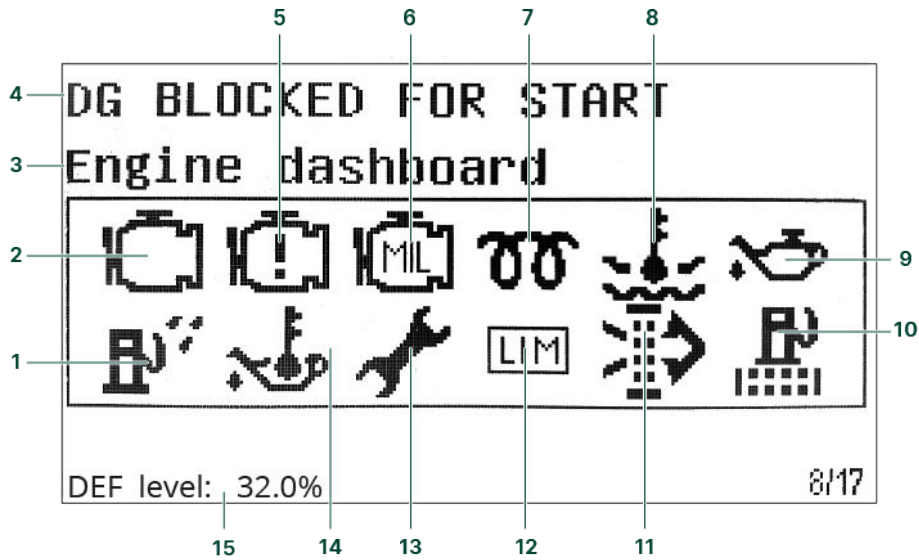
After-treatment page








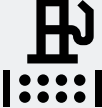
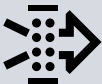





| No. | Referent | Symbol | Description |
|-----|--------------------------------------|--------|---|
| 1 | After-treatment status | - | |
| 2 | Engine emission system failure | | Emission failure or malfunction. |
| 3 | Diesel Particle Filter (DPF) | | Regeneration is needed. |
| 4 | Page name | - | |
| 5 | Controller status | - | |
| 6 | Diesel Particle Filter (DPF) Inhibit | | Regeneration is inhibited. |
| 7 | High temperature - Regeneration | | There is a high temperature and regeneration is in process. |
| 8 | HC burn-off | | Hydrocarbon accumulation that requires burn-off. |

| No. | Referent | Symbol | Description |
|-----|--------------------------------------|---|---|
| 9 | Engine emission system failure level |    | Emission failure or malfunction, with the severity. |
| 10 | Diesel Particle Filter (DPF) level |    | Regeneration needed, with the severity. |
| 11 | DEF level warning |  | Low DEF level. |
| 12 | DEF shutdown |  | DEF problem stops normal operation. |
| 13 | DEF level inducement |   | Mid-level inducement. Severe inducement. |
| 14 | Diesel Exhaust Fluid (DEF) |  | DEF quality is low. |
| 15 | Diesel Exhaust Fluid (DEF) % level | | Shows the level (%) of the Diesel Exhaust Fluid. |

Engine dashboard



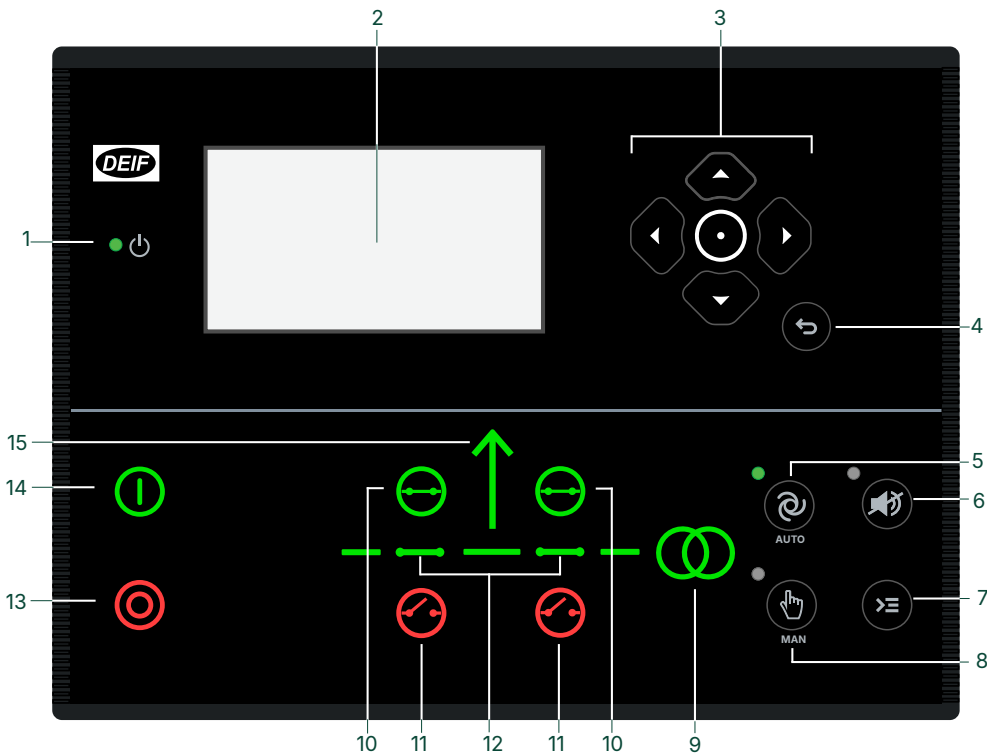
| No. | Referent | Symbol | Description |
|-----|---------------------------------|---|---|
| 1 | Water in fuel |  | There is water in the fuel. |
| 2 | Engine interface status |  | An engine warning. |
| 3 | Page name | - | - |
| 4 | Controller status | - | - |
| 5 | Engine interface status |  | An engine shutdown. |
| 6 | Engine interface status |  | An engine malfunction. |
| 7 | Cold start |  | The engine is cold. |
| 8 | High engine coolant temperature |  | The engine coolant temperature is high. |
| 9 | Low engine oil pressure |  | The engine oil pressure is low. |
| 10 | Fuel filter clogging |  | The fuel filter is blocked. |
| 11 | Air filter clogging |  | The air filter is blocked. |
| 12 | LIMIT lamp |  | Only for MTU engines. |
| 13 | Oil change |  | The engine needs an oil change. |







| No. | Referent | Symbol | Description |
|-----|------------------------------------|---|--|
| 14 | High engine oil temperature |  | The engine oil temperature is high. |
| 15 | Diesel Exhaust Fluid (DEF) % level | | Shows the level (%) of the Diesel Exhaust Fluid. |





NOTE Grey symbols show that communication is available for the referent. An engine type might not support all of the referents.

3. iE 150 Mains controller

3.1 Display layout



| No. | Name | Function |
|-----|--|--|
| 1 | Power | Green: The controller power is ON. OFF: The controller power is OFF. |
| 2 | Display screen | Resolution: 240 x 128 px. Viewing area: 88.50 x 51.40 mm. Six lines, each with 25 characters. |
| 3 | Navigation | Move the selector up, down, left, and right on the screen. |
| |  Enter button | Go to the Menu system. Confirm the selection on the screen. |
| 4 |  Back button | Go to the previous page. |
| 5 |  AUTO mode button | Use to switch to AUTO mode. The controller automatically connects and disconnects the mains. No operator actions are needed. The controllers use the power management configuration to automatically select the power management action. |
| 6 |  Silence horn button | Stops an alarm horn (if configured) and enters the Alarm menu. |
| 7 |  Shortcut menu button | Access the General shortcuts, Jump menu, Mode selection, Test, and Lamp test. |
| 8 |  Manual mode button | Use to switch to MANUAL mode. The operator or an external signal can connect or disconnect the mains. The mains controller cannot automatically connect or disconnect the mains. The controller automatically synchronises before closing a breaker, and automatically deloads before opening a breaker. |
| 9 | Mains symbol | Green: Mains voltage and frequency are OK. The controller can synchronise and close the breaker. |

| No. | Name | Function |
|-----|---|---|
| | | Red: Mains voltage and/or frequency are not OK. |
| 10 |  Close breaker | Push to close the breaker. |
| 11 |  Open breaker | Push to open the breaker. |
| 12 | Breaker symbols | Green: Breaker is closed. Green flashing: Synchronising or deloading. Red: Mains voltage and/or frequency are not OK. |
| 13 |  Stop | Stops the plant. |
| 14 |  Start | Starts the plant. |
| 15 | Load symbol | OFF: Power management application. Green: The supply voltage and frequency are OK. Red: Supply voltage/frequency failure. |

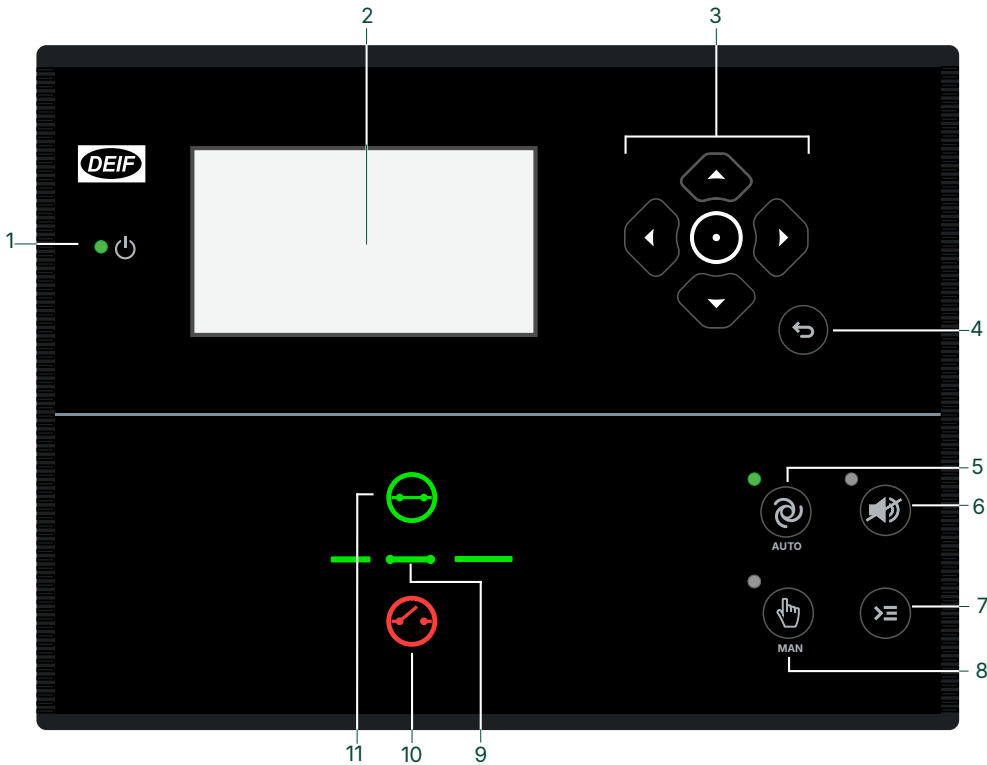
3.2 Mains controller functions







| Synchronising functions |
|---------------------------------------|
| Synchronising (dynamic) |
| Synchronising (static) |
| Short-time parallel between MB and TB |



| Mains functions |
|--|
| Mains current (3 × true RMS) |
| Mains/busbar voltage (3-phase/4-wire) |
| Phase angle compensation generator/busbar/mains synchronising over a transformer |
| ATS control |
| Load management |
| Plant PF control |
| Mains feeder control, feeders paralleled |
| Main feeders control, main-tie-main for critical power |

4. iE 150 BTB controller

4.1 Display layout



| No. | Name | Function |
|-----|--|--|
| 1 | Power | Green: The controller power is ON. OFF: The controller power is OFF. |
| 2 | Display screen | Resolution: 240 x 128 px. Viewing area: 88.50 x 51.40 mm. Six lines, each with 25 characters. |
| 3 | Navigation buttons | Move the selector up, down, left, and right on the screen. |
| |  Enter button | Go to the Menu system. Confirm the selection on the screen. |
| 4 |  Back button | Go to the previous page. |
| 5 |  AUTO mode button | Use to switch to AUTO mode. The controller automatically joins and splits the busbar. No operator actions are needed. The controllers use the power management configuration to automatically select the power management action. |
| 6 |  Silence horn button | Stops an alarm horn (if configured) and enters the Alarm menu. |
| 7 |  Shortcut menu button | Access the General shortcuts, Jump menu, and Lamp test. |
| 8 |  Manual mode button | Use to switch to MANUAL mode. The operator or an external signal can join or split the busbar. The BTB controller cannot automatically join or split the busbar. The controller automatically synchronises before closing a breaker, and automatically deloads before opening a breaker. |
| 9 | Breaker symbols | Green: Breaker is closed. Green flashing: Synchronising or deloading. |

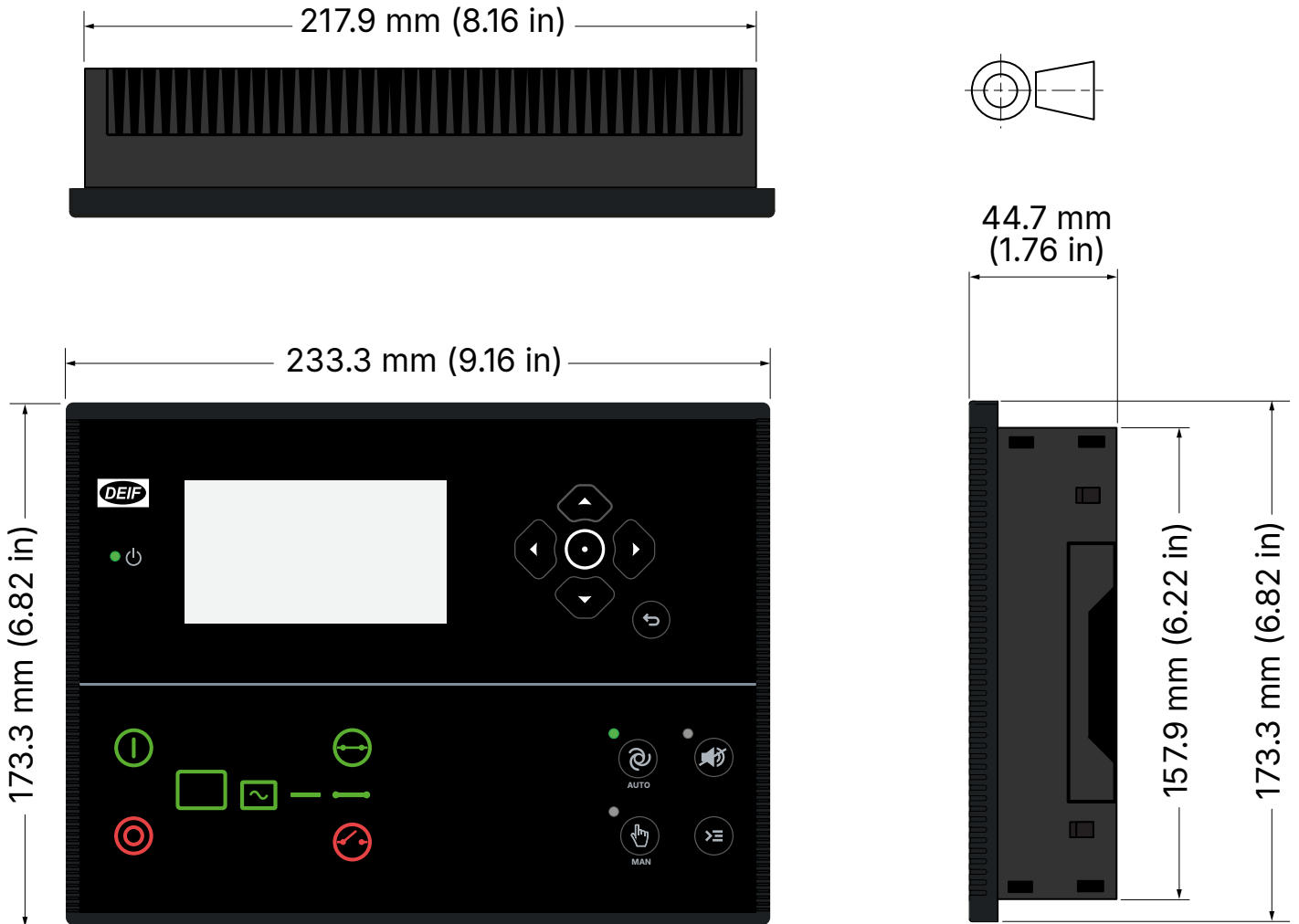
| No. | Name | Function |
|-----|---|----------------------------|
| | | Red: Breaker failure. |
| 10 |  Open breaker | Push to open the breaker. |
| 11 |  Close breaker | Push to close the breaker. |

4.2 BTB controller functions

| BTB controller functions |
|--|
| Synchronising |
| Section power control |
| Phase angle compensation generator/busbar/mains synchronising over a transformer |

5. Technical specifications

5.1 Dimensions



Dimensions and weight

| | |
|----------------------|--|
| Dimensions | Length: 233.3 mm (9.16 in) Height: 173.3 mm (6.82 in) Depth: 44.7 mm (1.76 in) |
| Panel cutout | Length: 218.5 mm (8.60 in) Height: 158.5 mm (6.24 in) Tolerance: ± 0.3 mm (0.01 in) |
| Max. panel thickness | 4.5 mm (0.18 in) |
| Mounting | UL/cUL Listed: Type complete device, open type 1 UL/cUL Listed: For use on a flat surface of a type 1 enclosure |
| Weight | 0.79 kg |

5.2 Mechanical specifications

Operation conditions

| | |
|-----------|--|
| Vibration | Response: <ul style="list-style-type: none"> 10 to 58.1 Hz, 0.15 mmpp |
|-----------|--|

Operation conditions

| | |
|---------------------|---|
| | <ul style="list-style-type: none">• 58.1 to 150 Hz, 1 g. To IEC 60255-21-1 (Class 2) Endurance: <ul style="list-style-type: none">• 10 to 150 Hz, 2 g. To IEC 60255-21-1 (Class 2) Seismic vibration: <ul style="list-style-type: none">• 3 to 8.15 Hz, 15 mmpp• 8.15 to 35 Hz, 2 g. To IEC 60255-21-3 (Class 2) |
| Shock | 10 g, 11 ms, half sine. To IEC 60255-21-2 Response (Class 2) 30 g, 11 ms, half sine. To IEC 60255-21-2 Withstand (Class 2) 50 g, 11 ms, half sine. To IEC 60068-2-27, test Ea Tested with three impacts in each direction in three axes (total of 18 impacts per test) |
| Bump | 20 g, 16 ms, half sine IEC 60255-21-2 (Class 2) Tested with 1000 impacts in each direction on three axes (total of 6000 impacts per test) |
| Galvanic separation | CAN port 2 (CAN B): 550 V, 50 Hz, 1 minute RS-485 port 1: 550 V, 50 Hz, 1 minute Ethernet: 550 V, 50 Hz, 1 minute Analogue output 51-52 (GOV): 550 V, 50 Hz, 1 minute Analogue output 54-55 (AVR): 3000 V, 50 Hz, 1 minute Note: No galvanic separation on CAN port 1 (CAN A) and RS-485 port 2 |
| Safety | Installation CAT. III 600 V Pollution degree 2 IEC/EN 60255-27 |
| Flammability | All plastic parts are self-extinguishing to UL94-V0 |
| EMC | IEC/EN 60255-26 |

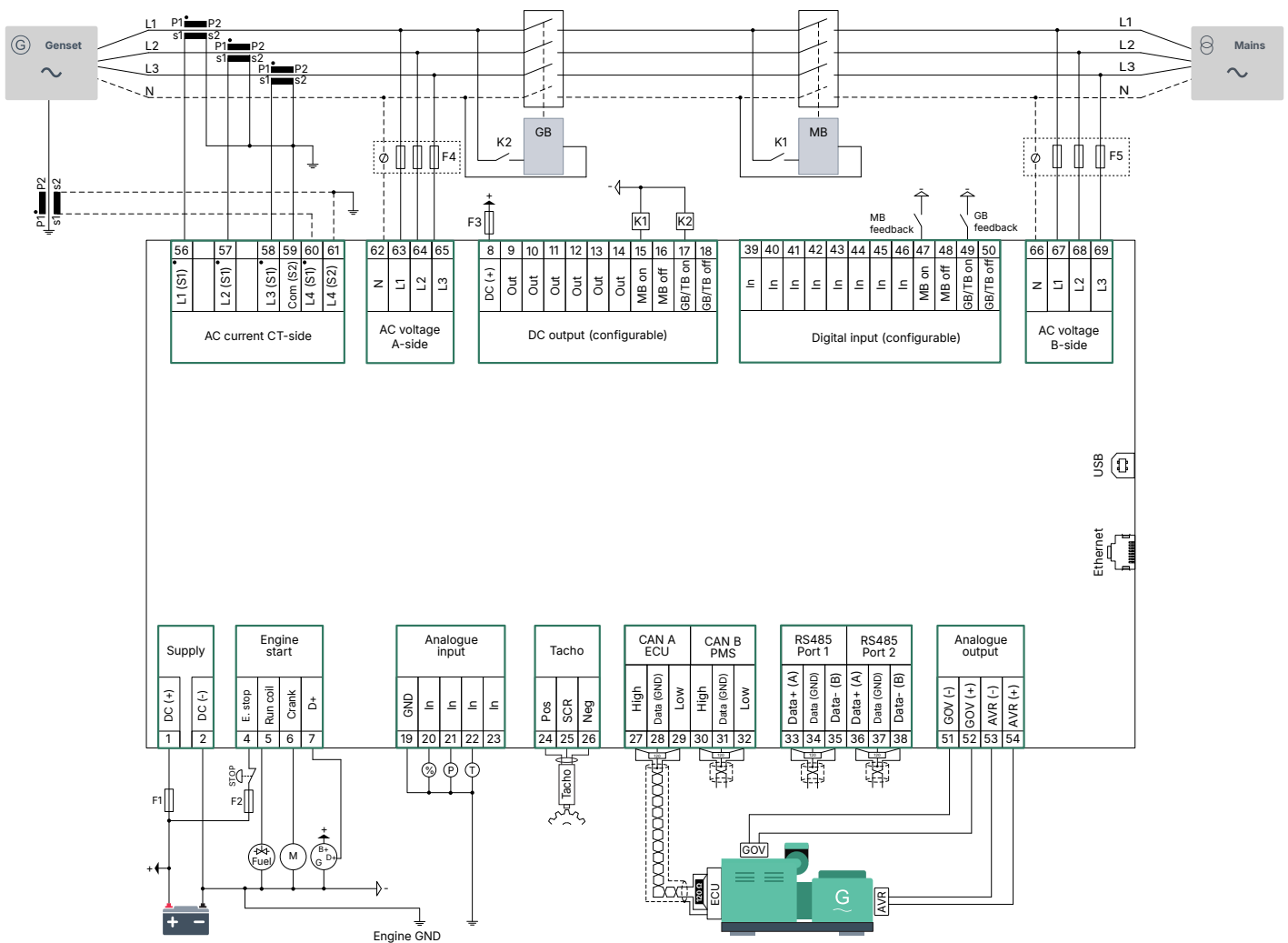
5.3 Environmental specifications

Operation conditions

| | |
|--|--|
| Operating temperature (incl. display screen) | -40 to +70 °C (-40 to +158 °F) |
| Storage temperature (incl. display screen) | -40 to +85 °C (-40 to +185 °F) |
| Accuracy and temperature | Temperature coefficient: 0.2 % of full scale per 10 °C |
| Operating altitude | 0 to 4000 m with derating |
| Operating humidity | Damp Heat Cyclic, 20/55 °C at 97 % relative humidity, 144 hours. To IEC 60255-1 Damp Heat Steady State, 40 °C at 93 % relative humidity, 240 hours. To IEC 60255-1 |
| Change of temperature | 70 to -40 °C, 1 °C / minute, 5 cycles. To IEC 60255-1 |
| Protection degree | IEC/EN 60529 <ul style="list-style-type: none">• IP65 (front of module when installed into the control panel with the supplied sealing gasket)• IP20 on terminal side |

5.4 Controller

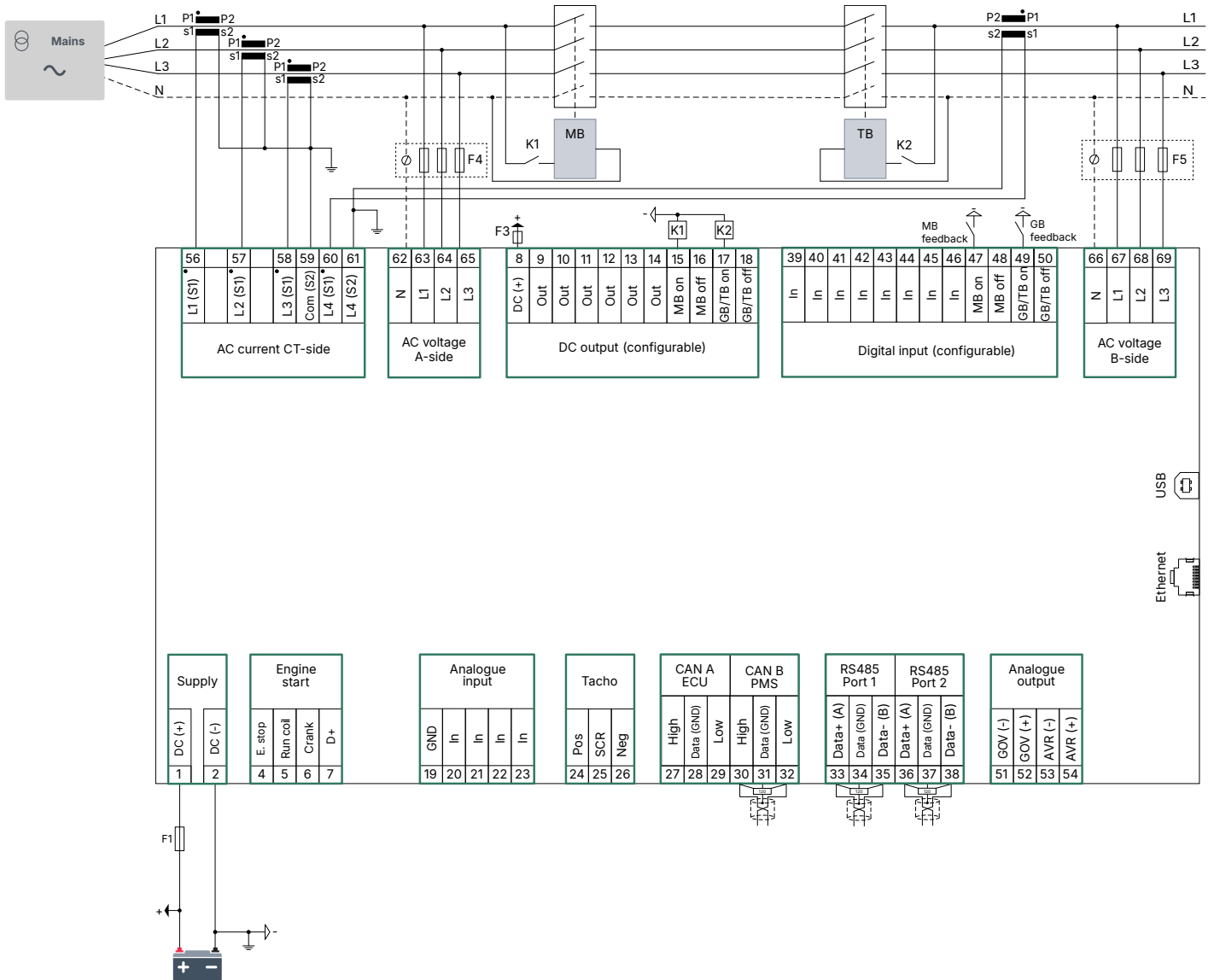
5.4.1 Typical wiring for generator controller



Fuses

- F1: 2 A DC max. time-delay fuse/MCB, c-curve
- F2: 6 A DC max. time-delay fuse/MCB, c-curve
- F3: 4 A DC max. time-delay fuse/MCB, b-curve
- F4, F5: 2 A AC max. time-delay fuse/MCB, c-curve

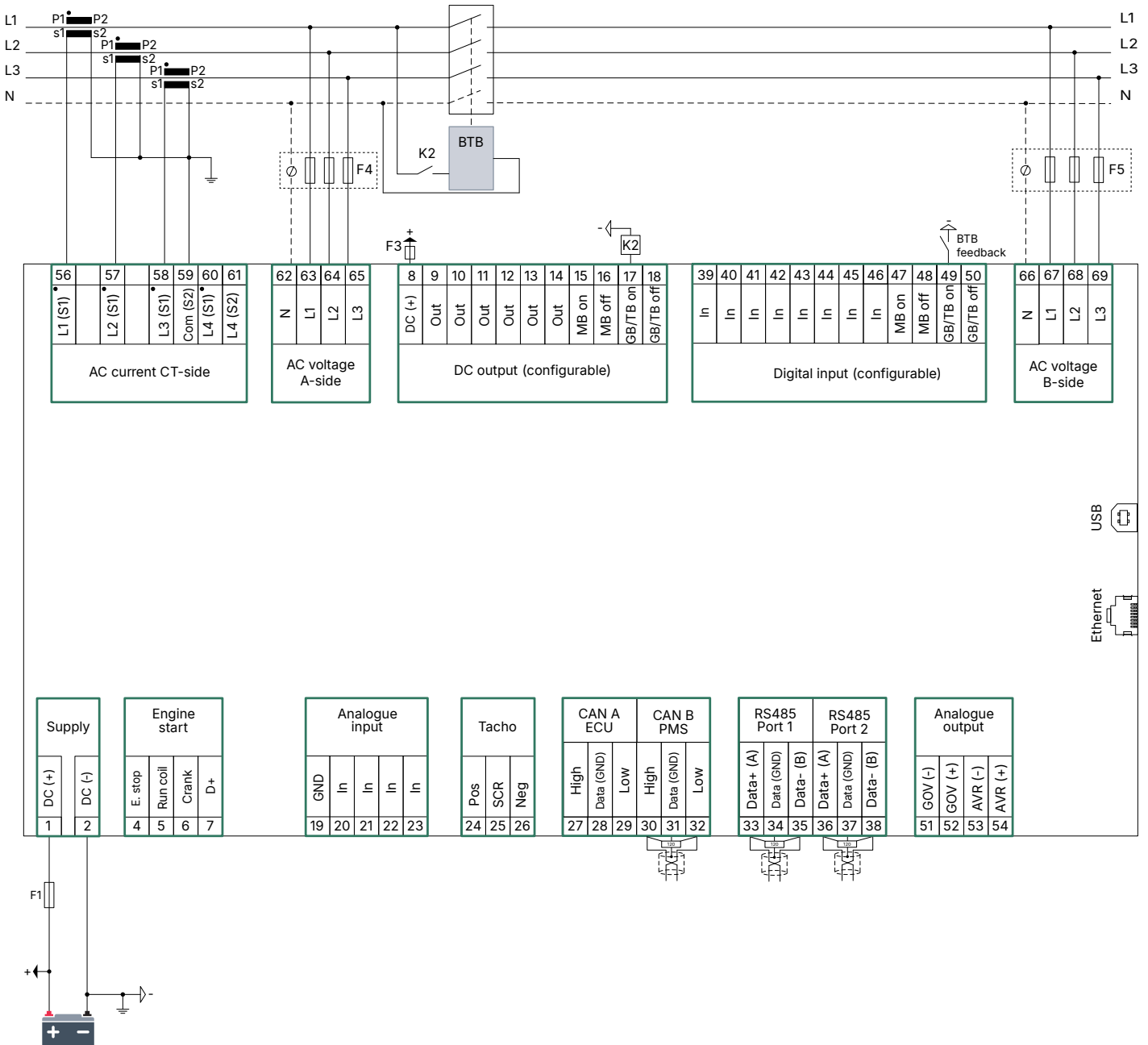
5.4.2 Typical wiring for mains controller



Fuses

- F1: 2 A DC max. time-delay fuse/MCB, c-curve
- F3: 4 A DC max. time-delay fuse/MCB, b-curve
- F4, F5: 2 A AC max. time-delay fuse/MCB, c-curve

5.4.3 Typical wiring for BTB controller



Fuses

- F1: 2 A DC max. time-delay fuse/MCB, c-curve
- F3: 4 A DC max. time-delay fuse/MCB, b-curve
- F4, F5: 2 A AC max. time-delay fuse/MCB, c-curve

5.4.4 Electrical specifications

| Power supply | |
|-----------------------------------|--|
| Power supply range | Nominal voltage: 12 V DC or 24 V DC Operating range: 6.5 to 36 V DC |
| Voltage withstand | Reverse polarity |
| Power supply drop-out immunity | 0 V DC for 50 ms (coming from min. 6 V DC) |
| Power supply load dump protection | Load dump protected according to ISO16750-2 test A |

Power supply

| | |
|-------------------|--------------------------|
| Power consumption | 5 W typical 12 W max. |
| RTC clock | Time and date backup |

Supply voltage monitoring

| | |
|-----------------|--|
| Measuring range | 0 V to 36 V DC Max. continuous operating voltage: 36 V DC |
| Resolution | 0.1 V |
| Accuracy | ± 0.35 V |

Voltage measurement

| | |
|--------------------|--|
| Voltage range | Nominal range: 100 to 690 V phase-to-phase (above 2000 m derate to max. 480 V) |
| Voltage withstand | $U_n + 35$ % continuously, $U_n + 45$ % for 10 seconds Measuring range of nominal: 10 to 135 % Low range, nominal 100 to 260 V: 10 to 351 V AC phase-to-phase High range, nominal 261 to 690 V: 26 to 932 V AC phase-to-phase |
| Voltage accuracy | ± 1 % of nominal within 10 to 75 Hz $+1/-4$ % of nominal within 3.5 to 10 Hz |
| Frequency range | 3.5 to 75 Hz |
| Frequency accuracy | ± 0.01 Hz within 60 to 135 % of nominal voltage ± 0.05 Hz within 10 to 60 % of nominal voltage |
| Input impedance | 4 M Ω /phase-to-ground, and 600 k Ω phase/neutral |

Current measurement

| | |
|-----------------------|---|
| Current range | Nominal: -/1 A and -/5 A Range: 2 to 300 % |
| Number of CT input | 4 |
| Max. measured current | 3 A (-/1 A) 15 A (-/5 A) |
| Current withstand | 7 A continuous 20 A for 10 seconds 40 A for 1 second |
| Current accuracy | From 10 to 75 Hz: <ul style="list-style-type: none">± 1 % of nominal from 2 to 100% current± 1 % of measured current from 100 to 300 % current From 3.5 to 10 Hz: <ul style="list-style-type: none">$+1/-4$ % of nominal from 2 to 100 % current$+1/-4$ % of measured current from 100 to 300 % current |
| Burden | Max. 0.5 VA |

Power measurement

| | |
|-----------------------|---|
| Accuracy power | ± 1 % of nominal within 35 to 75 Hz |
| Accuracy power factor | ± 1 % of nominal within 35 to 75 Hz |

| D+ | |
|-------------------------|------------------------------|
| Excitation current | 210 mA, 12 V 105 mA, 24 V |
| Charging fail threshold | 6 V |

| Tacho input | |
|---------------------------------|---|
| Voltage input range | +/- 1 V _{peak} to 70 V _{peak} |
| W | 8 to 36 V |
| Frequency input range | 10 to 10 kHz (max.) |
| Frequency measurement tolerance | 1 % of reading |

| Digital inputs | |
|-----------------------------------|--|
| Number of inputs | 12 x digital inputs Negative switching |
| Maximum input voltage | +36 V DC with respect to plant supply negative |
| Minimum input voltage | -24 V DC with respect to plant supply negative |
| Current source (contact cleaning) | Initial 10 mA, continuous 2 mA |

| DC outputs | |
|-------------------------|--|
| Number of 3 A outputs | 2 x outputs (for fuel and crank) 15 A DC inrush and 3 A continuous, supply voltage 0 to 36 V DC Endurance tested according to UL/ULC6200:2019 1.ed: 24 V, 3 A, 100000 cycles (with an external freewheeling diode) |
| Number of 0.5 A outputs | 10 x outputs 2 A DC inrush and 0.5 A continuous, supply voltage 4.5 to 36 V DC |
| Common | 12/24 V DC |

| Analogue inputs | |
|------------------|--|
| Number of inputs | 4 x analogue inputs |
| Electrical range | Configurable as: <ul style="list-style-type: none"> Negative switching digital input 0 V to 10 V sensor 4 mA to 20 mA sensor 0 Ω to 2.5 kΩ sensor |
| Accuracy | Current: <ul style="list-style-type: none"> Accuracy: ±20 uA ±1.00 % rdg Voltage: <ul style="list-style-type: none"> Range: 0 to 10 V DC Accuracy: ±20 mV ±1.00 % rdg RMI 2-wire LOW: <ul style="list-style-type: none"> Range: 0 to 800 Ω Accuracy: ±2 Ω ±1.00 % rdg RMI 2-wire HIGH: <ul style="list-style-type: none"> Range: 0 to 2500 Ω Accuracy: ±5 Ω ±1.00 % rdg |

| Voltage regulator output | |
|------------------------------|----------------------------|
| Output types | Isolated DC voltage output |
| Voltage range | -10 to +10 V DC |
| Resolution in voltage mode | Less than 1 mV |
| Maximum common mode voltage | ±3 kV |
| Minimum load in voltage mode | 500 Ω |
| Accuracy | ±1 % of setting value |

| Speed governor output | |
|------------------------------------|---|
| Output types | Isolated DC voltage output Isolated PWM output |
| Voltage range | -10 to +10 V DC |
| Resolution in voltage mode | Less than 1 mV |
| Maximum common mode voltage | ±550 V |
| Minimum load in voltage mode | 500 Ω |
| PWM frequency range | 1 to 2500 Hz ±25 Hz |
| PWM duty cycle resolution (0-100%) | 12 bits (4096 steps) |
| PWM voltage range | 1 to 10.5 V |
| Voltage accuracy | ±1% of setting value |

| Display unit | |
|--------------|---------------------------------------|
| Type | Graphical display screen (monochrome) |
| Resolution | 240 x 128 pixels |
| Navigation | Five-key menu navigation |
| Log book | Data log and trending function |
| Language | Multi-language display |

5.4.5 Communication

| Communication | |
|---------------|---|
| CAN A | <p>You can connect these in a daisy chain (and operate them at the same time):</p> <ul style="list-style-type: none"> • Engine CAN Port • DVC 550 • CIO 116, CIO 208, and CIO 308 • IOM 220 and IOM 230 <p>Data connection 2-wire + common, or 3-wire Not isolated External termination required (120 Ω + matching cable) DEIF engine specification (J1939 + CANopen)</p> |
| CAN B | <p>You can connect one of these:</p> <ul style="list-style-type: none"> • Power management • CANshare • AOP-2 <p>Data connection 2-wire + common, or 3-wire Isolated</p> |

| Communication | |
|---------------|---|
| | External termination required (120 Ω + matching cable) PMS 125 kbit and 250 kbit |
| RS-485 Port 1 | Used for: Modbus RTU, PLC, SCADA, Remote monitoring (Insight) Data connection 2-wire + common, or 3-wire Isolated External termination required (120 Ω + matching cable) 9600 to 115200 |
| RS-485 Port 2 | Used for: Modbus RTU, PLC, SCADA, Remote monitoring (Insight) Data connection 2-wire + common, or 3-wire Not isolated External termination required (120 Ω + matching cable) 9600 to 115200 |
| RJ45 Ethernet | Used for: <ul style="list-style-type: none"> • Modbus to PLC, SCADA, and so on • Backup power management system (PMS) communication between iE 150 controllers • NTP time synchronisation with NTP servers • PC utility software Isolated Auto detecting 10/100 Mbit Ethernet port |
| USB | Service port (USB-B) |

5.5 Approvals

| Standards |
|--|
| CE |
| UL/cUL Listed to - UL/ULC6200:2019 1.ed. Controllers for Use in Power Production |

NOTE Refer to www.deif.com for the most recent approvals.

5.5.1 UL/cUL Listed

| Requirements | |
|------------------------|--|
| Installation | To be installed in accordance with the NEC (US) or the CEC (Canada) |
| Enclosure | A suitable type 1 (flat surface) enclosure is required Unventilated/ventilated with filters for controlled/pollution degree 2 environment |
| Mounting | Flat surface mounting |
| Connections | Use 90 °C copper conductors only |
| Wire size | AWG 30-12 |
| Terminals | Tightening torque: 5-7 lb-in. |
| Current transformers | Use Listed or Recognized isolating current transformers |
| Communication circuits | Only connect to communication circuits of a listed system/equipment |

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