

CODESYS Guidelines

for AMC 300, AMC 600, AWC 500, and iE 250



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1. About this manual

1.1 Software versions

The information in this document corresponds to the following software versions.

Software	Details	Version
BSP/OS	AMC 300 Board Support Package	PCM3.1 BSPv4 (4.0.5.0) or later PCM3.3 BSPv4 (5.0.0.0) or later
	AWC 500 Operating System	PCM5.2 OSv3 (3.0.1.0) or later
	AMC 600 Operating System	PCM6.1 OSv3 (1.0.1.0) or later
	iE 250 PLC Operating System	BSPv5 (5.0.0.0) or later
CODESYS CONTROL	CODESYS run-time	V3.5 SP 15 3.5.15.20 V3.5 SP 18 3.5.18.40 or later
CODESYS IDE	PC software for development of CODESYS applications	V3.5 SP 15 3.5.15.20 V3.5 SP 18 3.5.18.40 or later
CODESYS TSP	AMC 300 CODESYS Target Support Package (TSP) AWC 500 CODESYS Target Support Package (TSP) AMC 600 CODESYS Target Support Package (TSP) iE 250 PLC CODESYS Target Support Package (TSP)	1.3.0.7 or later

1.2 Technical support

CODESYS in general	
The CODESYS store	My question: Ask questions about CODESYS. FAQ: Frequently asked questions. Forum: Discuss different CODESYS topics with other users.
CODESYS Development System online help	Online help is available from the Help menu.

DEIF support options	
Technical documentation	Download all technical product documentation from https://www.deif.com/documentation .
Support	DEIF offers 24-hour support. See www.deif.com for contact details, there may be a DEIF subsidiary located near you. You can also e-mail support@deif.com.
Service	DEIF engineers can help with design, commissioning, operating and optimisation.
Training	DEIF regularly offers training courses at the DEIF offices worldwide.

1.3 System requirements

The requirements for the development PC to install the Development packages, PC tools and drivers are:

- Microsoft Windows 10, 32 bit version
- Microsoft Windows 10, 64 bit version (Recommended)

As the AMC 300 and the AMC 600 support SSH (Secure Shell) and SCP (Secure Copy) as basic communication protocols, it can be accessed from any system supporting these protocols (if enabled).

NOTE Not all browsers are suitable for this software. We recommend to use Google Chrome or Mozilla Firefox.

1.4 Warnings and safety

Recommendations for data security

To minimise the risk of data security breaches we recommend to:

- As far as possible, avoid exposing controllers and controller networks to public networks and the Internet.
- Use additional security layers like a VPN for remote access, and install firewall mechanisms.
- Restrict access to authorised persons.

1.5 Legal information

Disclaimer

DEIF A/S reserves the right to change any of the contents of this document without prior notice.

The English version of this document always contains the most recent and up-to-date information about the product. DEIF does not take responsibility for the accuracy of translations, and translations might not be updated at the same time as the English document. If there is a discrepancy, the English version prevails.

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2. Installation

2.1 CODESYS development package

2.1.1 About the CODESYS development package

The AMC 300, AMC 600, AWC 500, and iE 250 PLC CODESYS development packages consist of three parts:

- CODESYS IDE: Installed on the development PC.
- CODESYS TSP (targeting AMC 300, AMC 600, AWC 500, or iE 250 PLC): Target support package installed into the IDE.
- CODESYS CONTROL run-time: Runs on the controller hardware.

CODESYS CONTROL run-time

The installation process for the CODESYS CONTROL run-time depends on the BSP/OS version.

For:

- AMC 300 PCM3.1 (BSPv4)
- AMC 300 PCM3.3 (BSPv5)
- AMC 600 PCM6.2 (BSPv5)
- iE 250 PLC PCM2.1 (BSPv5)

the CODESYS CONTROL run-time is bundled in the operating system. An update of the PLC run-time follows the update of a new bundle.

Whereas for:

- AWC 500 PCM5.2
- AMC 600 PCM6.1 (OSv3)

the CODESYS CONTROL run-time is added via the installation package (.dupdate file). This package is pre-installed from the DEIF factory when you order the controller. You can update the CODESYS CONTROL run-time independently from the operating system.

2.1.2 Download the CODESYS development package

You can download the CODESYS IDE, CODESYS TSP, and the CODESYS run-time by submitting your email address via the DEIF website. A link is sent to you to download the CODESYS IDE and CODESYS TSP, respectively.

Follow these steps to download the CODESYS IDE:

1. Go to the DEIF website www.deif.com.
2. Open the search bar , and type the controller name to open a list of product options.
3. Select the controller from the list.
4. Select the **Software** tab.
5. Open the **CODESYS** list, and select either:
 - **AMC 300 CODESYS TSP v1.3.0.x**
 - **AWC 500 CODESYS TSP v1.3.0.x**
 - **AMC 600 CODESYS TSP v1.3.0.x or**
 - **iE 250 PLC CODESYS TSP v1.3.0.x**
6. Submit your email address to receive a download link to the software.

someone@someone.com

E-mail notification on future releases

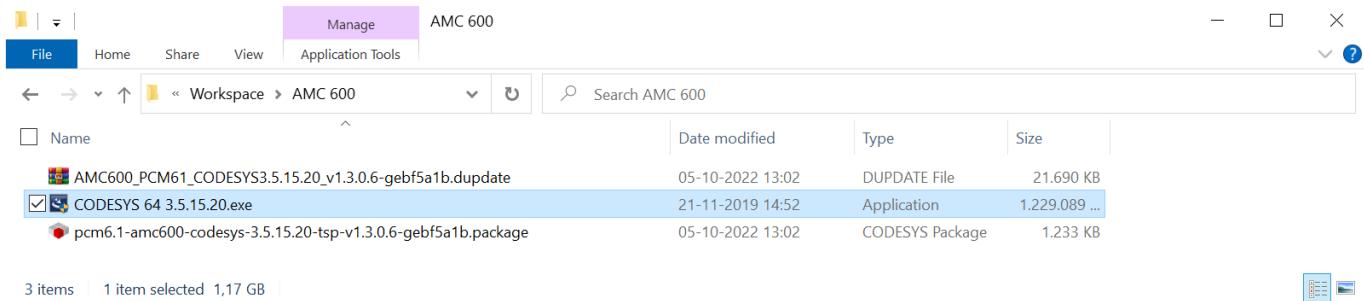
Download

7. Follow the link in the email to download the DEIF CODESYS software package to your computer.
8. Repeat the steps to download the **CODESYS IDE** installation file, for example:
 - **CODESYS V3.5 SP15 or**
 - **CODESYS V3.5 SP18**
9. If it is necessary to update the CODESYS run-time, download the CODESYS CONTROL run-time. For example,
 - **AMC 300 PCM3.1 Code package**
 - **AWC 500 CODESYS run-time for PCM5.2**
 - **AMC 600 CODESYS run-time for PCM6.1 or**
 - **iE 250, AMC 300, or AMC 600 Code package (common for PCM2.1, PCM3.3 and PCM6.2)**

2.2 Install CODESYS V3.5 SP15

This section guides you through the installation of the CODESYS IDE and installation of the CODESYS TSP.

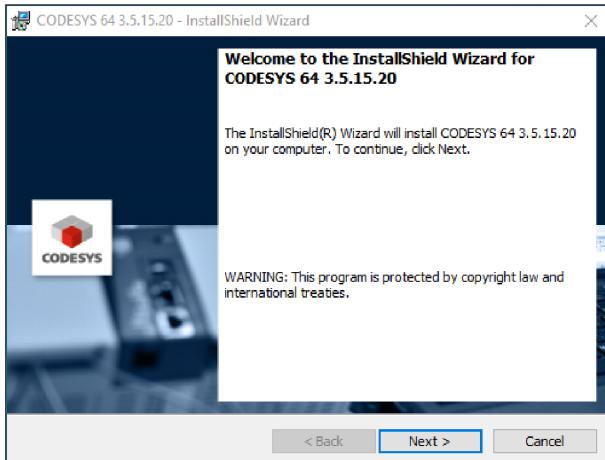
- Run the installation file (for example, CODESYS 64 3.5.15.20.exe) to install CODESYS IDE to the development computer with default settings.



- If you are prompted to install necessary Microsoft Visual C++ packages, follow the instructions on the screen.

The CODESYS InstallShield Wizard

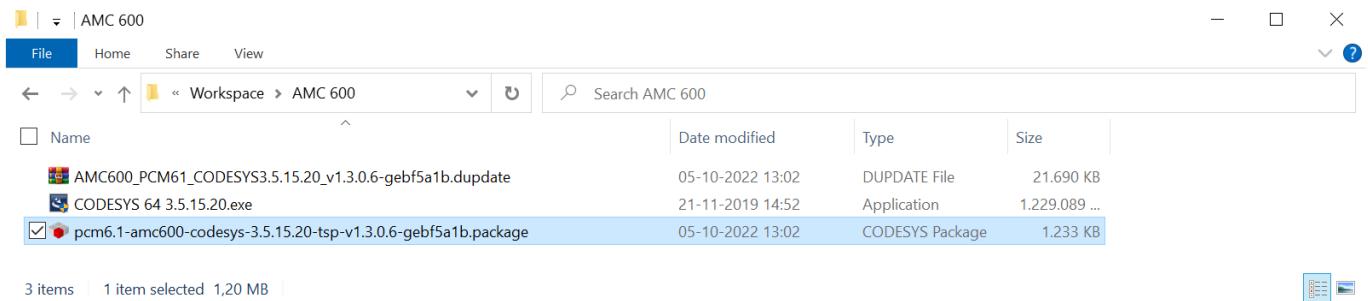
- When the CODESYS InstallShield Wizard starts, select **Next**.



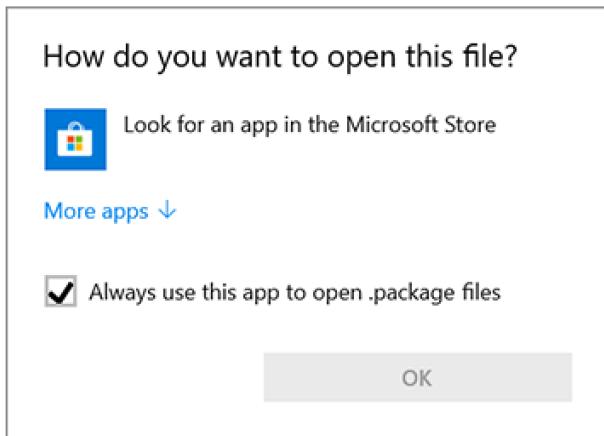
- Licence Agreement:** Accept the agreement and select **Next**.
- Choose Destination Location:** Choose a folder for the installation, and select **Next**.
- Select Features:** Choose the features you want to install, and select **Next**.
- Select Program Folder:** Choose a program folder, and select **Next**.
- Start Copying Files:** The chosen features and the destination folder are shown. If everything is correct, select **Next**.
- Very important information:** Confirm that you have read the information, and select **Next**.
- InstallShield Wizard Complete:** Select **Finish** to exit the installation wizard.

2.2.1 Install the CODESYS TSP

- Run the installation file (for example, pcm6.1-amc600-codesys-3.5.15.20-gebf5a1b.package) to install the AMC 600 CODESYS TSP (Target Support Package) to the development computer with default settings.



2. The file extension .package is registered with CODESYS on Windows. If CODESYS is not installed or you do not have the correct version, you will see this message:

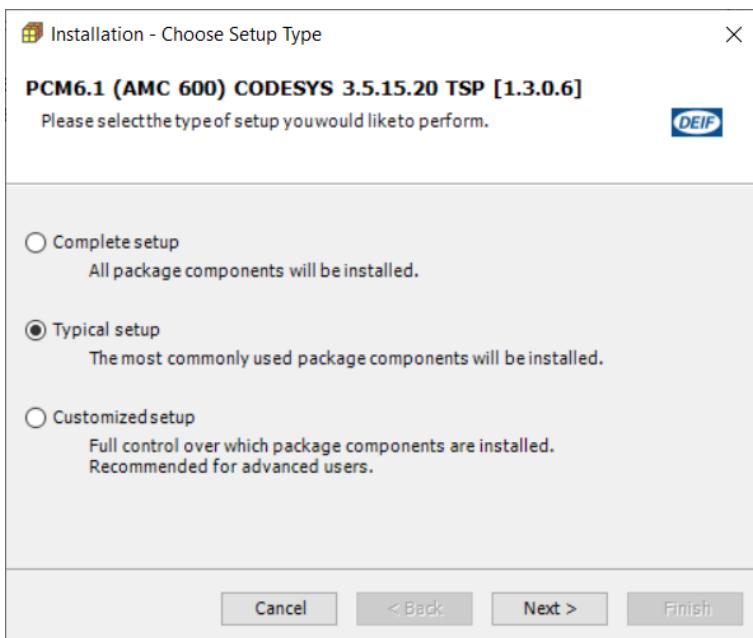


3. Install a correct version of CODESYS (see section **Install CODESYS V3.5 SP15**), then run the installation file again.

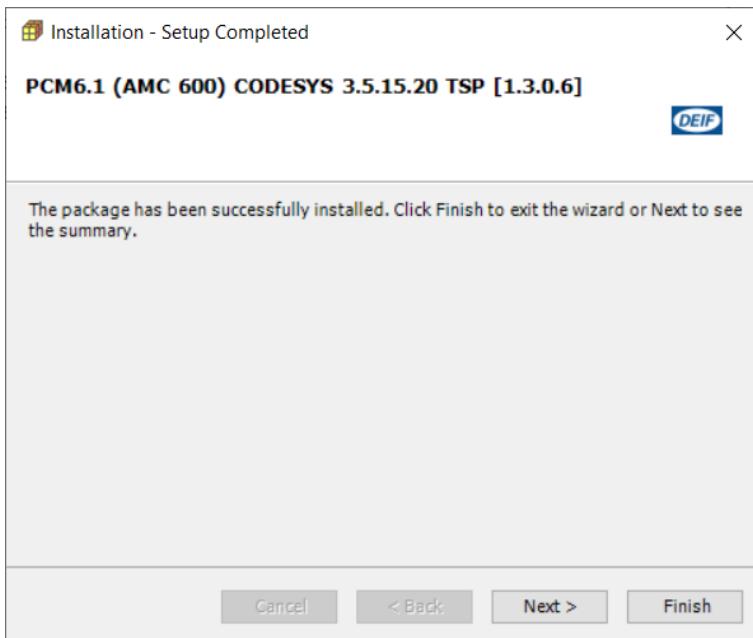
If CODESYS is installed, but you do not want the AMC 600 CODESYS TSP package associated with it, you can open CODESYS and install the package file with **Open > Install package**.

This starts the Package Manager and installs the required AMC 600 Device Descriptions (and the EtherCAT Slave Information files).

1. Choose a setup, and select **Next**.



2. When the package is installed, select **Next** to finish the installation.



3. Select **Finish** to exit the installation wizard or **Next** to see a summary.

2.2.2 Open CODESYS for the first time

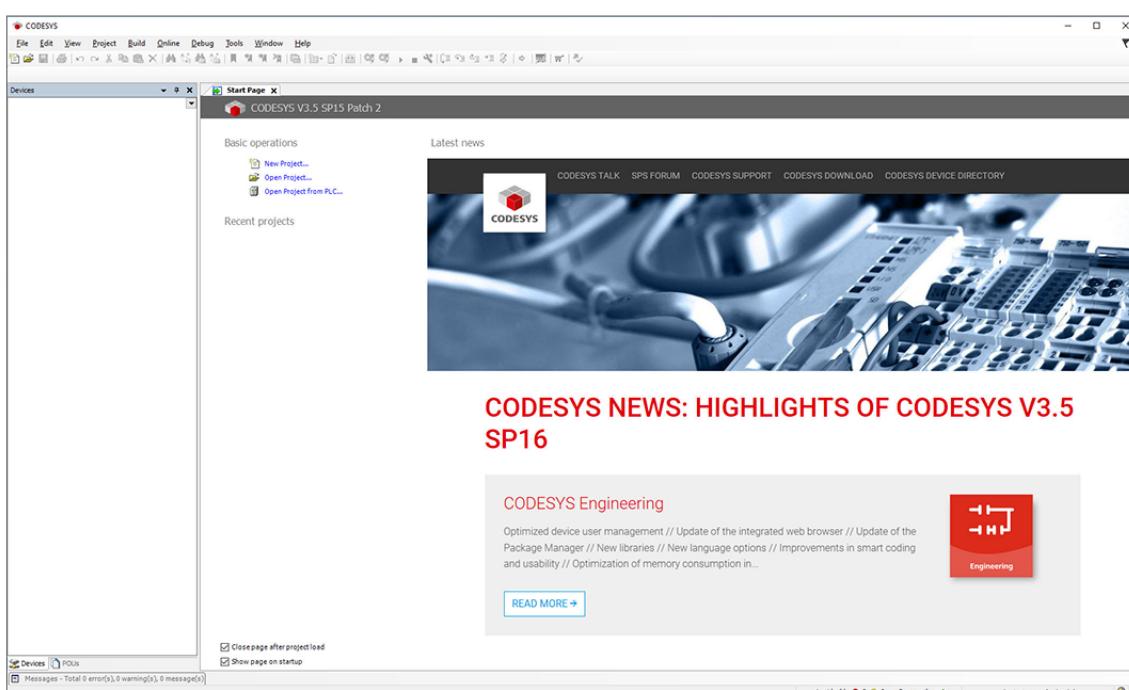
To open CODESYS you can:

- Double-click the desktop icon



- In the start menu, select **Start > 3S CODESYS > CODESYS V3.5 SP15 (or later version)**

The CODESYS start page:

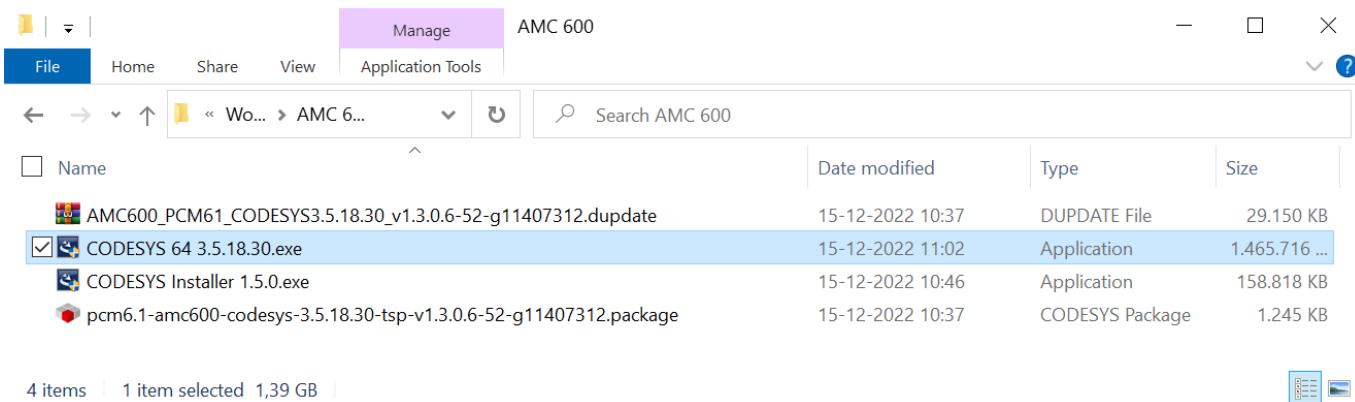


2.3 Install CODESYS V3.5 SP18

This section guides you through the installation of the CODESYS IDE and installation of the CODESYS TSP.

From CODESYS V3.5 SP18, you have the option to use the direct installation or install CODESYS via the CODESYS Installer. Both methods are shown in this section.

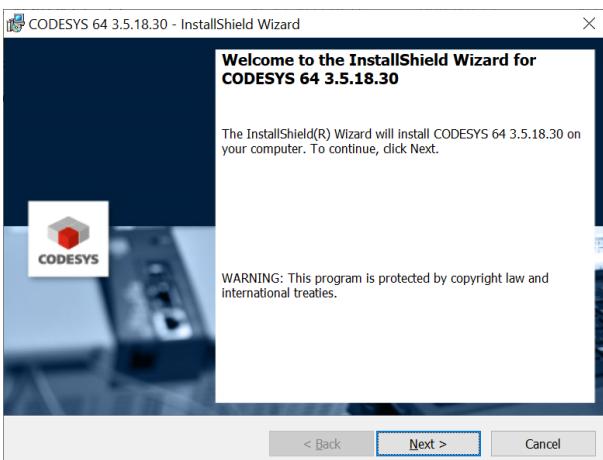
1. Run the installation file (for example, CODESYS 64 3.5.18.30.exe) to install CODESYS IDE to the development computer with default settings.



2. If you are prompted to install necessary Microsoft Visual C++ packages, follow the instructions on the screen.

The CODESYS InstallShield Wizard

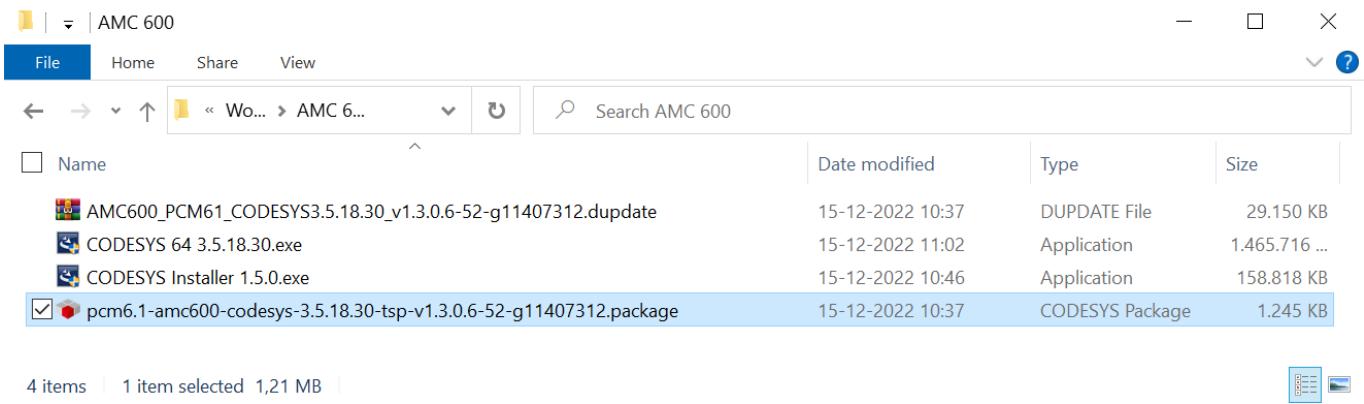
1. When the CODESYS InstallShield Wizard starts, select **Next**.



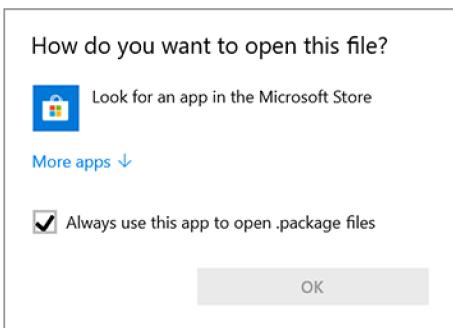
2. **Licence Agreement:** Accept the agreement and select **Next**.
3. **Choose Destination Location:** Choose a folder for the installation, and select **Next**.
4. **Select Features:** Choose the features you want to install, and select **Next**.
5. **Select Program Folder:** Choose a program folder, and select **Next**.
6. **Start Copying Files:** The chosen features and the destination folder are shown. If everything is correct, select **Next**.
7. **Very important information:** Confirm that you have read the information, and select **Next**.
8. **InstallShield Wizard Complete:** Select **Finish** to exit the installation wizard.

2.3.1 Install the CODESYS TSP

1. Run the installation file (for example, pcm6.1-amc600-codesys-3.5.18.30-tsp-v1.3.0.6-52-g11407312) to install the AMC 600 CODESYS TSP (Target Support Package) to the development computer with default settings.



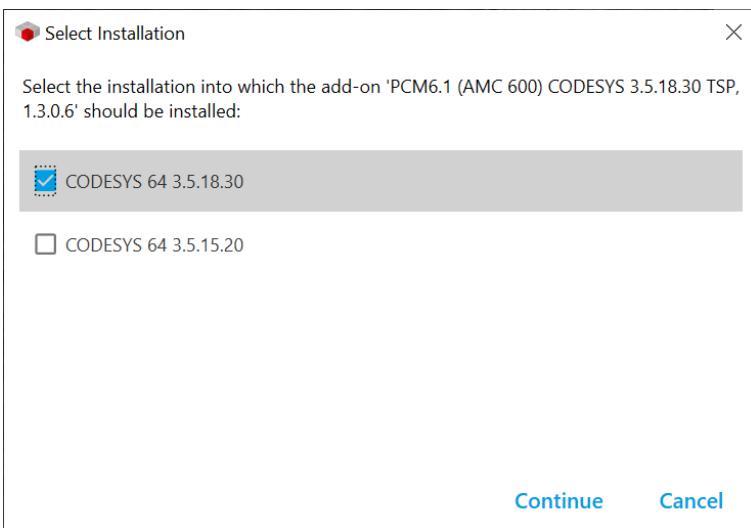
2. The file extension .package is registered with CODESYS on Windows. If CODESYS is not installed or it is not a correct version, you will see this message.



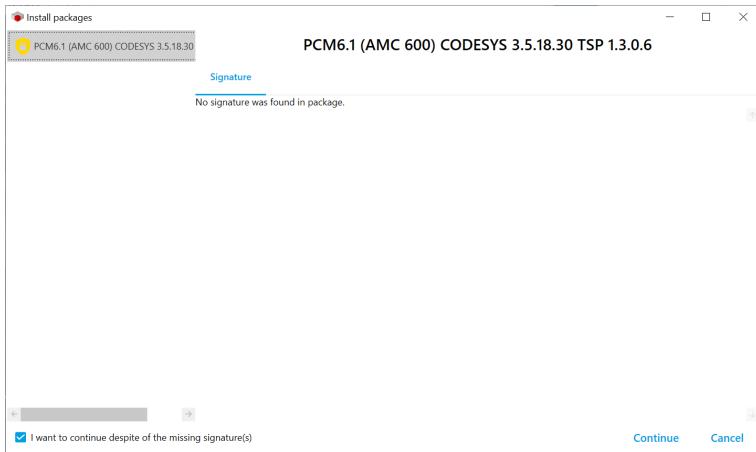
3. Install a correct version of CODESYS (see section **Install CODESYS V3.5 SP18**), then run the installation file again.

If CODESYS is installed, but you do not want the CODESYS TSP package associated with it, you can open CODESYS and install the package file via **Open > Install package**. This starts the Package Manager and installs the required EtherCAT Device Descriptions for the controller products (and the EtherCAT Slave Information files)

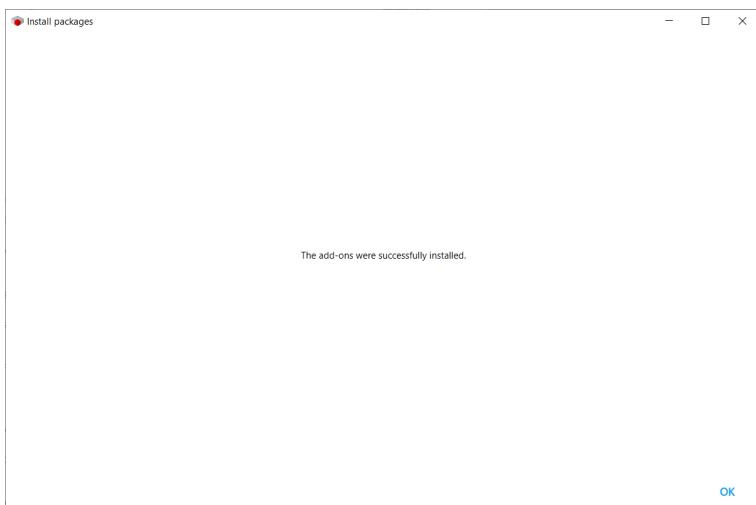
4. When the installation starts, select the CODESYS version for installation.



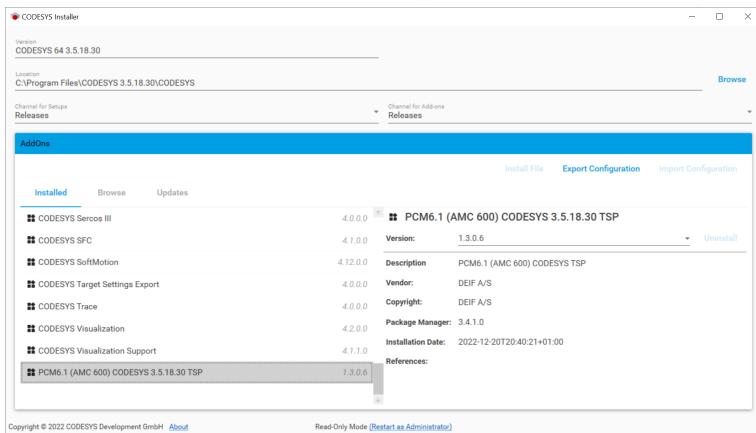
5. Select that you want to **Continue** although there is a missing installation package.



6. Select **OK** when the installation has been completed.



You can view the installed CODESYS TSP in the CODESYS Installer, as shown below.



7. Choose a setup, and select **Next**.
8. When the package is installed, select **Next** to finish the installation.
9. Select **Finish** to exit the installation wizard, or **Next** to see a summary.

2.3.2 Install/upgrade CODESYS V3 installation via CODESYS Installer

The CODESYS Installer is a Package Manager that can be used to manage CODESYS Installations.

1. Run the installation file for CODESYS Installer (for example, CODESYS Installer 1.5.0.exe) to install the CODESYS Installer to the development computer with default settings.

AMC 600				
File	Home	Share	View	Application Tools
←	→	▼	▲	⟳
📁	« Wo... > AMC 6...	▼	⟳	🔍 Search AMC 600
Name	Date modified	Type	Size	
AMC600_PCM61_CODESYS3.5.18.30_v1.3.0.6-52-g11407312.duplicate	15-12-2022 10:37	DUPDATE File	29.150 KB	
CODESYS 64 3.5.18.30.exe	15-12-2022 11:02	Application	1.465.716 ...	
<input checked="" type="checkbox"/> CODESYS Installer 1.5.0.exe	15-12-2022 10:46	Application	158.818 KB	
pcm6.1-amc600-codesys-3.5.18.30-tsp-v1.3.0.6-52-g11407312.package	15-12-2022 10:37	CODESYS Package	1.245 KB	

2. If you are prompted to install necessary Microsoft Visual C++ packages, follow the instructions on the screen.

The CODESYS Installer InstallShield Wizard

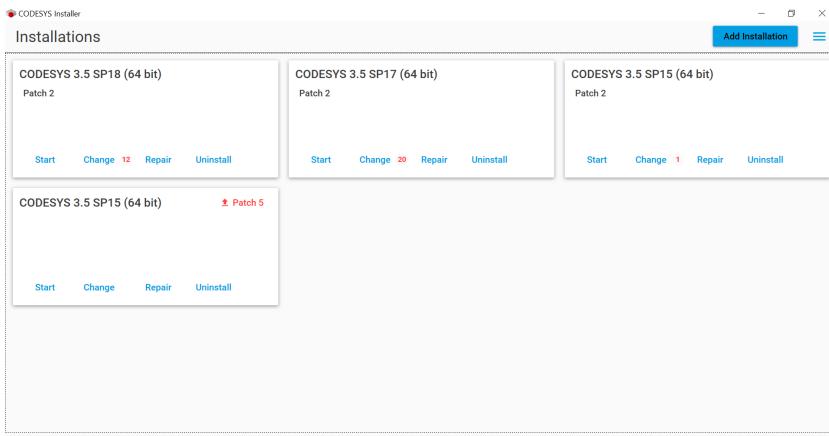
- When the CODESYS InstallShield Wizard starts, select **Next**.



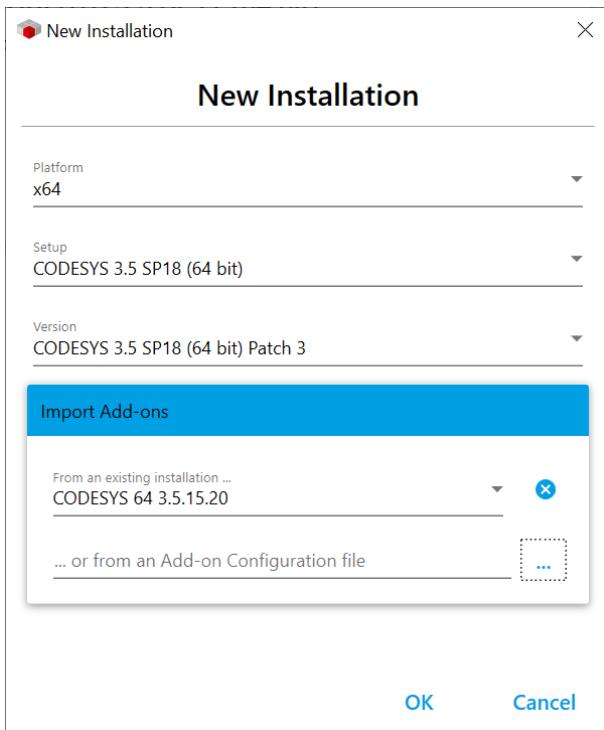
2. **Licence Agreement:** Accept the agreement, and select **Next**.
 3. **InstallShield Wizard Complete:** Select **Launch CODESYS Installer** and **Finish** to exit the installation.

Add new CODESYS Installation

1. Open CODESYS Installer, and select New Installation in the upper right corner.



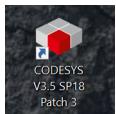
2. Select the new CODESYS version to install and the previous version to import settings from.



2.3.3 Open CODESYS for the first time

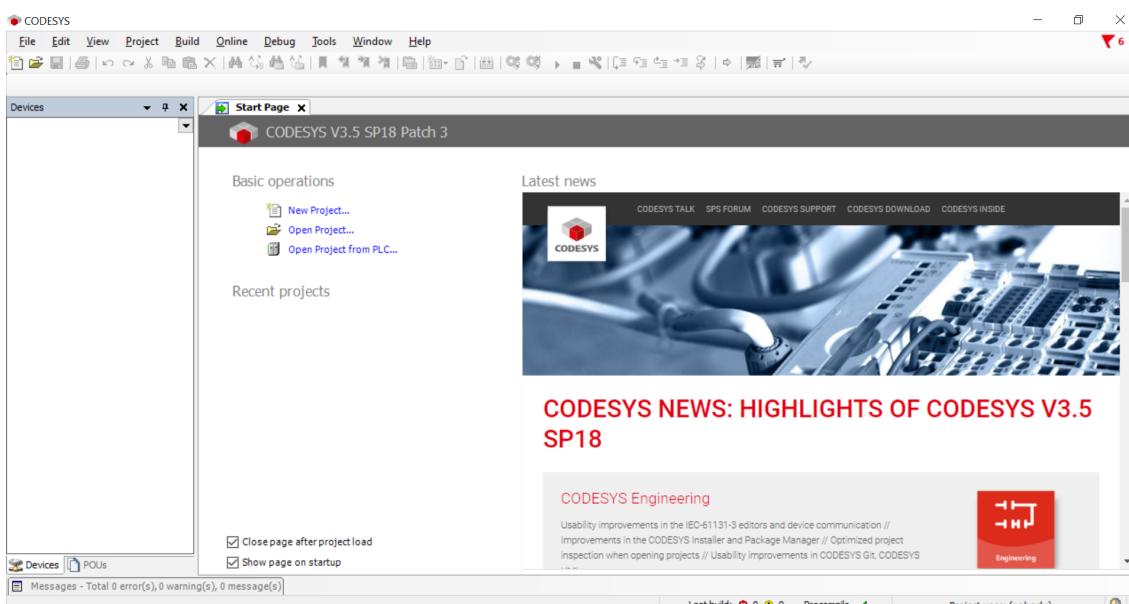
To open CODESYS you can:

- Double-click the desktop icon



- In the start menu, select **Start > 3S CODESYS > CODESYS V3.5 SP18 (or later version)**

The CODESYS start page:

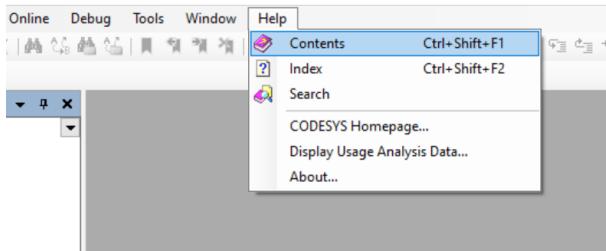


3. CODESYS Online Help

3.1 Start the CODESYS Online Help

Use the CODESYS Online Help to get more detailed information about the CODESYS programming environment.

On the CODESYS start page, select **Help > Contents** in the menu.



This opens the CODESYS Online Help page.

A screenshot of a web browser displaying the CODESYS Online Help for the Development System. The URL is 'help.codesys.com/webapp/_cds_f_development_system_introduction;product=codesys;version=3.5.17.0'. The page title is 'CODESYS Online Help'. On the left is a sidebar with links like 'CODESYS Development System', 'Fieldbus Support', etc. The main content area has a title 'CODESYS Development System'. It features a 'CODESYS' logo, the text 'CODESYS GmbH', and a note that the help corresponds to CODESYS V3.5 SP17. Below that is a 'Last update: July 2021' message and a link to 'www.codesys.com'. At the bottom of the content area is a list of links: 'Using CODESYS Help', 'CODESYS System overview', 'Features', 'Customization of the user interface language', and 'Copyrights and Trademarks'.

3.2 New to CODESYS

If you are new to CODESYS, we recommend you start with the guide under the menu **Your First CODESYS Program**.

The screenshot shows a web browser window for the CODESYS Online Help. The URL is help.codesys.com/webapp/_cds_tutorial_refrigerator_control;product=codecsys;version=3.5.17.0. The page title is "Your First CODESYS Program". On the left, there is a navigation sidebar with a tree view of topics. The "Your First CODESYS Program" topic is highlighted. The main content area lists several steps or sections related to getting started with a project.

- Before you get started
- Contents of your first project
- Preparation
- Creating the project and selecting the PLC device
- To program the controller application in the project, see the following sections:
- Declaring the global variables
- Creating the main program for the cooling control in the CFC editor
- Creating a POU for signal management in the ladder diagram editor
- Calling the Signals program in the main program
- Creating an ST POU for a simulation
- Defining the programs to be executed in the task configuration
- Defining the "active application" for the communication with the PLC
- Debugging the application program
- To establish a connection to the PLC, see the following sections:
- Starting the gateway server and PLC
- In the very first communication configuration: Adding the gateway

3.3 Visualization

Under the menu **CODESYS Visualization**, you can read more about the possibilities with visualization.

The screenshot shows a web browser window for the CODESYS Online Help. The URL is help.codesys.com/webapp/_visu_f_core_visualization;product=core_visualization;version=3.5.17.0. The page title is "CODESYS Visualization". On the left, there is a navigation sidebar with a tree view of topics. The "CODESYS Visualization" topic is highlighted. The main content area includes a section titled "Everything in one project" and a "Note" section.

Everything in one project

In the same CODESYS project, you use CODESYS Visualization to create the suitable user interface for your application. You link the visualization to the application variables and in this way they can animate and display data. When creating a visualization and an application, you use common functions, for example, as library and source code management or find/replace throughout the project.

Note

For some hints and best practises for configuring and creating a visualization see the document "Best Practices, Visualization". It is available in PDF format with the CODESYS installation.

- Functionality overview
- System overview and mechanism, display variants

Functionality overview

- **Display variant depending on the target platform**

You can run the same visualization on different target platforms. Possible display variants include CODESYS WebVisu, CODESYS TargetVisu, and CODESYS HMI. Moreover, In addition, there is a display integrated in the development system.

- **Visualization editor**

In the graphic editor, you design the desired user interface from visualization elements. The visualization elements are provided from libraries in a toolbox. You

3.4 Programming references

Detailed information about programming is found under the menu **Reference, Programming**.

The screenshot shows the 'Reference, Programming' section of the CODESYS Online Help. The left sidebar contains a navigation tree with topics like 'CODESYS Development System', 'Configuring CODESYS', and 'Programming Languages and Editors'. The main content area displays a list of programming-related topics: 'Variables', 'Operators', 'Operands', 'Data Types', 'Pragmas', 'Identifiers', 'Shadowing Rules', 'Keywords', 'Methods 'FB_Init', 'FB_Reinit', and 'FB_Exit'', and 'Error Messages and Warnings'. The top bar includes links for 'Imprint' and 'Privacy Policy'.

3.5 Libraries included in CODESYS

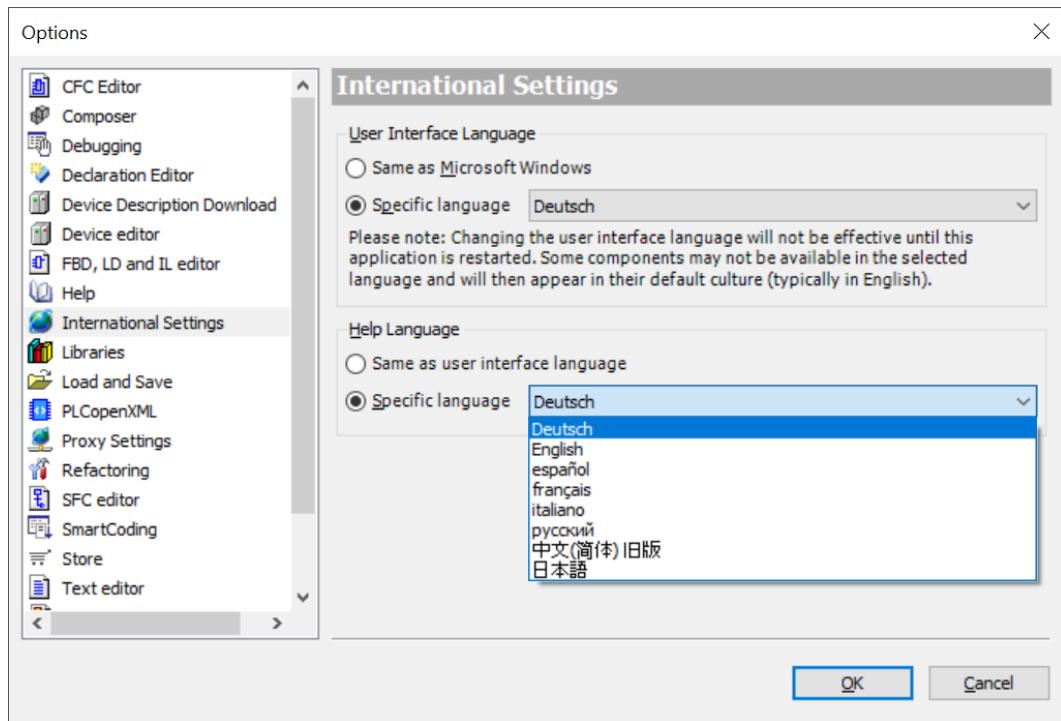
The standard libraries are described under the menu **Libraries**.

The screenshot shows the 'Libraries' section of the CODESYS Online Help. The left sidebar lists various categories such as 'CODESYS Development System', 'Fieldbus Support', and 'Libraries'. Under 'Libraries', there is a link to 'Guidelines for Creating Libraries'. The main content area is titled 'Libraries' and contains text explaining that libraries are used for preparing POU's and functions for use in CODESYS applications. It also provides links for 'Managing Libraries' and 'Creating your own CODESYS libraries'. A 'See also' section includes a link to 'Using Libraries'. The top bar includes links for 'Imprint' and 'Privacy Policy'.

More information about libraries is found in the **Library Manager** for DEIF specific libraries.

3.6 Language settings

The default language for the menu and help files is English. You can change this under **Tool > Options > International Settings** to a variety of languages.



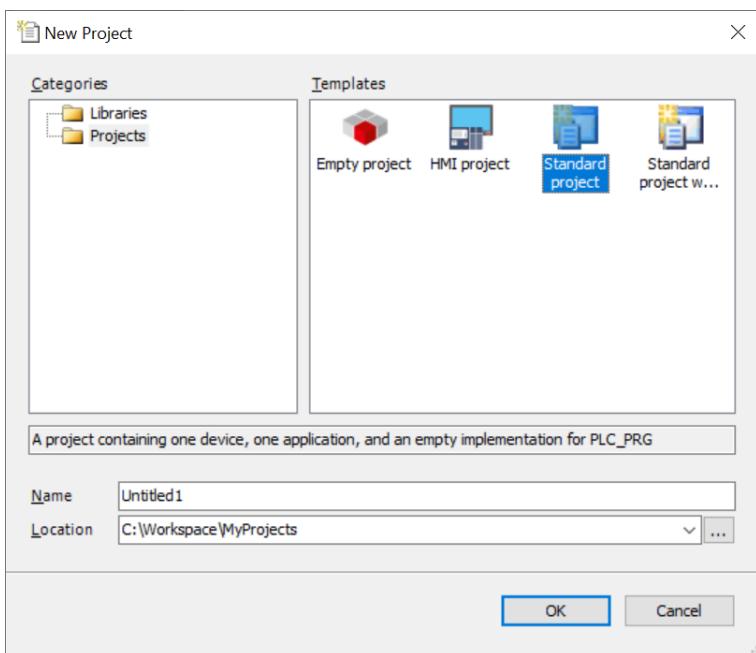
NOTE The CODESYS TSP must be installed before you change the language settings.

4. Create a CODESYS project

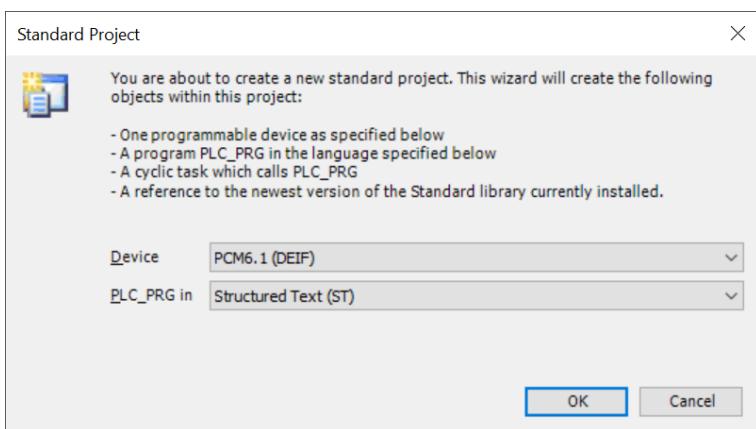
4.1 Create a new project

To create a new CODESYS project:

1. Go to **File > New Project ***.



2. Select **Standard project** in the Templates field.
3. Write a project name.
4. Select a location path for the project file.
5. Select **OK** to open the Standard Project window.



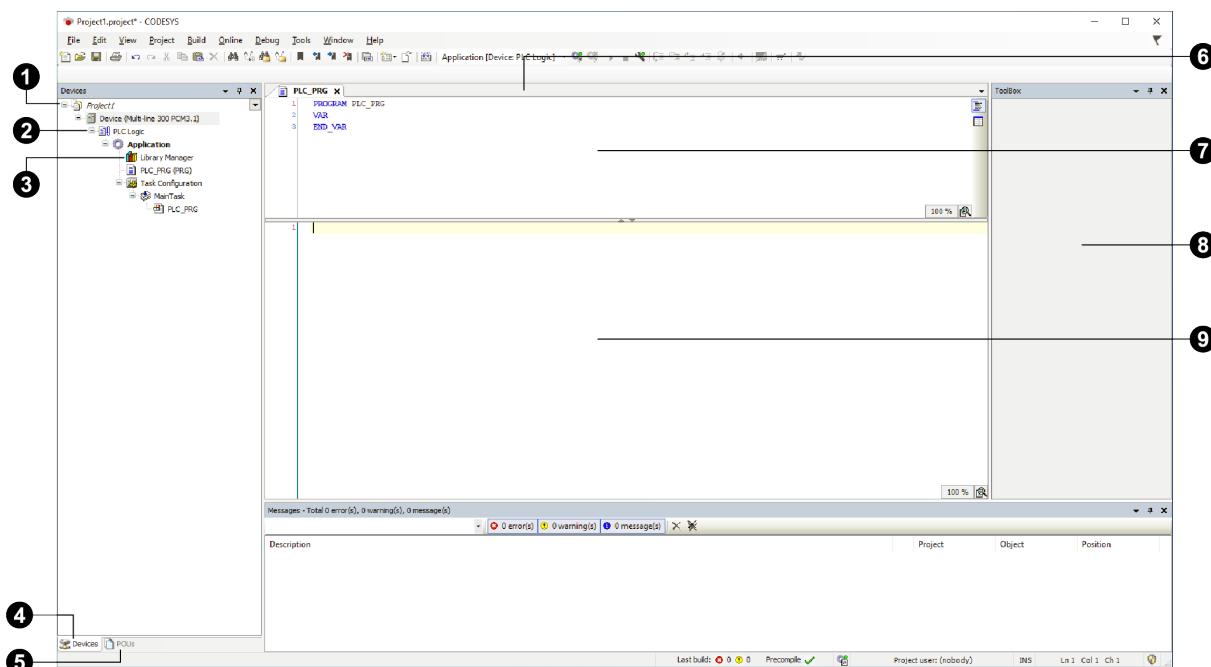
6. In the Device field, select one of these as the device:
 - **AMC 300 PCM 3.1 (DEIF A/S)**
 - **AWC 500 PCM 5.2 (DEIF A/S)**
 - **AMC 600 PCM 6.1 (DEIF A/S)** or
 - **iE 250 PCM2.1 (DEIF A/S)**
7. In the PLC_PRG in field, select **Structured Text (ST)** as the programming language. **
8. Select **OK** to continue.

NOTE * You can also select **Empty project** if you want to create an entire project from scratch.

NOTE ** New POU's can use a different programming language.

4.2 CODESYS layout

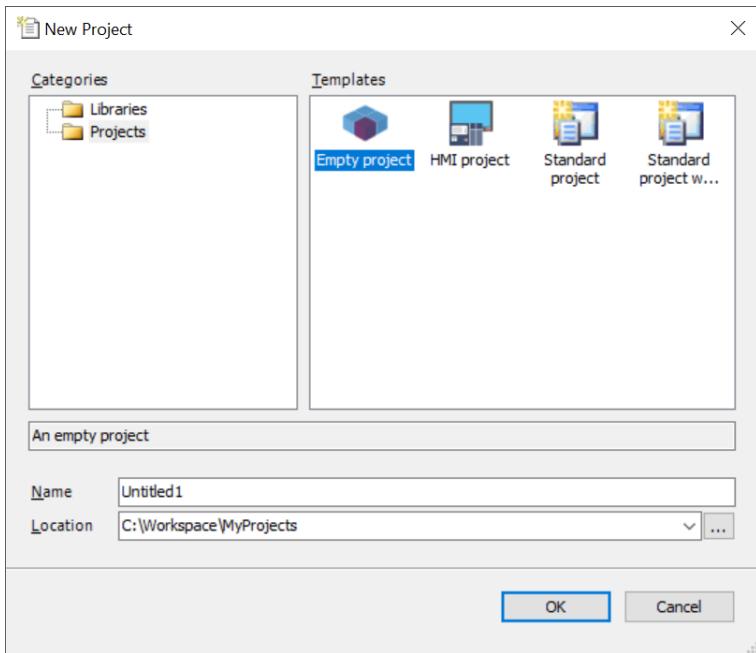
The image below shows the terminology used for the project view throughout the CODESYS manual.



No.	Item	Description
1	Project tree	The project tree is an overview of your project. A typical project will consist of: <ul style="list-style-type: none"> • One or more devices (AMC 300, AWC 500, AMC 600, or iE 250 PLC controllers). • One or more applications containing the Libraries, POU:s and tasks.
2	PLC Logic node	A PLC Logic node shows that the device is a programmable device and has no other functions associated to it.
3	Library manager	The Library manager contains the libraries for the project. Each library consists of functions and function blocks that can be used in your programs.
4	Devices tab	The Devices tab gives you quick access to the project tree.
5	POU:s tab	The POU:s (Program Object Units) tab gives you quick access to the device independent POU:s.
6	Working area	The working area consists of tabs representing different parts of the project. These project parts can be opened from the project tree. The illustration shows the working area for the POU, PLC_PRG. The working area for this POU consists of a declaration workspace, an implementation workspace and a toolbox menu.
7	Declaration workspace	The declaration workspace consists of the variables for the POU functions.
8	Additional toolboxes	Some elements have additional toolboxes to help you build your program, for example Visualisation.
9	Implementation workspace	The implementation workspace is used to program your POU.

4.3 Build from an empty project

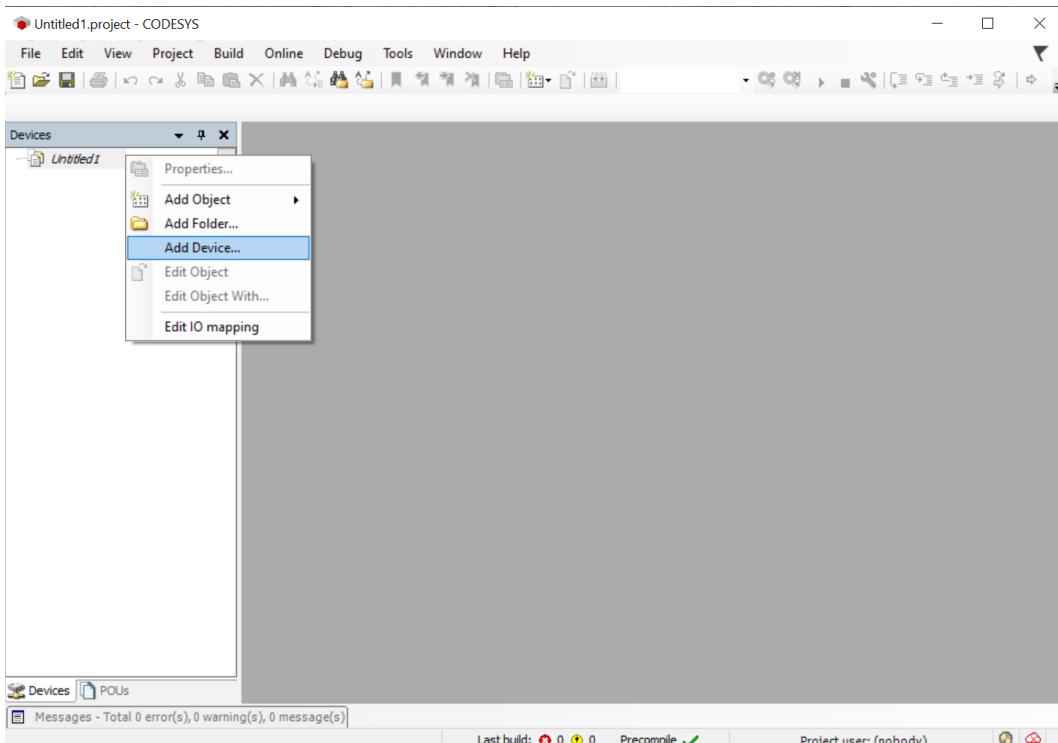
1. Select **File > New Project > Empty project.**



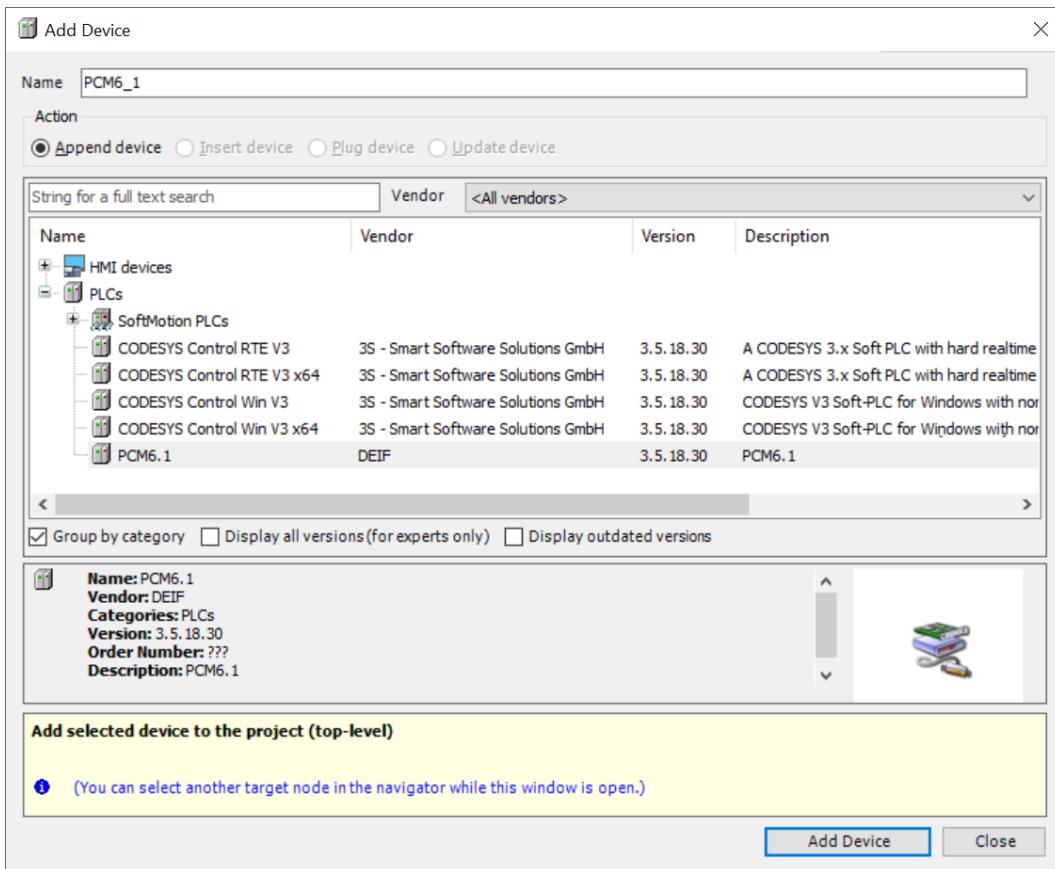
2. Write a project name in the field **Name** (for example, Project1).
3. Select a location to save the project (for example, C:\Workspace\MyProject\).
4. Select **OK** to continue.

4.4 Add the DEIF Device

1. In the project window, select **Add Device**.



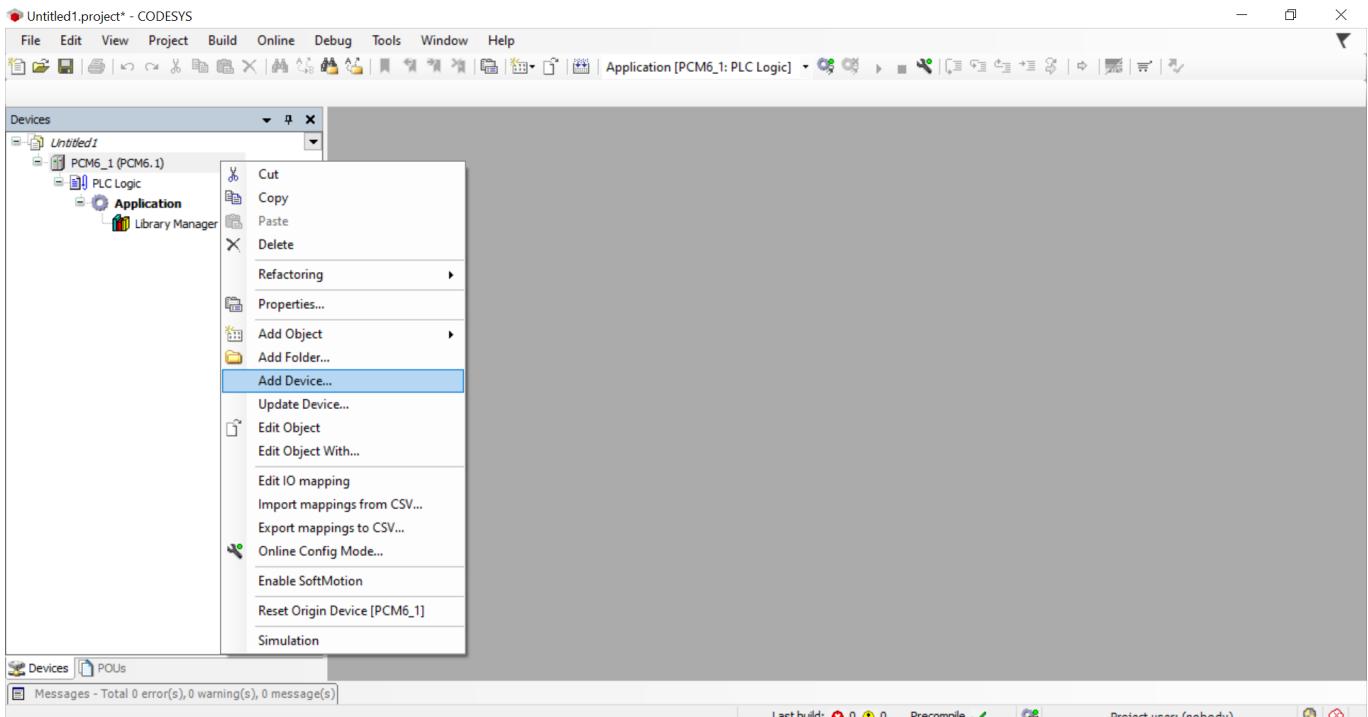
2. In the Add Device window, select a device from the list.



3. Select **Add Device**.

4.5 Add EtherCAT master device

1. In the project window, select **Add Device**.



2. In the Add Device window, select a device from the list.

Add Device

Name: EtherCAT_Master

Action:

- Append device
- Insert device
- Plug device
- Update device

Name	Vendor	Version	Description
CXxxxx internal EtherCAT Master	3S - Smart Software Solutions GmbH	4.3.0.0	CXxxxx internal EtherCAT Ma...
EtherCAT Master	3S - Smart Software Solutions GmbH	4.3.0.0	EtherCAT Master...
EtherCAT Master SoftMotion	3S - Smart Software Solutions GmbH	4.3.0.0	EtherCAT Master SoftMotion..

Group by category Display all versions (for experts only) Display outdated versions

EtherCAT Master

Name: EtherCAT Master
Vendor: 3S - Smart Software Solutions GmbH
Categories: Master
Version: 4.3.0.0
Order Number:
Description: EtherCAT Master...

Append selected device as last child of
PCM6_1

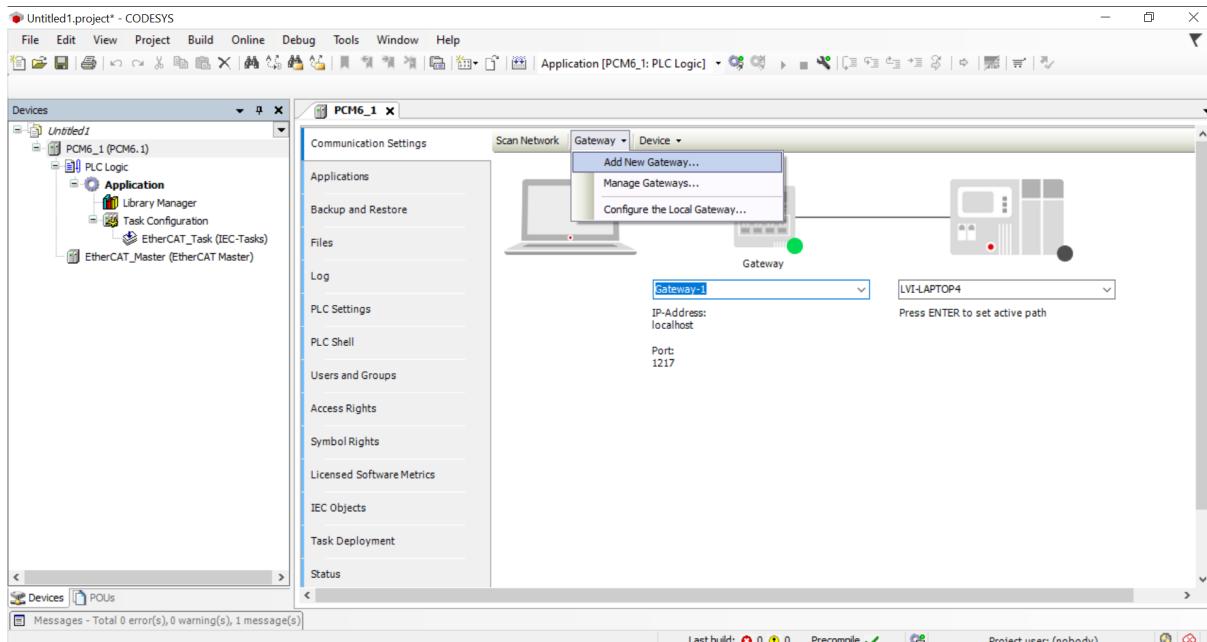
ⓘ (You can select another target node in the navigator while this window is open.)

Add Device **Close**

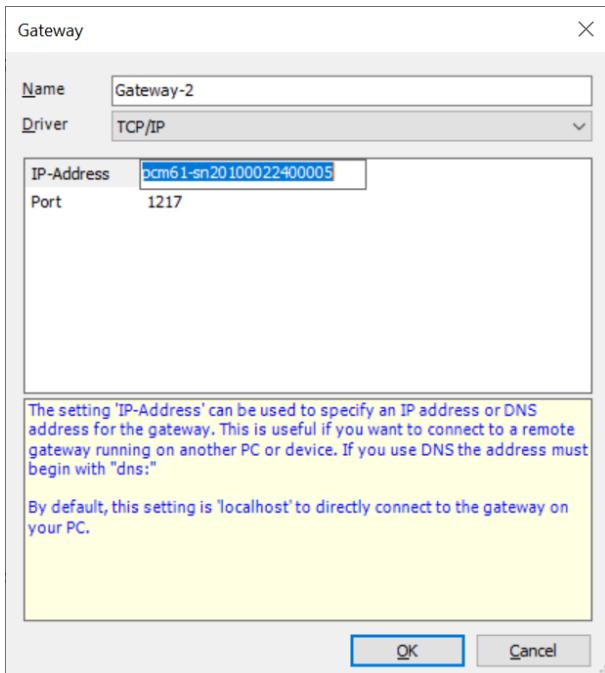
3. Select **Add Device**.

4.6 Connect to the AMC 300, AWC 500, AMC 600, or iE 250 PLC controller

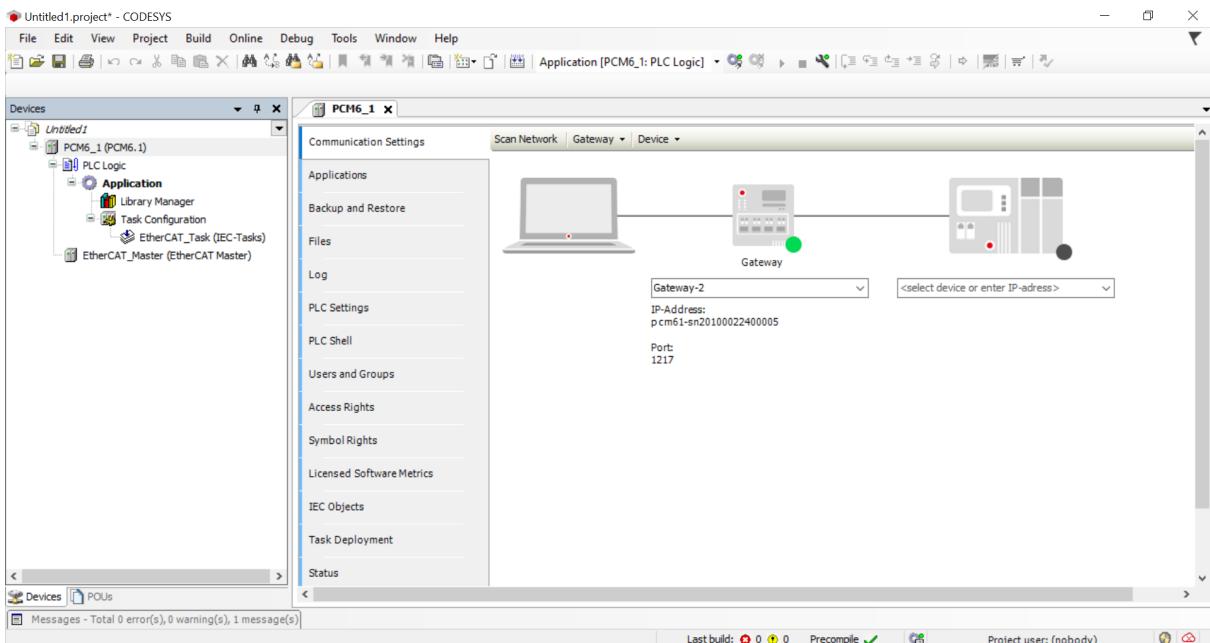
1. In the project window, double-click the AMC 300, AWC 500, AMC 600, or iE 250 PLC controller.
 - A gateway with the default IP address **localhost** is shown.
 - We recommend you create a new gateway with a new IP address or hostname for the controller.
2. Select **Gateway > Add new gateway**.



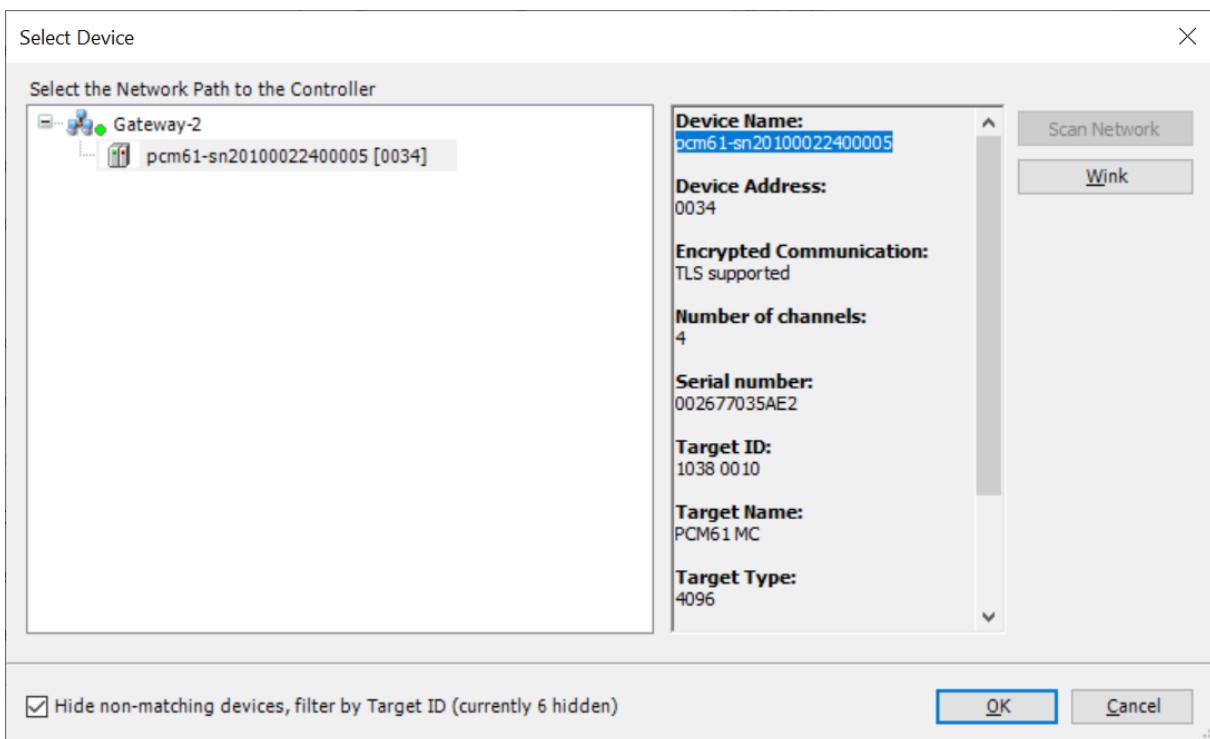
3. Enter the hostname or the IP address for AMC 300, AWC 500, AMC 600, or iE 250 PLC controller (for example, 192.168.20.13).



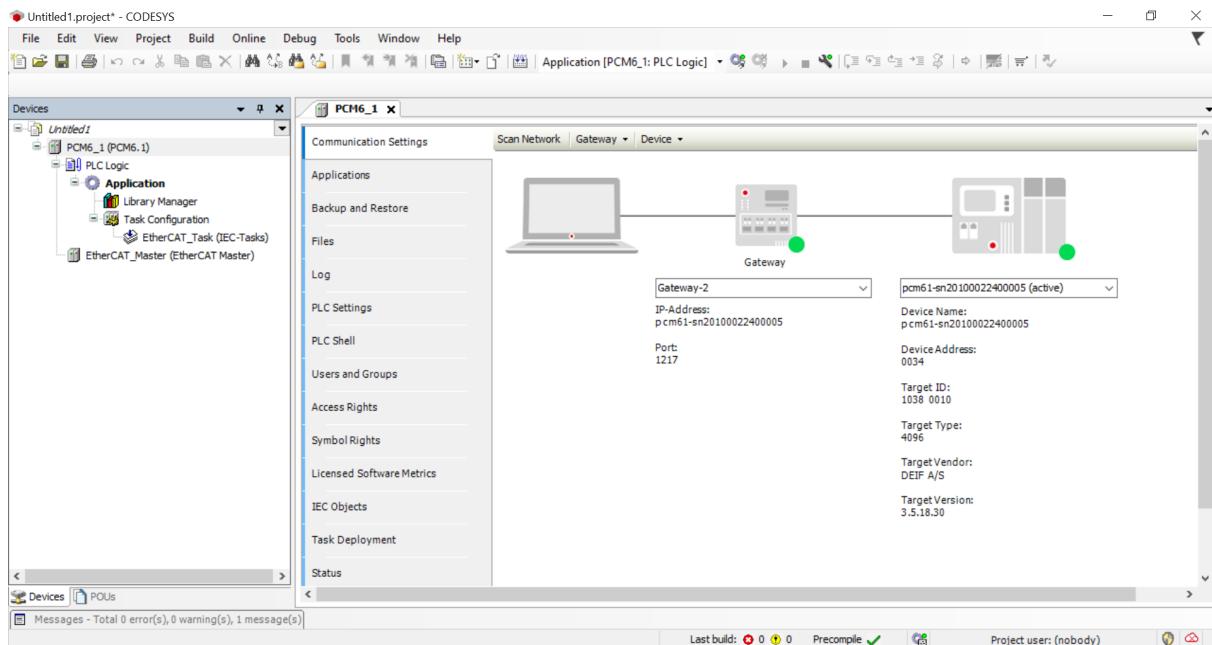
4. Select **OK**.
5. Select **Scan Network** to find the PLC controller on the network.



6. Select the device.
7. Select **OK**.
8. Select **Device**.
9. Select the device to set the active network path to the controller.

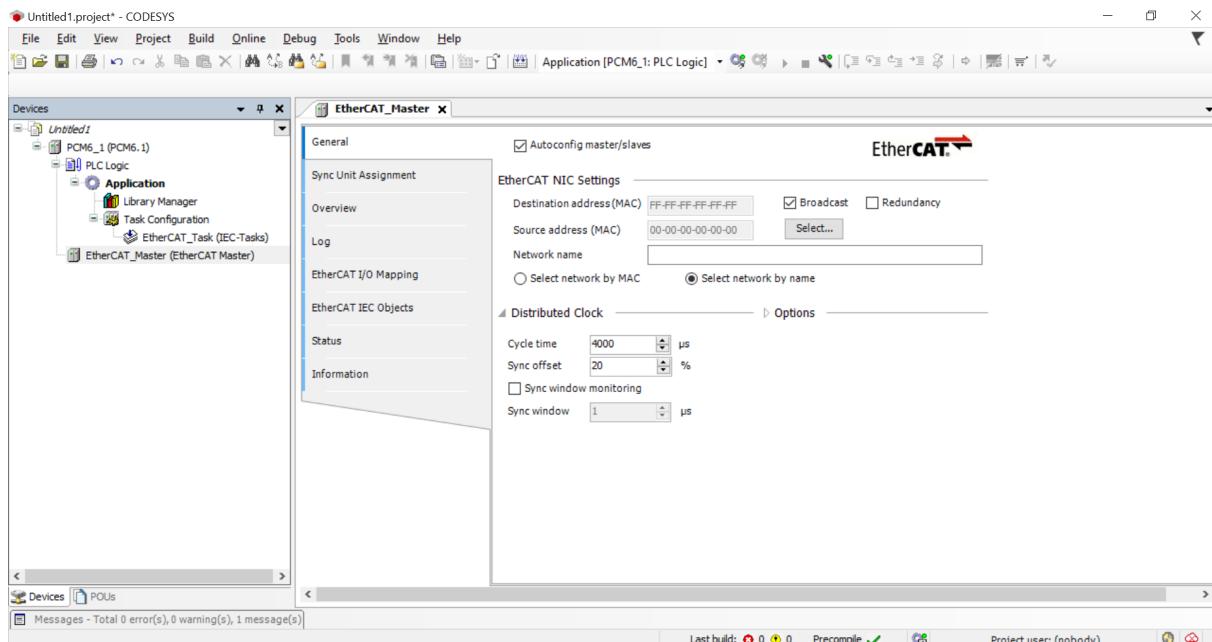


10. Select **OK**.
11. The connection is now active.

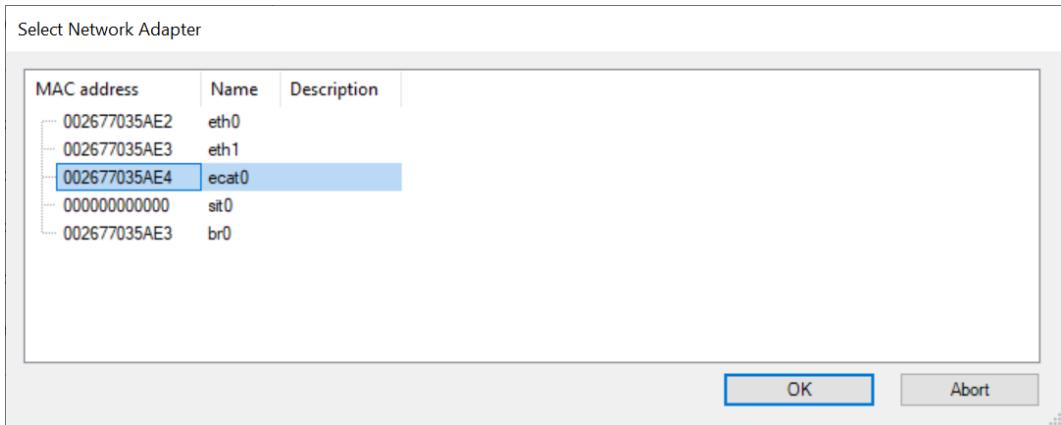


4.7 Setup EtherCAT master

1. Open the **EtherCAT_Master** tag.



2. Change the NIC Settings to **Select network by name**.
3. Select **Browse** to find the network interface to bind the EtherCAT master to.



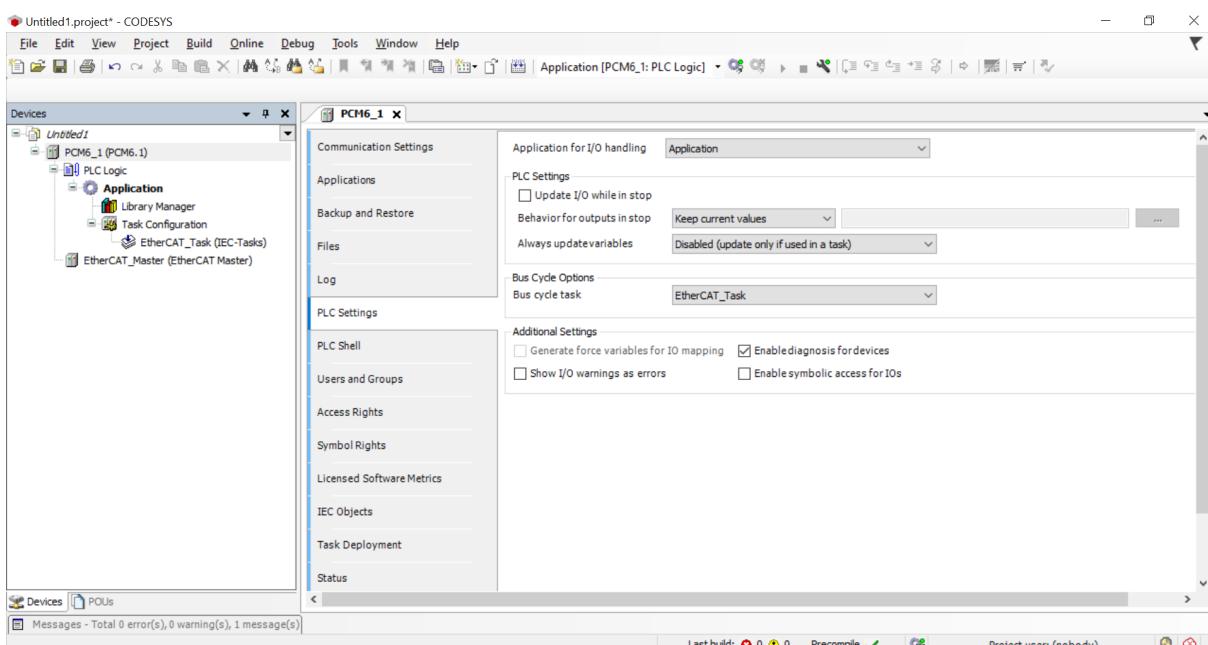
4. Select:

- AMC 300: **eth0 adapter*** (corresponding to EtherCAT OUT port 1 and EtherCAT OUT port 2)
- AWC 500: **ecat0 adapter***
- AMC 600: **ecat0 adapter***

NOTE *The same network adapter number for the eth0 (EtherCAT port) is used on all shipped devices.

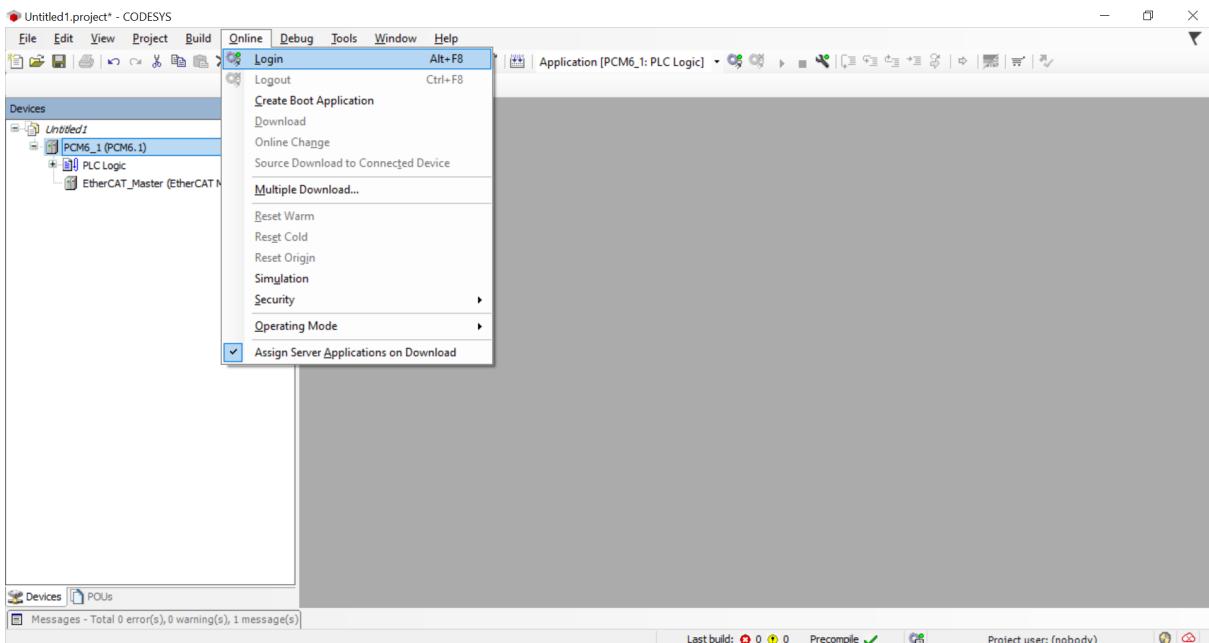
We recommend to specify which task handles the bus communication:

- In **Device > PLC Settings > Bus cycle options**: Specify the **Bus cycle task** to **EtherCAT_master**.

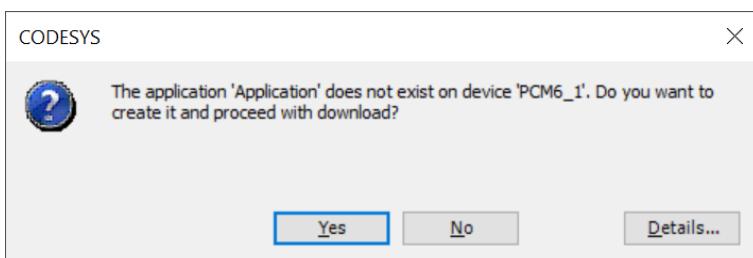


4.8 Scan for devices

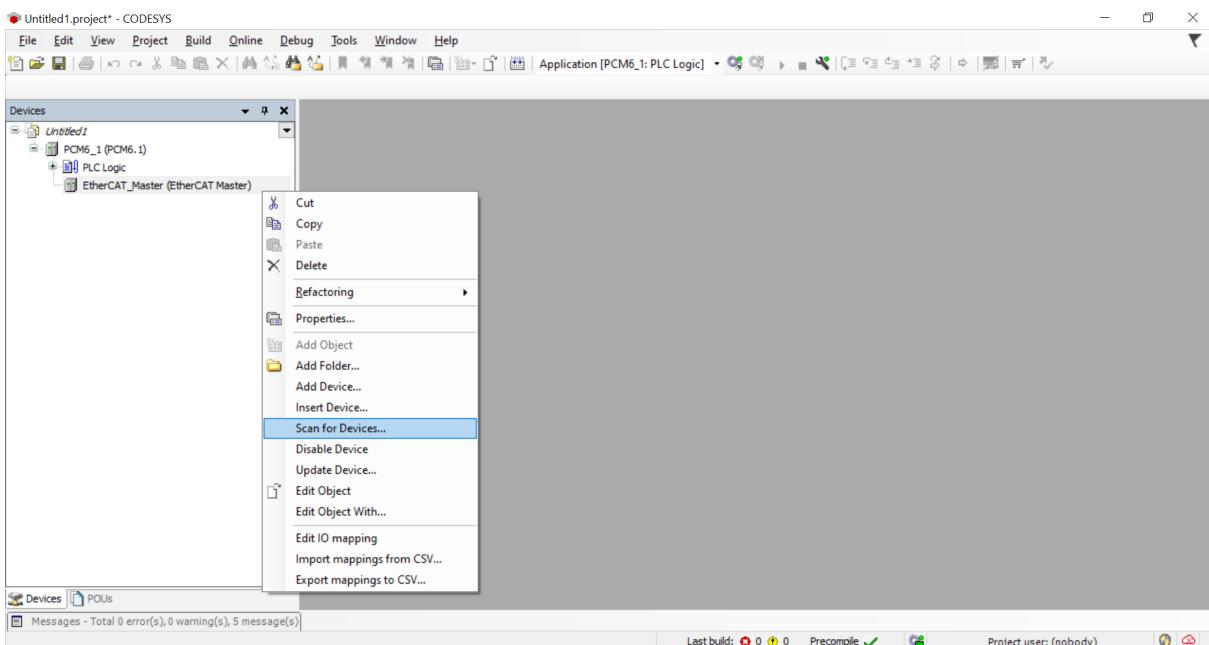
- Login to the PLC.



2. In the pop-up window, select **Yes** to create an application.



3. Select **EtherCAT_Master (EtherCAT Master)**, and then **Scan For Devices...** in the drop-down menu.



NOTE If EtherCAT Master is running on the PLC, you can scan for devices without being logged in. If a scan fails, then use the above procedure.

4. In the devices window, select **Copy All Devices to Project**.

Scan Devices

Scanned Devices

Device name	Device type	Alias Address
PCM61	PCM6.1 Computer Module	0
AIO61	AIO6.1 Analogue I/O Module	0
TIM61	TIM6.1 Temperature Input Module	0
DIO61	DIO6.1 Digital Input and Output	0
IFM61	IFM6.1 Interface and Fieldbus M...	0
IFM62	IFM6.2 Interface and Fieldbus...	0
IFM61_1	IFM6.1 Interface and Fieldbus...	0
SIM62	SIM6.2 Station Interface Module	0

Assign Address Show differences to project

Copy All Devices to Project Close

NOTE Due to a bug in CODESYS TSP, select the devices and **Copy to project**. Then add the SIM6.2 manually under PCM6.1.

Scan Devices

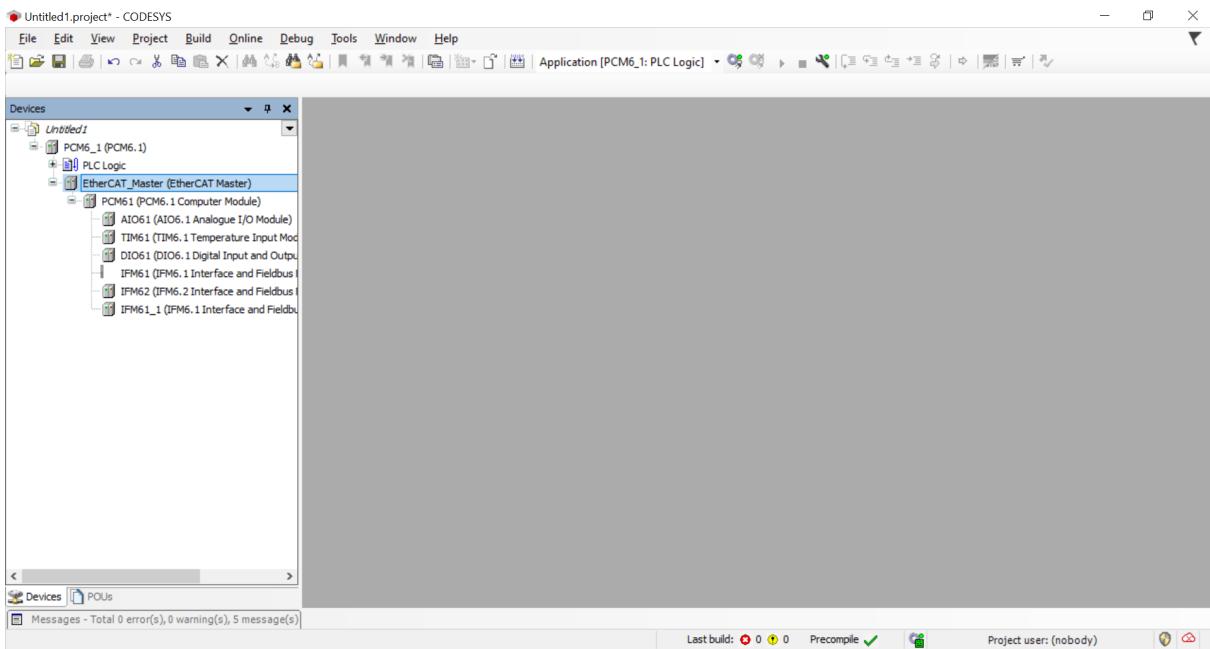
Scanned Devices

Device name	Device type	Alias Address
PCM61	PCM6.1 Computer Module	0
AIO61	AIO6.1 Analogue I/O Module	0
TIM61	TIM6.1 Temperature Input Module	0
DIO61	DIO6.1 Digital Input and Output	0
IFM61	IFM6.1 Interface and Fieldbus M...	0
IFM62	IFM6.2 Interface and Fieldbus...	0
IFM61_1	IFM6.1 Interface and Fieldbus...	0
SIM62	SIM6.2 Station Interface Module	0

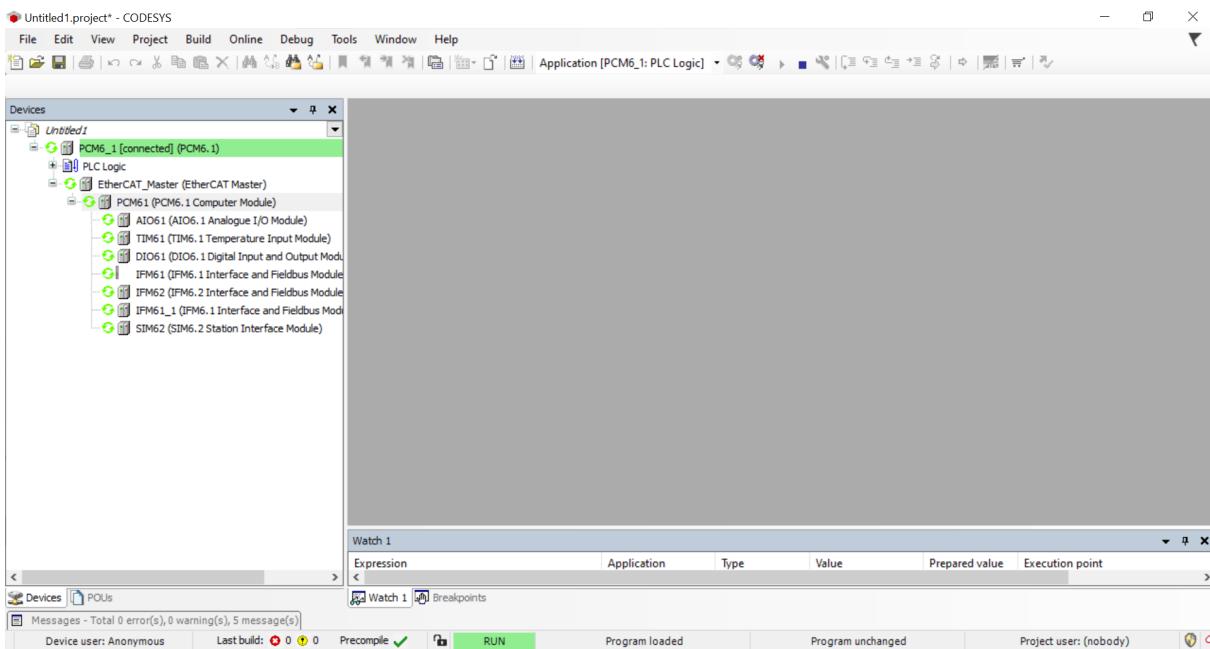
Assign Address Show differences to project

Copy to project Close

- The devices are now displayed in the Devices tree.



6. If the project is downloaded again, the entire EtherCAT network can enter operation.



4.9 I/O module variables

In this section, an overview of the IO mapper of each module for the different controllers is shown.

4.9.1 AMC 300

IOM3·1 variables

The screenshot shows the CODESYS IDE interface with the following details:

- Project Tree:** Shows the project structure with a Device (Multi-line 300 PCM3.1) containing PLC Logic, Application, EtherCAT Master, and Power Supply Modules (PSM_3_1, PSM_3_2).
- Device View:** A tree view for the IOM_3_1 module under the EtherCAT I/O Mapping category.
- Table View:** A detailed table of I/O mappings for the IOM_3_1 module. The table has columns for Variable, Mapping, Channel, Address, Type, Unit, and Description.

Variable	Mapping	Channel	Address	Type	Unit	Description
		Relay 1	%QX10.2	BIT		Relay 1
		Relay 2	%QX10.3	BIT		Relay 2
		Relay 3	%QX10.4	BIT		Relay 3
		Relay 4	%QX10.5	BIT		Relay 4
		DI 1	%IX632.0	BIT		DI 1
		DI 2	%IX632.1	BIT		DI 2
		DI 3	%IX632.2	BIT		DI 3
		DI 4	%IX632.3	BIT		DI 4
		DI 5	%IX632.4	BIT		DI 5
		DI 6	%IX632.5	BIT		DI 6
		DI 7	%IX632.6	BIT		DI 7
		DI 8	%IX632.7	BIT		DI 8
		DI 9	%IX633.0	BIT		DI 9
		DI 10	%IX633.1	BIT		DI 10

- Status Bar:** Shows build status (Last build: 0 errors, 0 warnings), precompile status, and project user information.

IOM3-2 variables

The screenshot shows the CODESYS Development Studio interface with the project 'Project1.project'. The left sidebar displays the device tree under 'Project1' with nodes like 'Device (Multi-line 300 PCM3.1)', 'PLC Logic', 'EtherCAT Master', and 'Port 1'. The main area shows the 'IOM_3_2' configuration tab with the 'EtherCAT I/O Mapping' tab selected. A table lists variables, their mappings, channels, addresses, types, units, and descriptions. The table includes rows for relay outputs (Relay_1 to Relay_4), output values (QD4 to QD7), digital inputs (DI1 to DI4), and various status and temperature inputs.

Variable	Mapping	Channel	Address	Type	Unit	Description
Relay_1			%QX12.0	BIT		Relay_1
Relay_2			%QX12.1	BIT		Relay_2
Relay_3			%QX12.2	BIT		Relay_3
Relay_4			%QX12.3	BIT		Relay_4
Output Value			%QD4	REAL		Output Value
Output Value			%QD5	REAL		Output Value
Output Value			%QD6	REAL		Output Value
Output Value			%QD7	REAL		Output Value
DI1			%IX36.0	BIT		DI1
DI2			%IX36.1	BIT		DI2
DI3			%IX36.2	BIT		DI3
DI4			%IX36.3	BIT		DI4
Output Value			%ID160	REAL		Output Value
Output Enabled			%IW322	INT		Output Enabled
Output Value			%ID162	REAL		Output Value
Output Enabled			%IW326	INT		Output Enabled
Output Value			%ID164	REAL		Output Value
Output Enabled			%IW330	INT		Output Enabled
Output Value			%ID166	REAL		Output Value
Output Enabled			%IW334	INT		Output Enabled
Input Value			%ID168	REAL		Input Value
Status			%IW338	INT		Status
Input Value			%ID170	REAL		Input Value
Status			%IW342	INT		Status
Input Value			%ID172	REAL		Input Value
Status			%IW346	INT		Status
Input Value			%ID174	REAL		Input Value
Status			%IW350	INT		Status

IOM3-3 variables

The screenshot shows the CODESYS Development Studio interface with the project 'Project1.project'. The left sidebar displays the device tree under 'Project1' with nodes like 'Device (Multi-line 300 PCM3.1)', 'PLC Logic', 'EtherCAT Master', and 'Port 1'. The main area shows the 'IOM_3_3' configuration tab with the 'EtherCAT I/O Mapping' tab selected. A table lists variables, their mappings, channels, addresses, types, units, and descriptions. The table includes rows for reserved inputs, analog inputs (Input Value, Status), digital inputs (Status), and various temperature and compensation parameters.

Variable	Mapping	Channel	Address	Type	Unit	Description
Reserved			%QW16	UINT		Reserved
Input Value			%ID176	REAL		Input Value
Status			%IW354	INT		Status
Input Value			%ID178	REAL		Input Value
Status			%IW358	INT		Status
Input Value			%ID180	REAL		Input Value
Status			%IW362	INT		Status
Input Value			%ID182	REAL		Input Value
Status			%IW366	INT		Status
Input Value			%ID184	REAL		Input Value
Status			%IW370	INT		Status
Input Value			%ID186	REAL		Input Value
Status			%IW374	INT		Status
Input Value			%ID188	REAL		Input Value
Status			%IW378	INT		Status
Input Value			%ID190	REAL		Input Value
Status			%IW382	INT		Status
Input Value			%ID192	REAL		Input Value
Status			%IW386	INT		Status
Input Value			%ID194	REAL		Input Value
Status			%IW390	INT		Status
MI_PowerEnabled			%IX782.0	BIT		MI_PowerEnabled
Temperature_1			%ID196	REAL		Temperature_1
Temperature_2			%ID197	REAL		Temperature_2
Temperature_3			%ID198	REAL		Temperature_3
Temperature_4			%ID199	REAL		Temperature_4
Temperature_5			%ID200	REAL		Temperature_5
CompensationTemperature_1			%ID201	REAL		CompensationTemp

IOM3-4 variables

The screenshot shows the CODESYS development environment for Project1.project. The left pane displays the project tree under 'Project1', including 'Device (Multi-line 300 PCM3.1)', 'PLC Logic', 'EtherCAT Master (EtherCAT Master)', and various module configurations like 'PSM_3_1' and 'PSM_3_2'. The right pane is focused on the 'IOM_3_4' device, showing its I/O mapping. A table lists 32 variables (Relay 1 to Relay 16 and DI 1 to DI 16) with their corresponding channel addresses (%QX34.0 to %QX34.15 and %IX846.4 to %IX846.15). Buttons at the bottom include 'Reset Mapping', 'Always update variables', and 'Use parent device setting'.

Variable	Mapping	Channel	Address	Type	Unit	Description
Relay 1			%QX34.0	BIT		Relay 1
Relay 2			%QX34.1	BIT		Relay 2
Relay 3			%QX34.2	BIT		Relay 3
Relay 4			%QX34.3	BIT		Relay 4
Relay 5			%QX34.4	BIT		Relay 5
Relay 6			%QX34.5	BIT		Relay 6
Relay 7			%QX34.6	BIT		Relay 7
Relay 8			%QX34.7	BIT		Relay 8
Relay 9			%QX35.0	BIT		Relay 9
Relay 10			%QX35.1	BIT		Relay 10
Relay 11			%QX35.2	BIT		Relay 11
Relay 12			%QX35.3	BIT		Relay 12
DI 1			%IX846.4	BIT		DI 1
DI 2			%IX846.5	BIT		DI 2
DI 3			%IX846.6	BIT		DI 3
DI 4			%IX846.7	BIT		DI 4
DI 5			%IX847.0	BIT		DI 5
DI 6			%IX847.1	BIT		DI 6
DI 7			%IX847.2	BIT		DI 7
DI 8			%IX847.3	BIT		DI 8
DI 9			%IX847.4	BIT		DI 9
DI 10			%IX847.5	BIT		DI 10
DI 11			%IX847.6	BIT		DI 11
DI 12			%IX847.7	BIT		DI 12
DI 13			%IX848.0	BIT		DI 13
DI 14			%IX848.1	BIT		DI 14
DI 15			%IX848.2	BIT		DI 15
DI 16			%IX848.3	BIT		DI 16

ACM3-1 variables

The screenshot shows the CODESYS development environment for Project1.project. The left pane displays the project tree under 'Project1', including 'Device (Multi-line 300 PCM3.1)', 'PLC Logic', 'EtherCAT Master (EtherCAT Master)', and various module configurations like 'PSM_3_1' and 'PSM_3_2'. The right pane is focused on the 'ACM_3_1' device, showing its I/O mapping. A table lists 32 variables (InhibitPdo_Out to P_ACIV_UxL4) with their corresponding channel addresses (%Q01 to %ID37). Buttons at the bottom include 'Reset Mapping', 'Always update variables', and 'Use parent device setting'.

Variable	Mapping	Channel	Address	Type	Unit	Description
InhibitPdo_Out			%Q01	UDINT		InhibitPdo_Out
SuppressFastDetectPdo_Out			%QW4	UINT		SuppressFastDetectPdo_Out
RMS_ACIV_UL1N			%ID12	REAL		RMS_ACIV_UL1N
RMS_ACIV_UL2N			%ID13	REAL		RMS_ACIV_UL2N
RMS_ACIV_UL3N			%ID14	REAL		RMS_ACIV_UL3N
RMS_ACIV_ULRESIDUAL			%ID15	REAL		RMS_ACIV_ULRESIDUAL
RMS_ACIV_UL1L2			%ID16	REAL		RMS_ACIV_UL1L2
RMS_ACIV_UL2L3			%ID17	REAL		RMS_ACIV_UL2L3
RMS_ACIV_UL3L1			%ID18	REAL		RMS_ACIV_UL3L1
RMS_AC3C_IL4_ACV1			%ID19	REAL		RMS_AC3C_IL4_ACV1
RMS_AC2V_UL1N			%ID20	REAL		RMS_AC2V_UL1N
RMS_AC2V_UL2N			%ID21	REAL		RMS_AC2V_UL2N
RMS_AC2V_UL3N			%ID22	REAL		RMS_AC2V_UL3N
RMS_AC2V_ULRESIDUAL			%ID23	REAL		RMS_AC2V_ULRESIDUAL
RMS_AC2V_UL1L2			%ID24	REAL		RMS_AC2V_UL1L2
RMS_AC2V_UL2L3			%ID25	REAL		RMS_AC2V_UL2L3
RMS_AC2V_UL3L1			%ID26	REAL		RMS_AC2V_UL3L1
RMS_AC3C_IL1			%ID27	REAL		RMS_AC3C_IL1
RMS_AC3C_IL2			%ID28	REAL		RMS_AC3C_IL2
RMS_AC3C_IL3			%ID29	REAL		RMS_AC3C_IL3
RMS_AC3C_IRESIDUAL			%ID30	REAL		RMS_AC3C_IRESIDUAL
RMS_AC3C_IL4_ACV2			%ID31	REAL		RMS_AC3C_IL4_ACV2
RMS_AC3C_IEARTH_L4_ACV2			%ID32	REAL		RMS_AC3C_IEARTH_L4_ACV2
P_AC2V_L1			%ID33	REAL		P_AC2V_L1
P_AC2V_L2			%ID34	REAL		P_AC2V_L2
P_AC2V_L3			%ID35	REAL		P_AC2V_L3
P_AC2V_L4			%ID36	REAL		P_AC2V_L4
P_ACIV_UxL4			%ID37	REAL		P_ACIV_UxL4

PSM3·1 variables

Variable	Mapping	Channel	Address	Type	Unit	Description
Relay 1			%QX0.0	BIT		Relay 1
Relay 2			%QX0.1	BIT		Relay 2
Relay 3			%QX0.2	BIT		Relay 3
Temperature			%ID0	REAL		Temperature
CardOK			%IW2	INT		CardOK
LinkStatus			%IW3	INT		LinkStatus
Battery voltage			%ID2	REAL		Battery voltage
Backplane voltage			%ID3	REAL		Backplane voltage
Power Fail Early Warning			%IW8	INT		Power Fail Early Warning
PSM counter			%ID5	DINT		PSM counter
Min			%ID6	REAL		Min
Max			%ID7	REAL		Max
ADCvalue			%IW16	UINT		ADCvalue
index			%IW17	UINT		index
Start			%IW18	UINT		Start
Gain			%IW19	UINT		Gain
Offset			%IW20	INT		Offset

PSM3·2 variables

Variable	Mapping	Channel	Address	Type	Unit	Description
Relay 1			%QX36.0	BIT		Relay 1
Relay 2			%QX36.1	BIT		Relay 2
Relay 3			%QX36.2	BIT		Relay 3
Temperature			%ID213	REAL		Temperature
CardOK			%IW428	INT		CardOK
LinkStatus			%IW429	INT		LinkStatus
Battery voltage			%ID215	REAL		Battery voltage
Backplane voltage			%ID216	REAL		Backplane voltage
Power Fail Early Warning			%IW434	INT		Power Fail Early Warning
PSM counter			%ID218	DINT		PSM counter
Min			%ID219	REAL		Min
Max			%ID220	REAL		Max
ADCvalue			%IW442	UINT		ADCvalue
index			%IW443	UINT		index
Start			%IW444	UINT		Start
Gain			%IW445	UINT		Gain
Offset			%IW446	INT		Offset

4.9.2 AMC 600

DIO6·1 variables

The screenshot shows the CODESYS development environment with the following details:

- Title Bar:** Untitled1.project* - CODESYS
- Menu Bar:** File, Edit, View, Project, Build, Online, Debug, Tools, Window, Help
- Toolbar:** Standard icons for file operations like Open, Save, Print, etc.
- Devices Tree:** Shows the project structure under Untitled1, including PCM6_1 (PCM6.1) and EtherCAT_Master (EtherCAT Master).
- Central Window:** DIO61 x (PCM6.1)
 - General Tab:** Displays a table of variables with columns: Variable, Mapping, Channel, Address, Type, Unit, and Description.
 - Table Data:**

Variable	Mapping	Channel	Address	Type	Unit	Description
		D01	%QX6.0	BIT		DO1 (terminal 1)
		D02	%QX6.1	BIT		DO2 (terminal 2)
		D03	%QX6.2	BIT		DO3 (terminal 3)
		D04	%QX6.3	BIT		DO4 (terminal 4)
		D05	%QX6.4	BIT		DO5 (terminal 5)
		D06	%QX6.5	BIT		DO6 (terminal 16)
		D07	%QX6.6	BIT		DO7 (terminal 17)
		D08	%QX6.7	BIT		DO8 (terminal 18)
		D09	%QX7.0	BIT		DO9 (terminal 19)
		D010	%QX7.1	BIT		DO10 (terminal 20)
			Output status	%IX122.6	BIT	Output status (false if the output drivers are overk
		DI1	%IX123.0	BIT		DI1 (terminal 7)
		DI2	%IX123.1	BIT		DI2 (terminal 8)
		DI3	%IX123.2	BIT		DI3 (terminal 9)
		DI4	%IX123.3	BIT		DI4 (terminal 10)
		DI5	%IX123.4	BIT		DI5 (terminal 11)
		DI6	%IX123.5	BIT		DI6 (terminal 12)
		DI7	%IX123.6	BIT		DI7 (terminal 13)
 - Buttons:** Create new variable, Map to existing variable, Reset Mapping, Always update variables, Use parent device setting.
 - Bottom Status Bar:** Last build: 0 errors, 0 warnings, Precompile checked, Project user: (nobody)

AIO6·1 variables

The screenshot shows the CODESYS development environment with the following details:

- Title Bar:** Untitled1.project* - CODESYS
- Menu Bar:** File, Edit, View, Project, Build, Online, Debug, Tools, Window, Help
- Toolbar:** Standard icons for file operations like Open, Save, Print, etc.
- Devices Tree:** Shows the project structure under Untitled1, including PCM6_1 (PCM6.1) and EtherCAT_Master (EtherCAT Master).
- Central Window:** AIO61 x (PCM6.1)
 - General Tab:** Displays a table of variables with columns: Variable, Mapping, Channel, Address, Type, Unit, and Description.
 - Table Data:**

Variable	Mapping	Channel	Address	Type	Unit	Description
AO 1 Value		%QW1	INT			AO 1 Value
AO 2 Value		%QW2	INT			AO 2 Value
AI 1 Under range		%IX2.0	BIT			AI 1 Under range
AI 1 Over range		%IX2.1	BIT			AI 1 Over range
AI 1 Error		%IX2.6	BIT			AI 1 Error
AI 1 TxPDO State		%IX3.6	BIT			AI 1 TxPDO State
AI 1 TxPDO Toggle		%IX3.7	BIT			AI 1 TxPDO Toggle
AI 1 Value		%IW2	INT			AI 1 Value
AI 2 Under range		%IX6.0	BIT			AI 2 Under range
AI 2 Over range		%IX6.1	BIT			AI 2 Over range
AI 2 Error		%IX6.6	BIT			AI 2 Error
AI 2 TxPDO State		%IX7.6	BIT			AI 2 TxPDO State
AI 2 TxPDO Toggle		%IX7.7	BIT			AI 2 TxPDO Toggle
AI 2 Value		%IW4	INT			AI 2 Value
AI 3 Under range		%IX10.0	BIT			AI 3 Under range
AI 3 Over range		%IX10.1	BIT			AI 3 Over range
AI 3 Error		%IX10.6	BIT			AI 3 Error
AI 3 TxPDO State		%IX11.6	BIT			AI 3 TxPDO State
AI 3 TxPDO Toggle		%IX11.7	BIT			AI 3 TxPDO Toggle
 - Buttons:** Create new variable, Map to existing variable, Reset Mapping, Always update variables, Use parent device setting.
 - Bottom Status Bar:** Last build: 0 errors, 0 warnings, Precompile checked, Project user: (nobody)

TIM6·1 variables

The screenshot shows the CODESYS IDE interface with the project "Untitled1" open. The main window displays the "TIM61" configuration dialog. On the left, a tree view shows the device structure under "PCM6_1 (PCM6.1)". The "EtherCAT I/O Mapping" tab is selected. The right side contains a table listing variables, their mappings, addresses, types, units, and descriptions. The table includes rows for RTD 1 Under range, RTD 1 Over range, RTD 1 Error, RTD 1 TxPDO State, RTD 1 TxPDO Toggle, RTD 1 Value, RTD 2 Under range, RTD 2 Over range, RTD 2 Error, RTD 2 TxPDO State, RTD 2 TxPDO Toggle, RTD 2 Value, RTD 3 Under range, RTD 3 Over range, RTD 3 Error, RTD 3 TxPDO State, RTD 3 TxPDO Toggle, RTD 3 Value, and RTD 4 Under range.

Variable	Mapping	Channel	Address	Type	Unit	Description
RTD 1 Under range			%IX66.0	BIT		RTD 1 Under range
RTD 1 Over range			%IX66.1	BIT		RTD 1 Over range
RTD 1 Error			%IX66.6	BIT		RTD 1 Error
RTD 1 TxPDO State			%IX67.6	BIT		RTD 1 TxPDO State
RTD 1 TxPDO Toggle			%IX67.7	BIT		RTD 1 TxPDO Toggle
RTD 1 Value			%IW34	INT		RTD 1 Value
RTD 2 Under range			%IX70.0	BIT		RTD 2 Under range
RTD 2 Over range			%IX70.1	BIT		RTD 2 Over range
RTD 2 Error			%IX70.6	BIT		RTD 2 Error
RTD 2 TxPDO State			%IX71.6	BIT		RTD 2 TxPDO State
RTD 2 TxPDO Toggle			%IX71.7	BIT		RTD 2 TxPDO Toggle
RTD 2 Value			%IW36	INT		RTD 2 Value
RTD 3 Under range			%IX74.0	BIT		RTD 3 Under range
RTD 3 Over range			%IX74.1	BIT		RTD 3 Over range
RTD 3 Error			%IX74.6	BIT		RTD 3 Error
RTD 3 TxPDO State			%IX75.6	BIT		RTD 3 TxPDO State
RTD 3 TxPDO Toggle			%IX75.7	BIT		RTD 3 TxPDO Toggle
RTD 3 Value			%IW38	INT		RTD 3 Value
RTD 4 Under range			%IX78.0	BIT		RTD 4 Under range

IFM6·1 variables

The screenshot shows the CODESYS IDE interface with the project "Untitled1" open. The main window displays the "IFM61" configuration dialog. On the left, a tree view shows the device structure under "PCM6_1 (PCM6.1)". The "EtherCAT I/O Mapping" tab is selected. The right side contains a table listing variables, their mappings, addresses, types, units, and descriptions. The table includes rows for COM1 Ctrl, COM1 Data out 0, COM1 Data out 1, COM1 Data out 2, COM1 Data out 3, COM1 Data out 4, COM1 Data out 5, COM1 Data out 6, COM1 Data out 7, COM1 Data out 8, COM1 Data out 9, COM1 Data out 10, COM1 Data out 11, COM1 Data out 12, COM1 Data out 13, COM1 Data out 14, COM1 Data out 15, COM1 Data out 16, and COM1 Data out 17.

Variable	Mapping	Channel	Address	Type	Unit	Description
COM1 Ctrl			%QW4	UINT		COM1 Ctrl
COM1 Data out 0			%QB10	BYTE		COM1 Data out 0
COM1 Data out 1			%QB11	BYTE		COM1 Data out 1
COM1 Data out 2			%QB12	BYTE		COM1 Data out 2
COM1 Data out 3			%QB13	BYTE		COM1 Data out 3
COM1 Data out 4			%QB14	BYTE		COM1 Data out 4
COM1 Data out 5			%QB15	BYTE		COM1 Data out 5
COM1 Data out 6			%QB16	BYTE		COM1 Data out 6
COM1 Data out 7			%QB17	BYTE		COM1 Data out 7
COM1 Data out 8			%QB18	BYTE		COM1 Data out 8
COM1 Data out 9			%QB19	BYTE		COM1 Data out 9
COM1 Data out 10			%QB20	BYTE		COM1 Data out 10
COM1 Data out 11			%QB21	BYTE		COM1 Data out 11
COM1 Data out 12			%QB22	BYTE		COM1 Data out 12
COM1 Data out 13			%QB23	BYTE		COM1 Data out 13
COM1 Data out 14			%QB24	BYTE		COM1 Data out 14
COM1 Data out 15			%QB25	BYTE		COM1 Data out 15
COM1 Data out 16			%QB26	BYTE		COM1 Data out 16
COM1 Data out 17			%QB27	BYTE		COM1 Data out 17

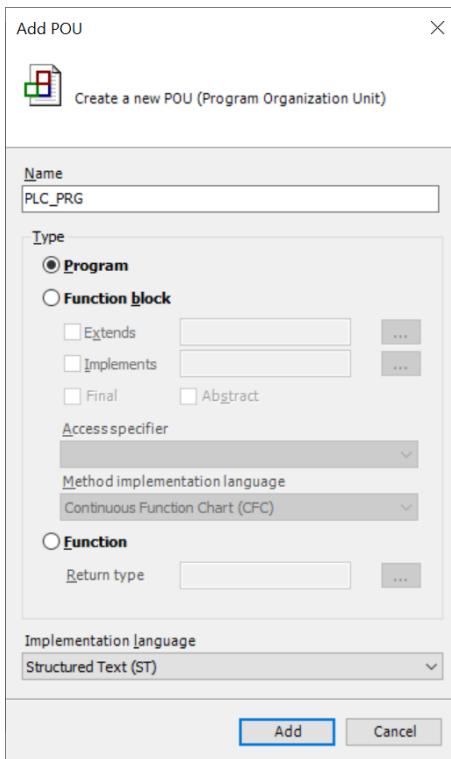
IFM6.2 variables

Variable	Mapping	Channel	Address	Type	Unit	Description
CAN 1 Tx counter			%QW52	UINT		CAN 1 Tx count
CAN 1 Rx counter			%QW53	UINT		CAN 1 Rx count
CAN 1 Number of tx messages			%QW54	UINT		CAN 1 Number
CAN 1Tx message 1			%QB110	ARRAY [0..9] OF BYTE		CAN 1Tx mess
CAN 1Tx message 2			%QB120	ARRAY [0..9] OF BYTE		CAN 1Tx mess
CAN 1Tx message 3			%QB130	ARRAY [0..9] OF BYTE		CAN 1Tx mess
CAN 1Tx message 4			%QB140	ARRAY [0..9] OF BYTE		CAN 1Tx mess
CAN 1Tx message 5			%QB150	ARRAY [0..9] OF BYTE		CAN 1Tx mess
CAN 1Tx message 6			%QB160	ARRAY [0..9] OF BYTE		CAN 1Tx mess
CAN 1Tx message 7			%QB170	ARRAY [0..9] OF BYTE		CAN 1Tx mess
CAN 1Tx message 8			%QB180	ARRAY [0..9] OF BYTE		CAN 1Tx mess
CAN 1Tx message 9			%QB190	ARRAY [0..9] OF BYTE		CAN 1Tx mess
CAN 1Tx message 10			%QB200	ARRAY [0..9] OF BYTE		CAN 1Tx mess
CAN 1 Auto reset when bus-off			%QX210.0	BIT		CAN 1 Auto res
CAN 2Tx counter			%QW106	UINT		CAN 2Tx count
CAN 2Rx counter			%QW107	UINT		CAN 2Rx count
CAN 2 Number of tx messages			%QW108	UINT		CAN 2 Number
CAN 2 Tx message 1			%QB218	ARRAY [0..9] OF BYTE		CAN 2 Tx mess

4.10 Add a program

1. Select Application > Add Object > POU....

2. In the Add POU window, tick Program and select Add.



4.11 Write a program

Example of a program.

```

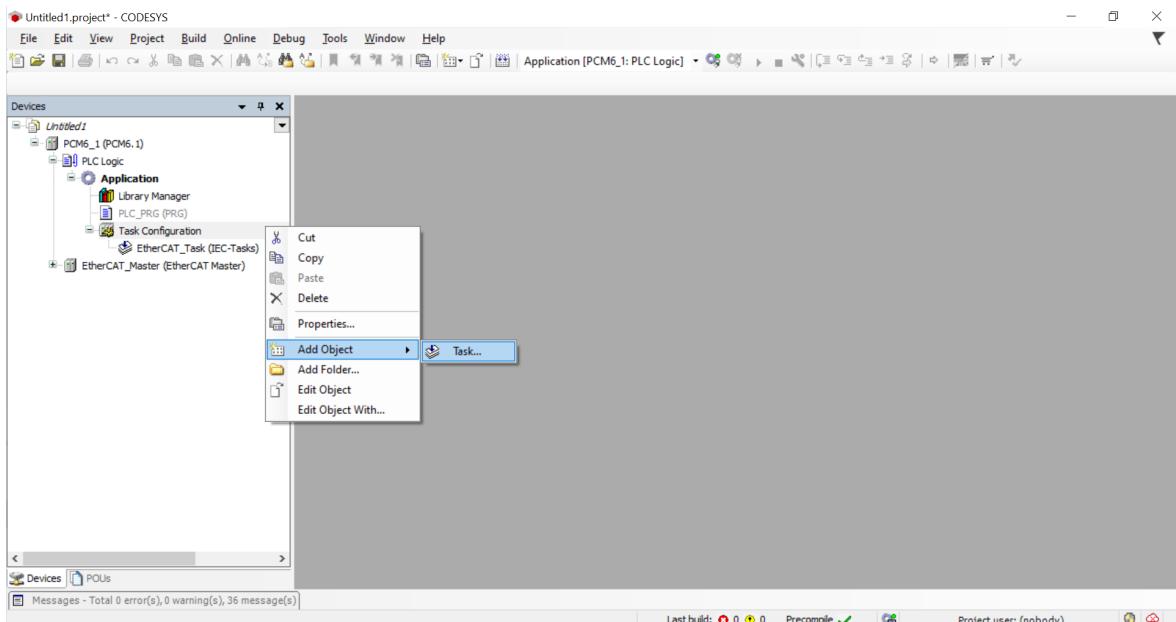
VAR
    Din : BOOL;
    Dout1: BOOL;
    Dout2: BOOL;
    Dout3: BOOL;
    Dout4: BOOL;
    safetyout : BOOL;
    cnt : INT;
    firsttime: BOOL := TRUE;
END_VAR

IF firsttime = TRUE THEN
    firsttime := FALSE;
END_IF
IF cnt > 50 THEN
    Dout4 := Dout3;
    Dout3 := Dout2;
    Dout2 := Dout1;
    Dout1 := NOT(Dout4);
    cnt := 0;
END_IF
cnt := cnt + 1;

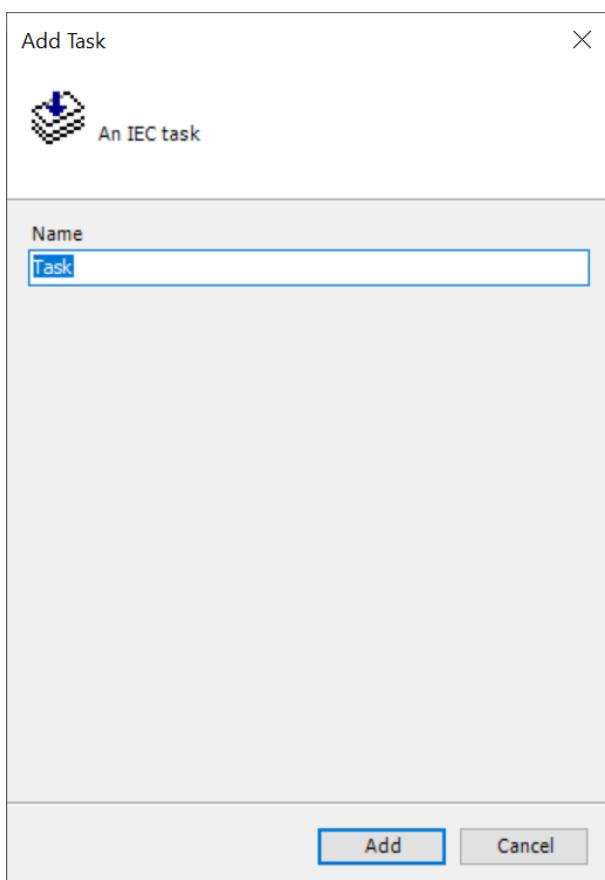
```

4.11.1 Add a task

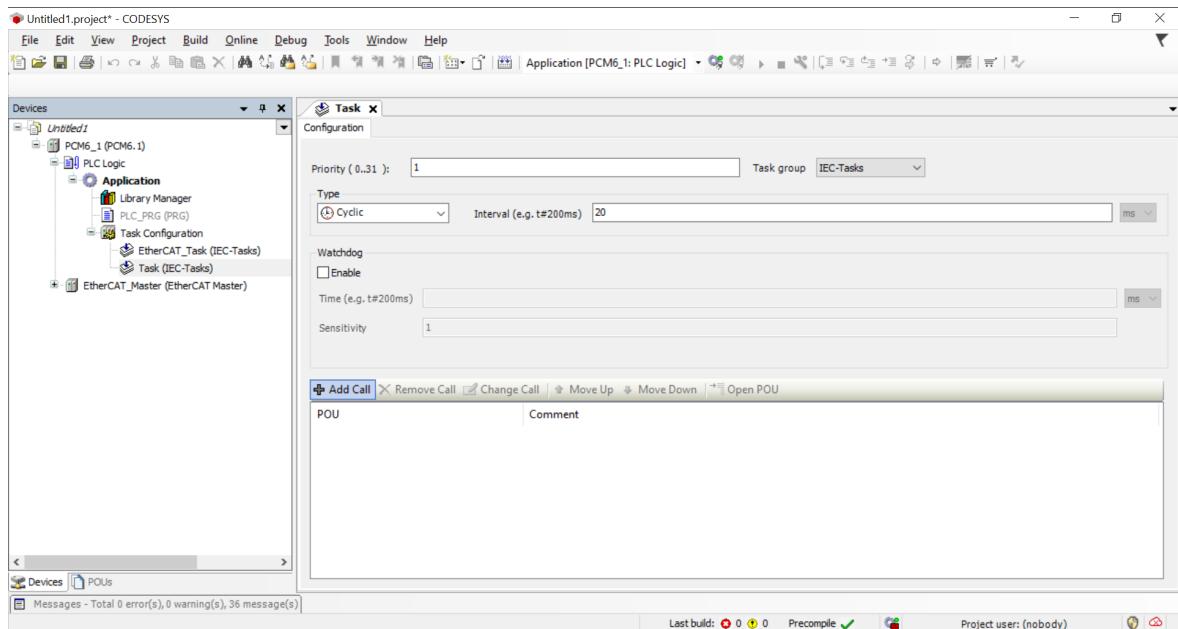
1. Select Task configuration > Add Object > Task....



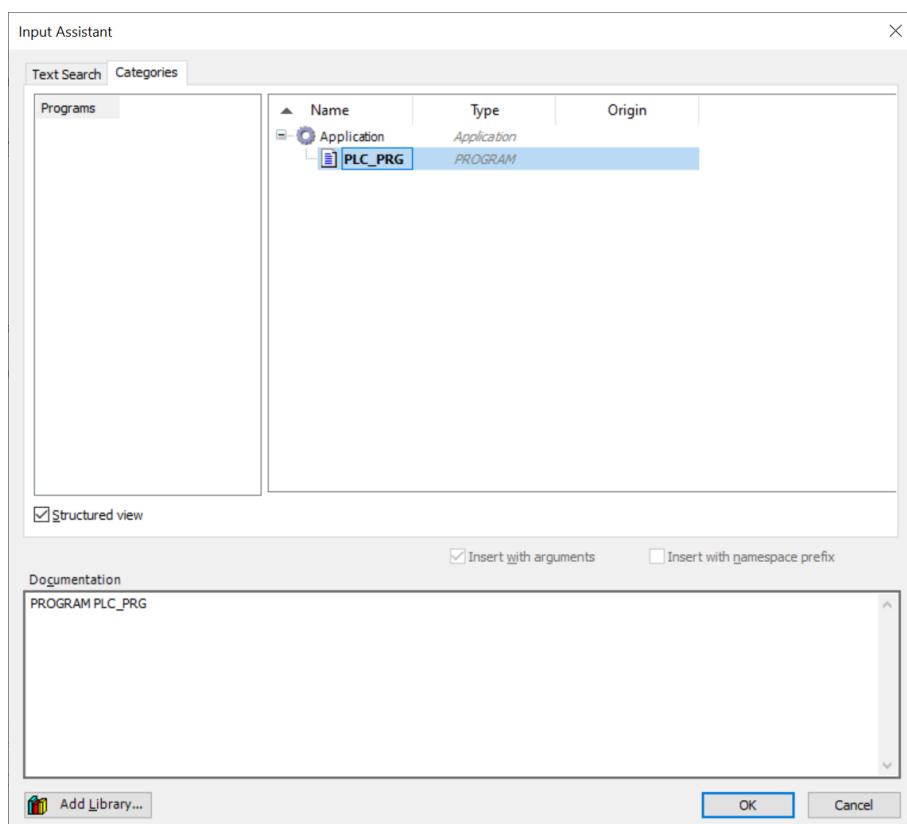
2. In the Add Task window, write a Task name and select Add.



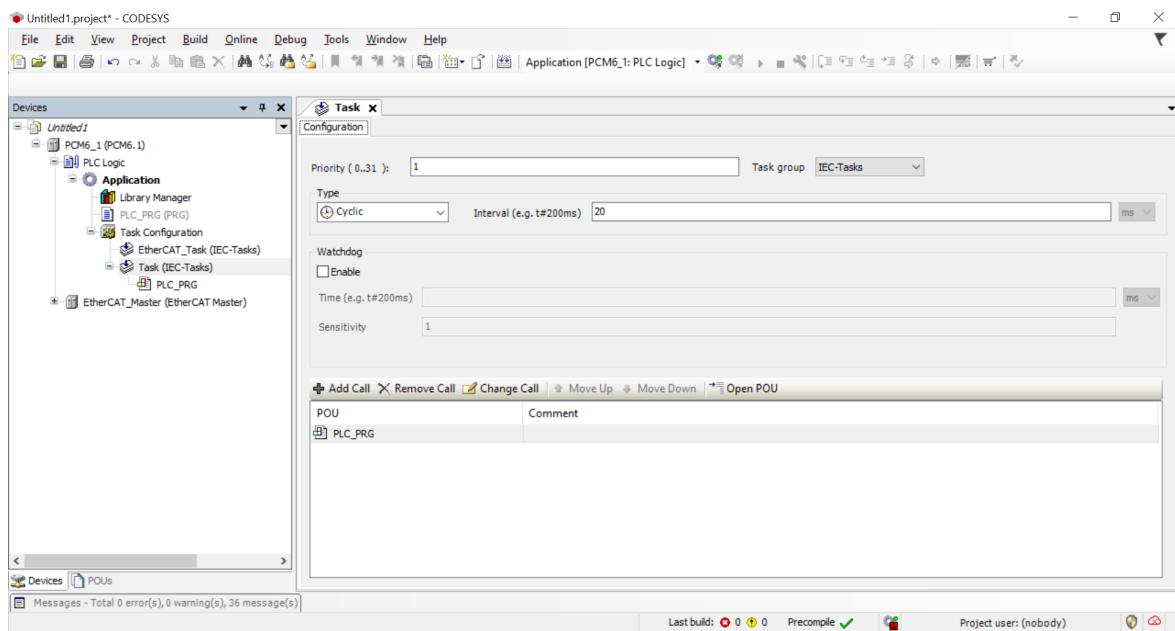
3. Select the Add Call tab.



4. In the Input Assistant window, select the program **PLC_PRG**.



5. The program PLC_PRG is now added to the project.

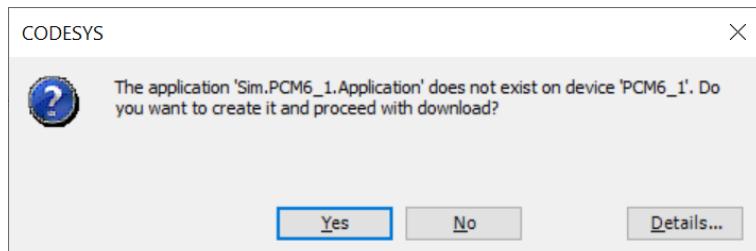


6. Login to the PLC.

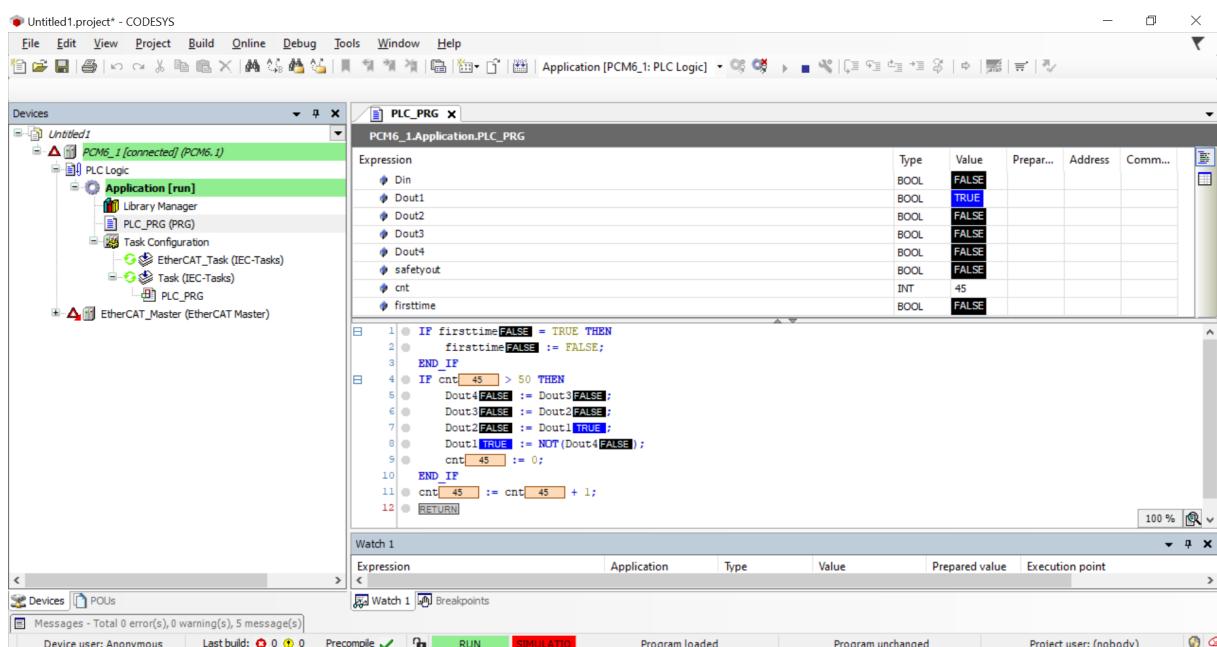
4.11.2 Simulation mode

It is possible to use Simulation mode, if a PLC controller is not connected.

1. Select Simulation mode with **Online > Simulation**.
2. Login to the AMC 300 with **Online > Login**.
3. In the pop-up window, select **Yes** to create the program.

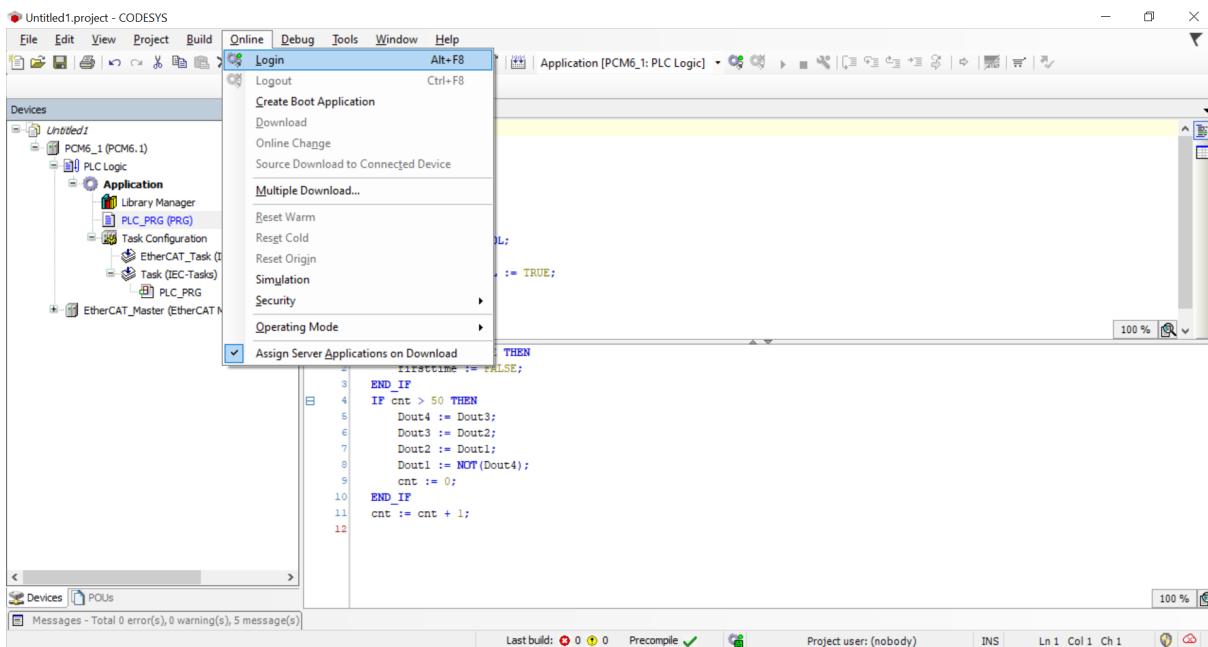


4. Select **Debug > Start** to run the program.



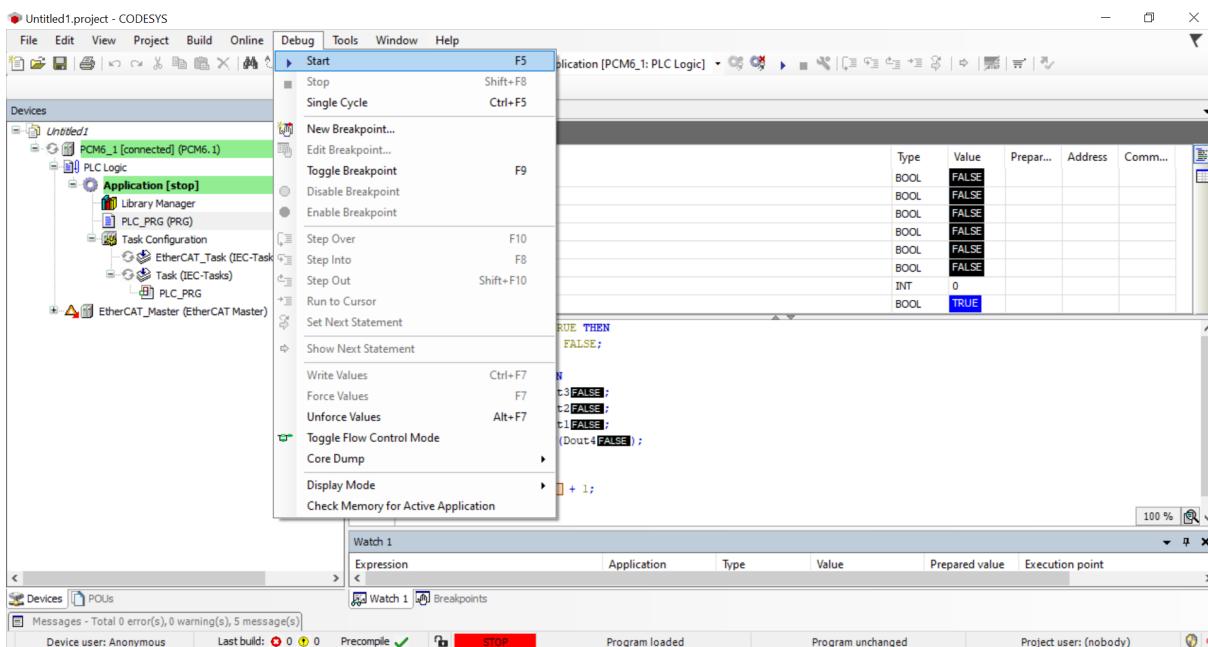
4.11.3 Login to the PLC

Select **Online > Login**.

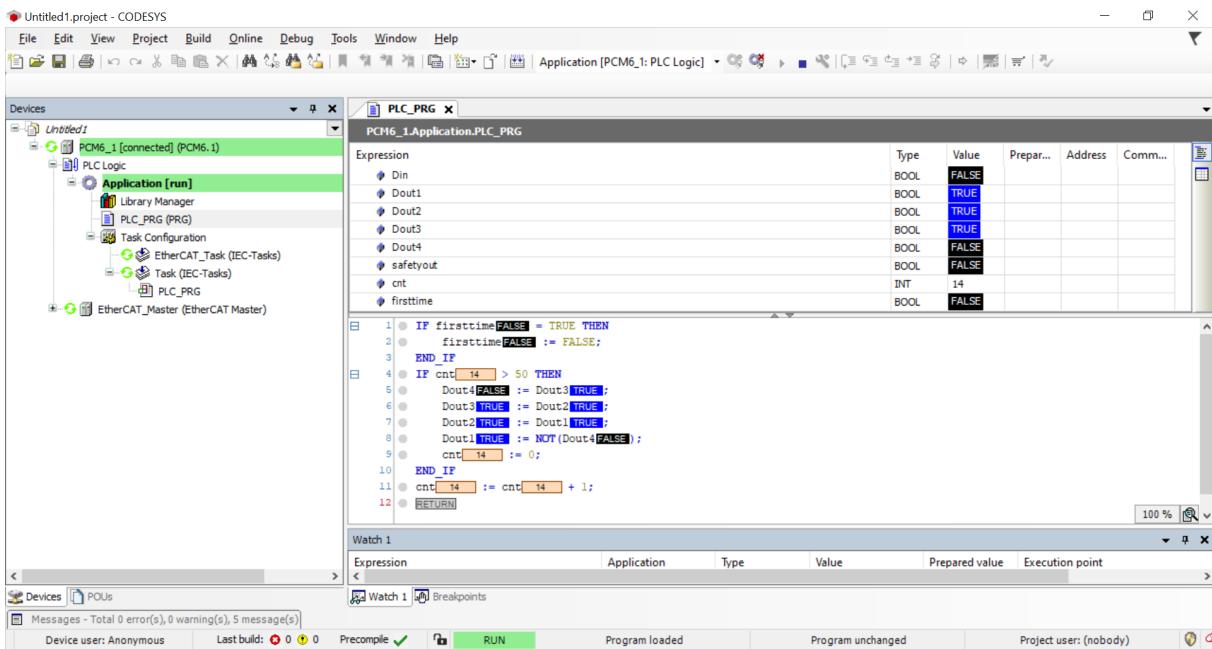


4.11.4 Start the program

To start the program, select **Debug > Start**.

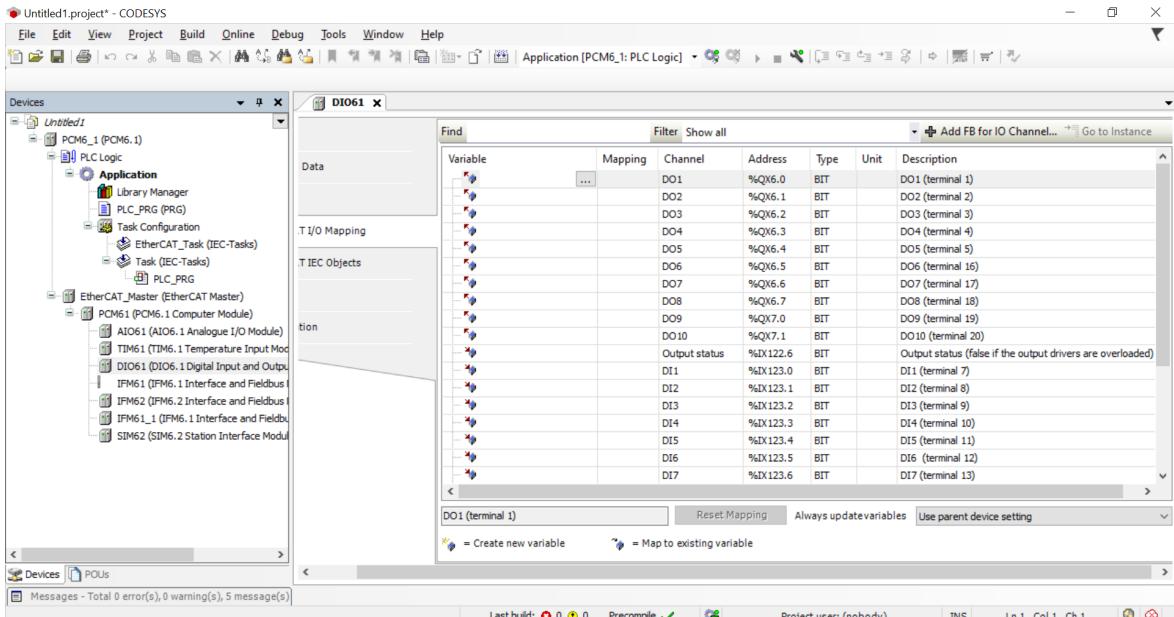


The project is now running.

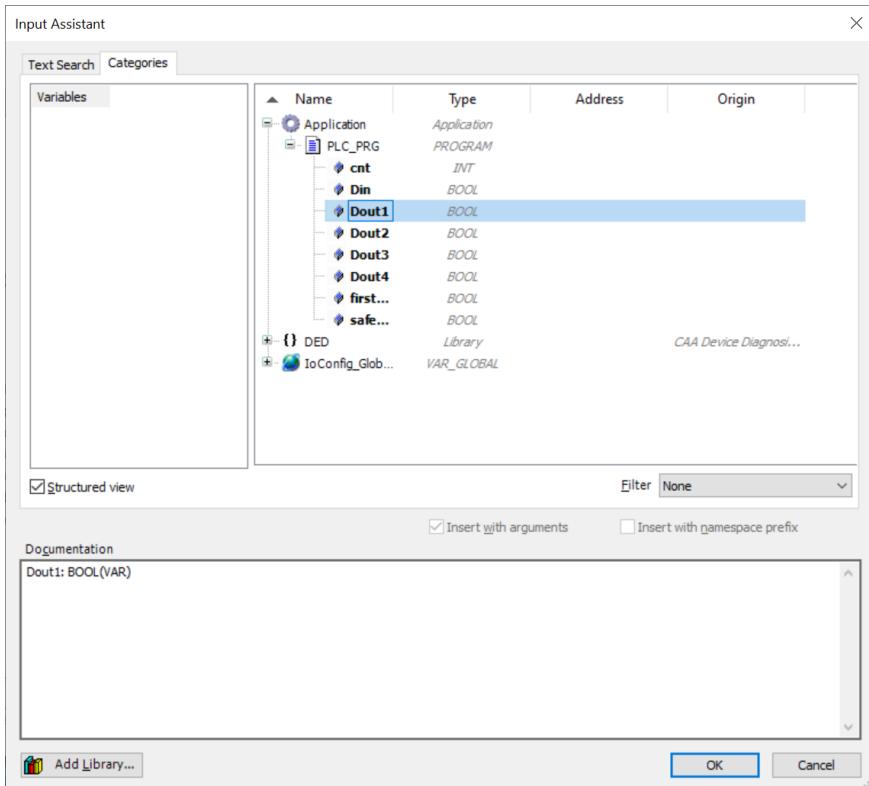


4.12 Link I/O variables to physical I/O

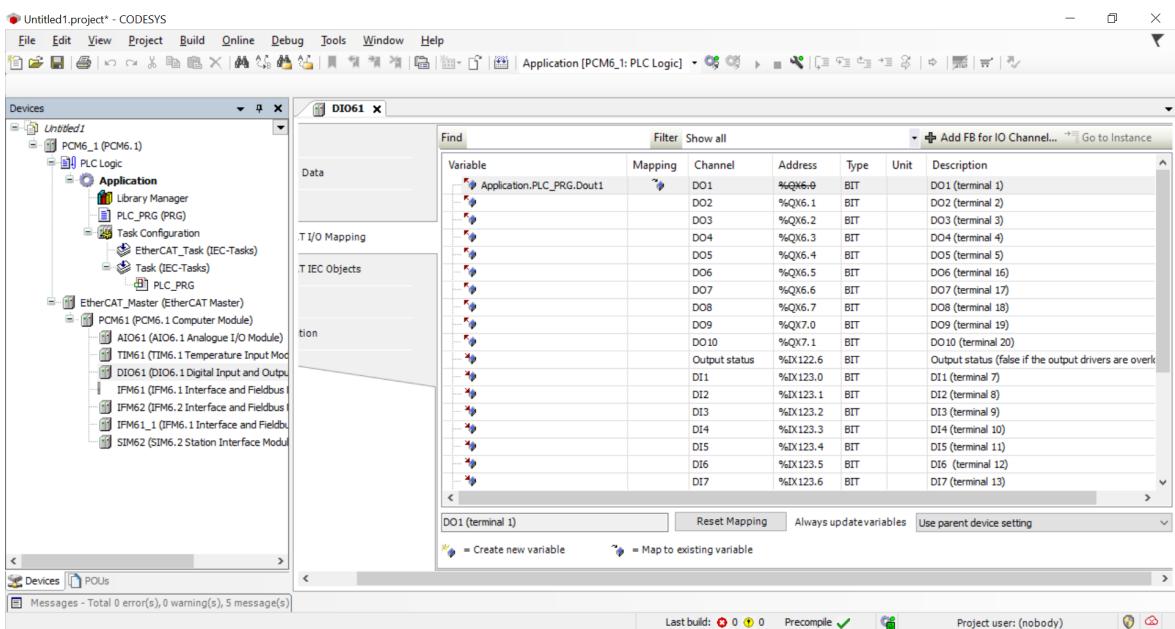
1. Select **Online > Logout** to go to offline mode.
2. Select a physical I/O.



3. Select ... of F2 to edit.
4. In the Input Assistant window, select a variable.



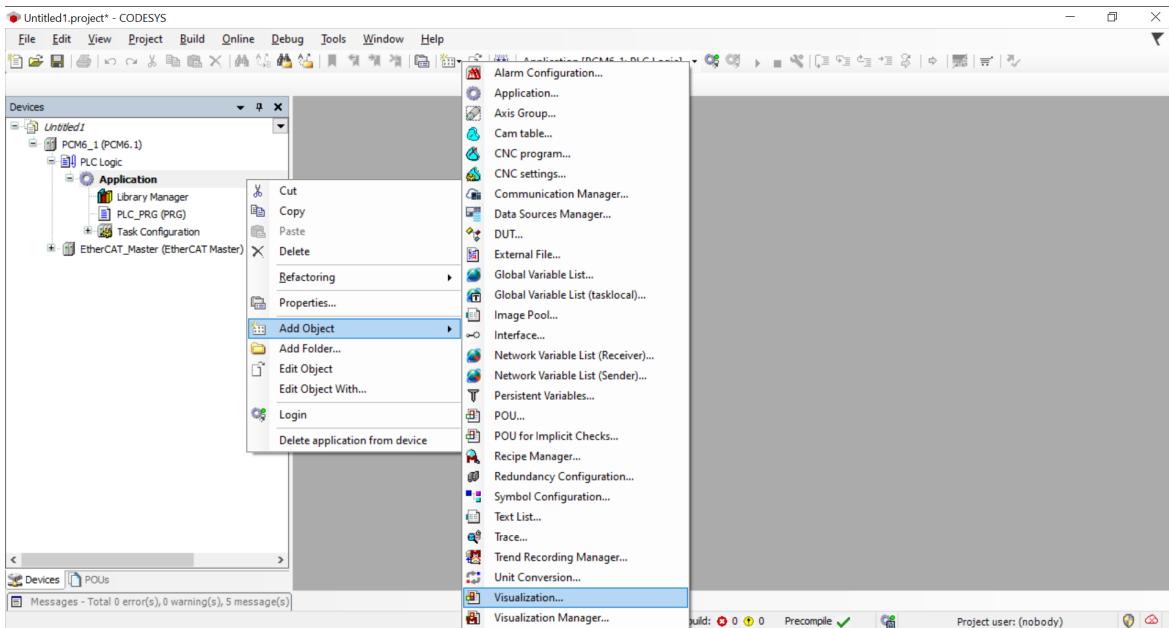
5. Select OK to link the variable to the physical I/O.



6. Repeat steps 1 to 5 for all output variables.

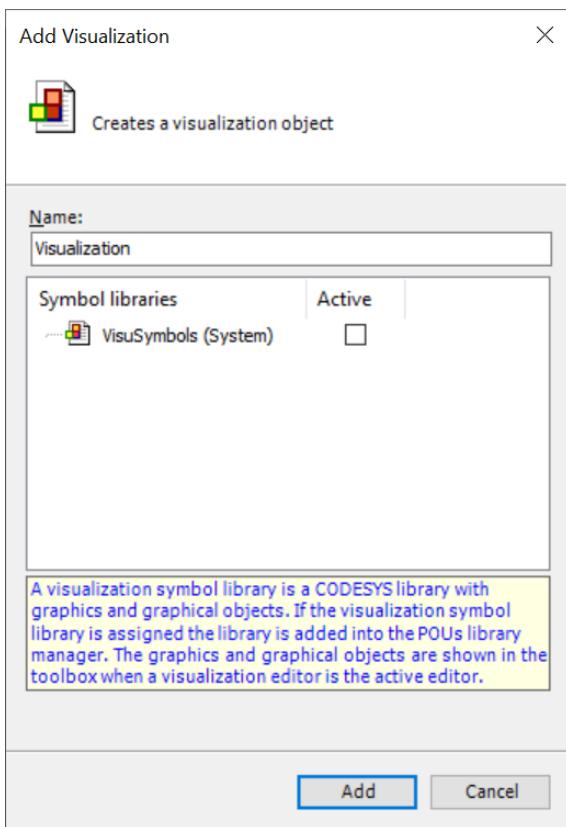
4.13 Add visualization

1. Select **Application > Add Object > Visualization.**



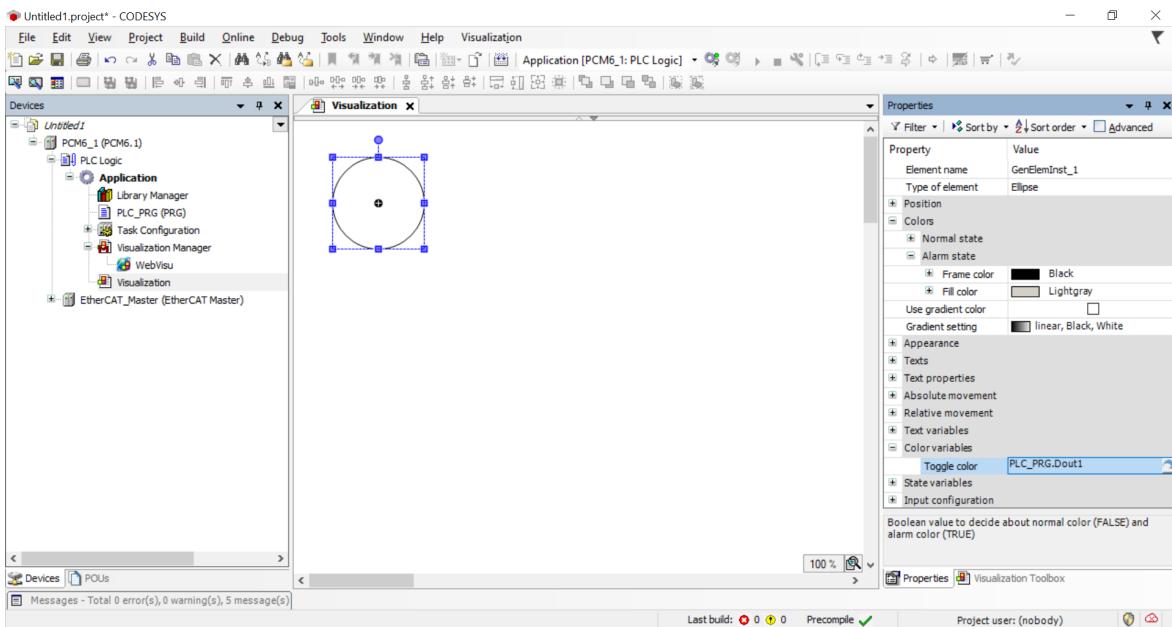
2. In the Add Visualization window, activate the **VisuSymbols (System)** library.

3. Select **Add**.

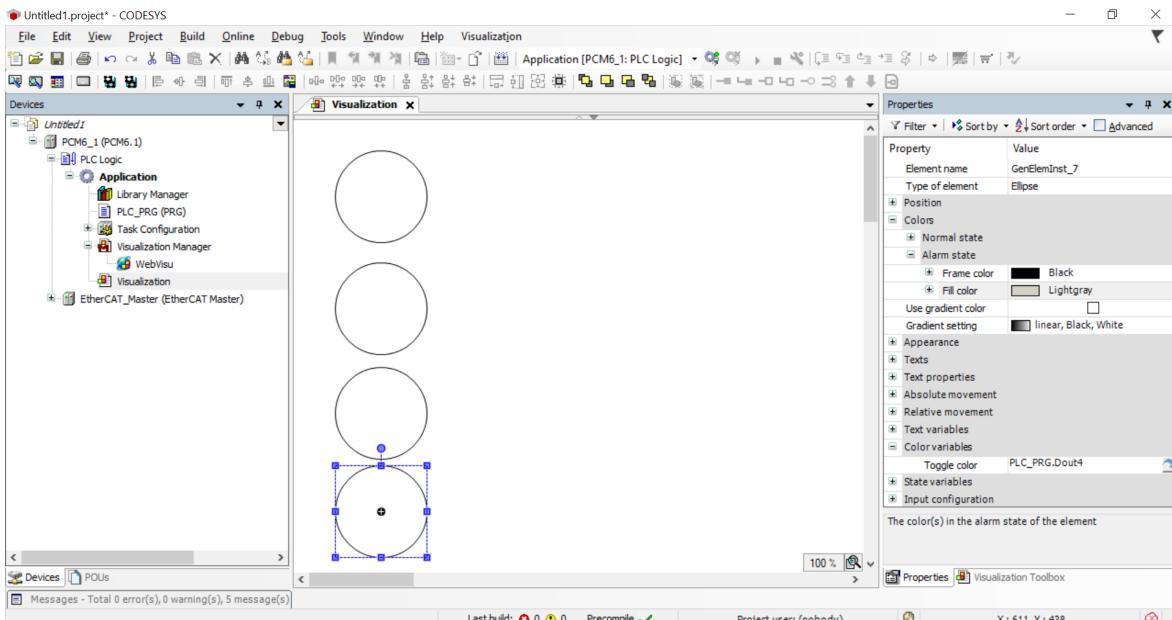


4.13.1 Drawing visualization (example)

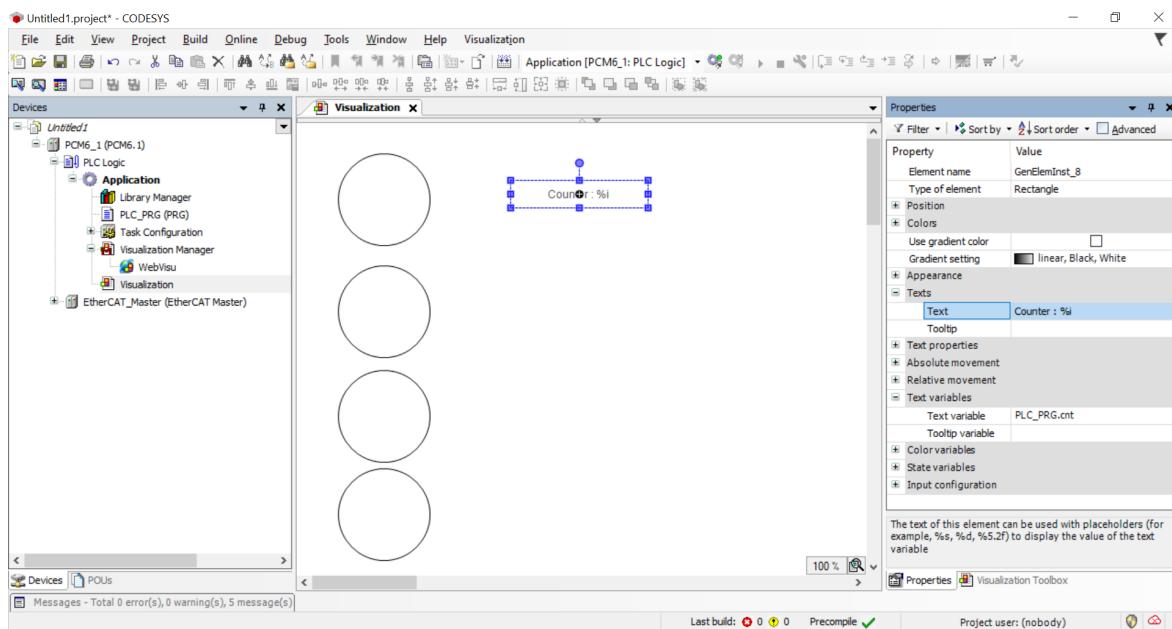
1. Draw an ellipse in the Visualization field.
2. Select **Properties > Color variation > Toggle Color** to link the ellipse to a variable.



3. Set **Properties > Colors > Alarmstate > Frame color** to Black.
4. Set **Properties > Colors > Alarmstate > Fill color** to Grey.
5. Repeat steps 1 to 4 (or copy-paste the ellipse) 3 times.

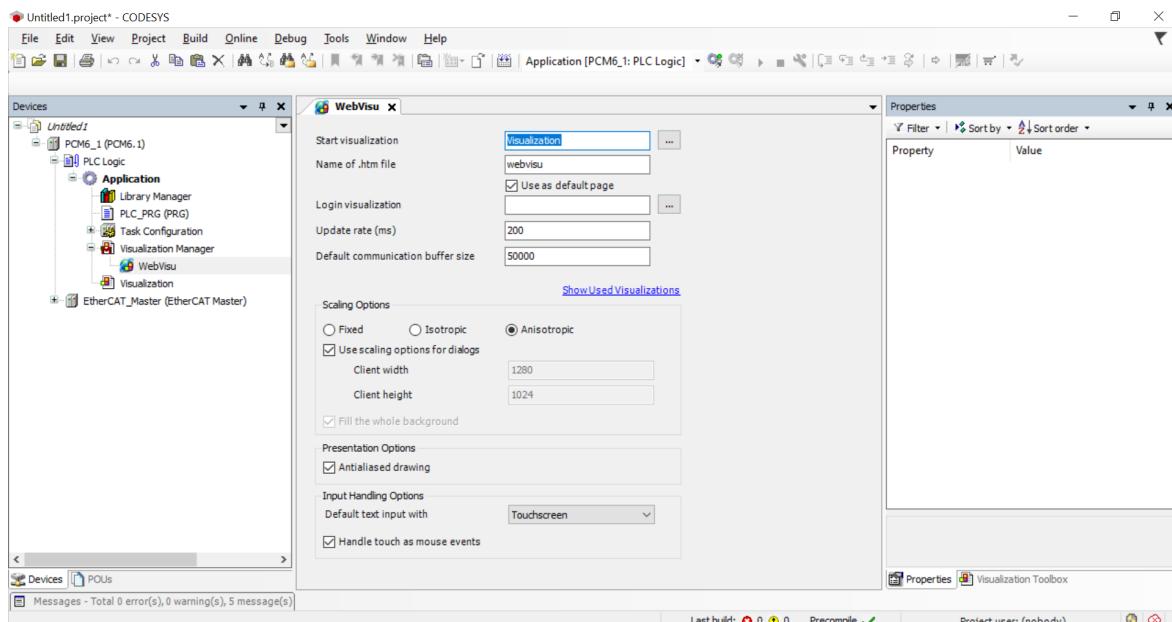


6. Use **Toggle Color** to change the new variables to other outputs.
7. Add a counter field (rectangle).

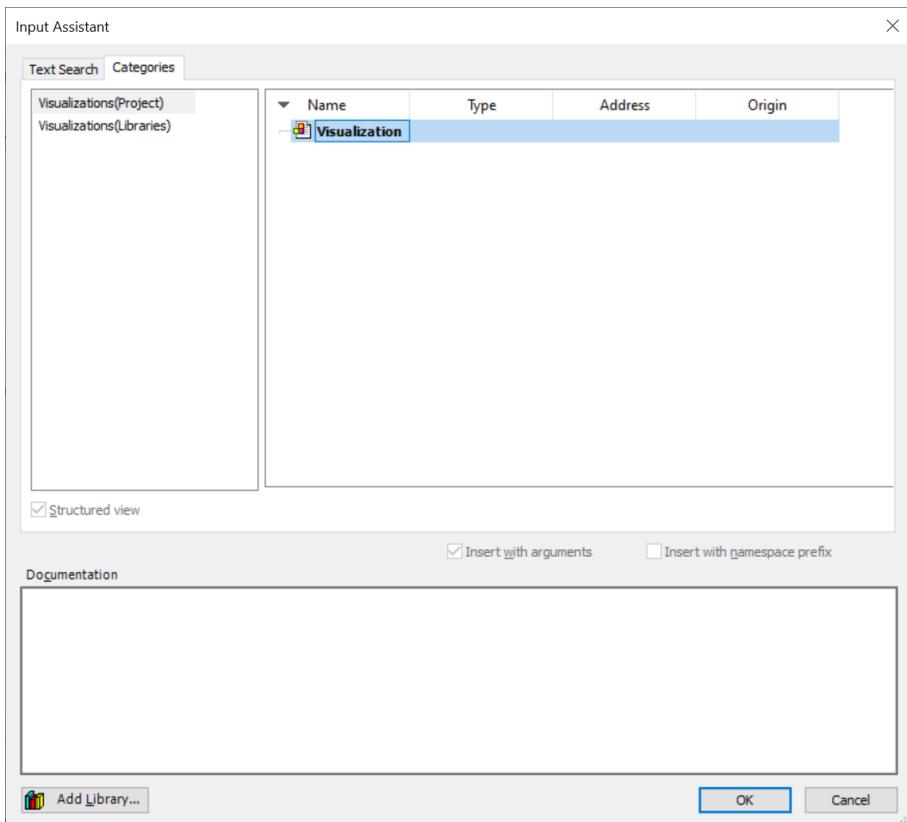


4.13.2 Set main visualization

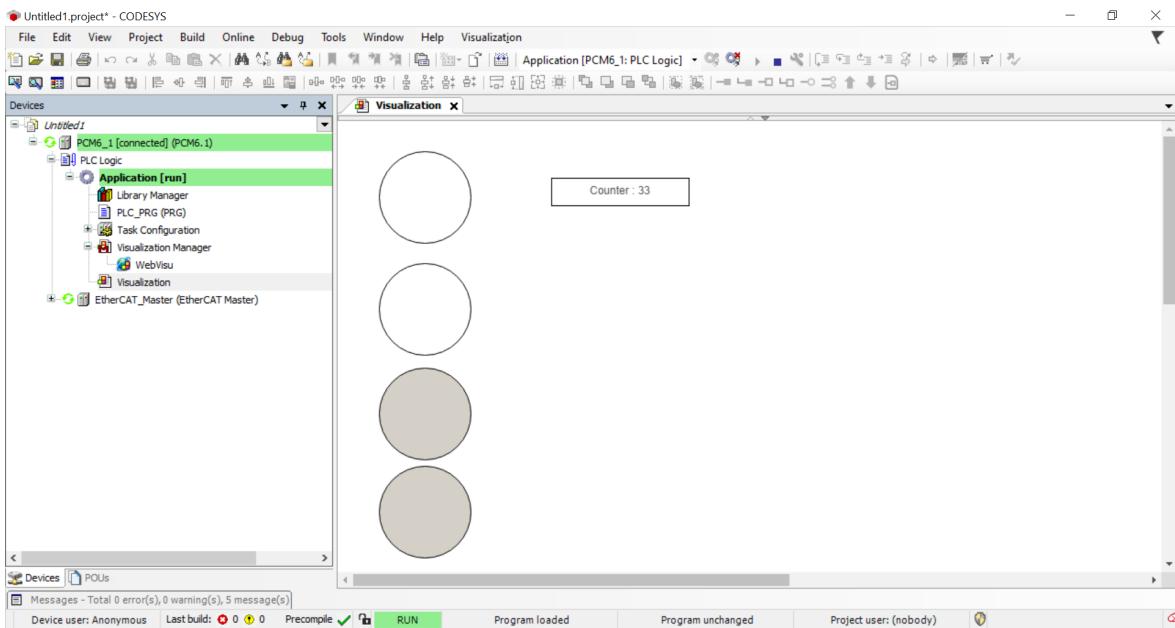
1. Select the **WebVisualization** tab.



2. In the Input Assistant window, select **Visualization**.



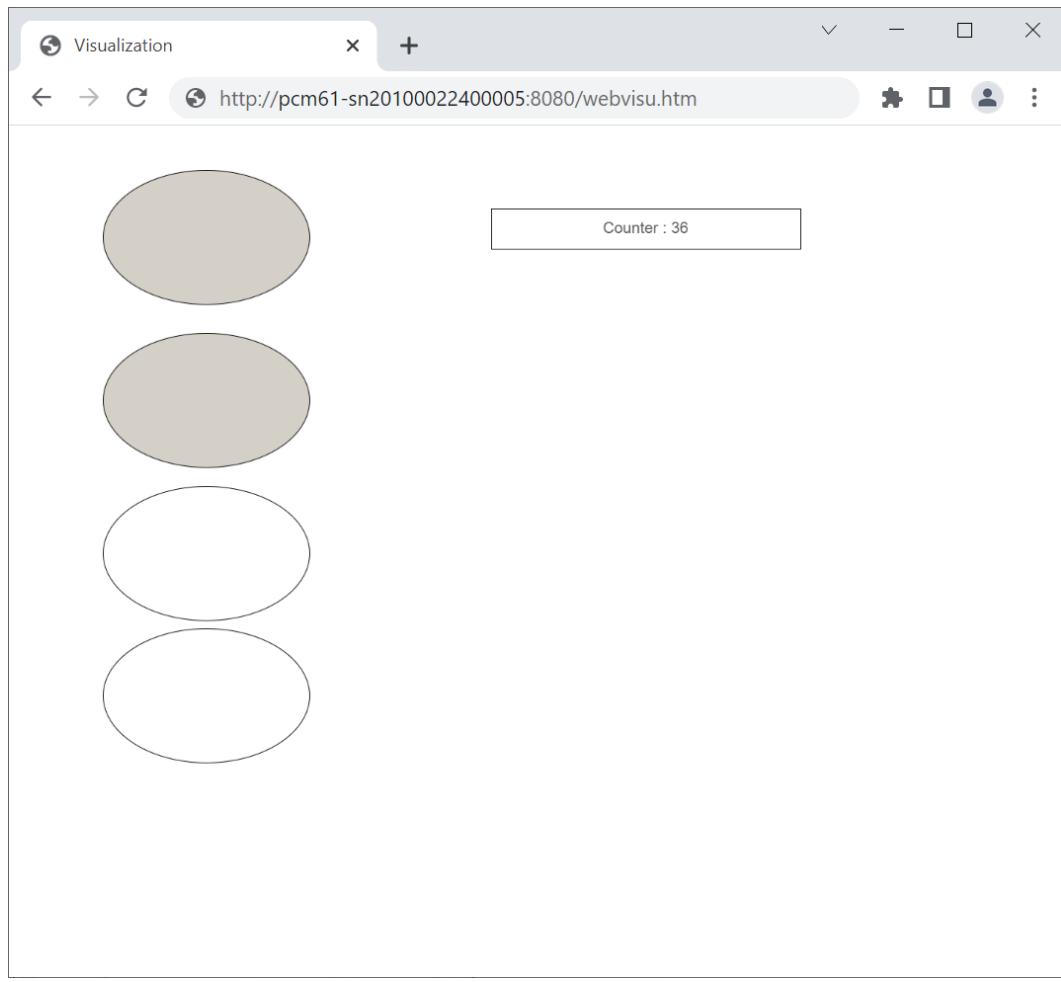
3. Select **OK**.
4. Login and run the program.
5. Select **Visualization** to view the first page.



4.13.3 View webvisualization or remote visualization

To see the webvisualization go to either

- [http://\[hostname or ip\]:8080/webvisu.htm](http://[hostname or ip]:8080/webvisu.htm) (for example, <http://amc600.local:8080/webvisu.htm>)
- via secure http to [https://\[hostname or ip\]:8443/webvisu.htm](https://[hostname or ip]:8443/webvisu.htm) (for example, <http://amc600.local:8443/>)

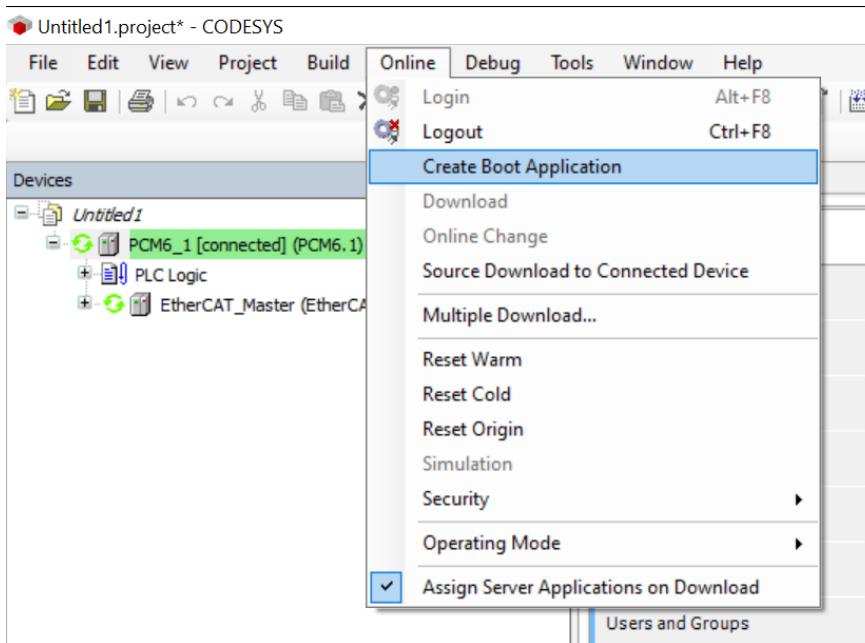


NOTE The port for http may be 8000 in some software versions.

4.14 Create a boot project

To make the PLC start with the application at power up, you can create a boot project in CODESYS.

1. Login to the PLC via **Online > Login**.
2. Select **Online > Create boot application**.



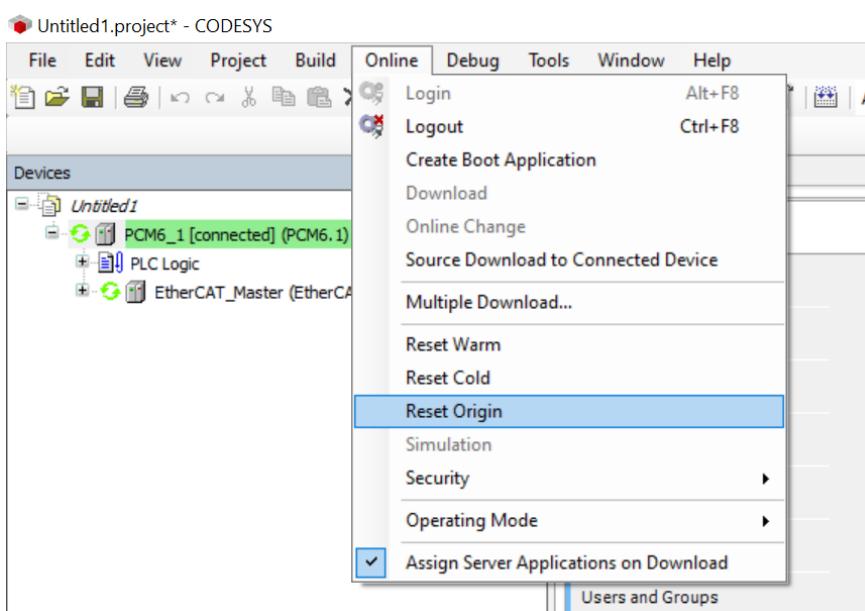
3. The boot project files are created under:

- /app/codesysapp/PlcLogic/Application
- /app/codesysapp/PlcLogic/visu

4. Reboot the PLC.

Remove a boot project

1. Login to the PLC via **Online > Login**.
2. Select **Online > Reset origin**.



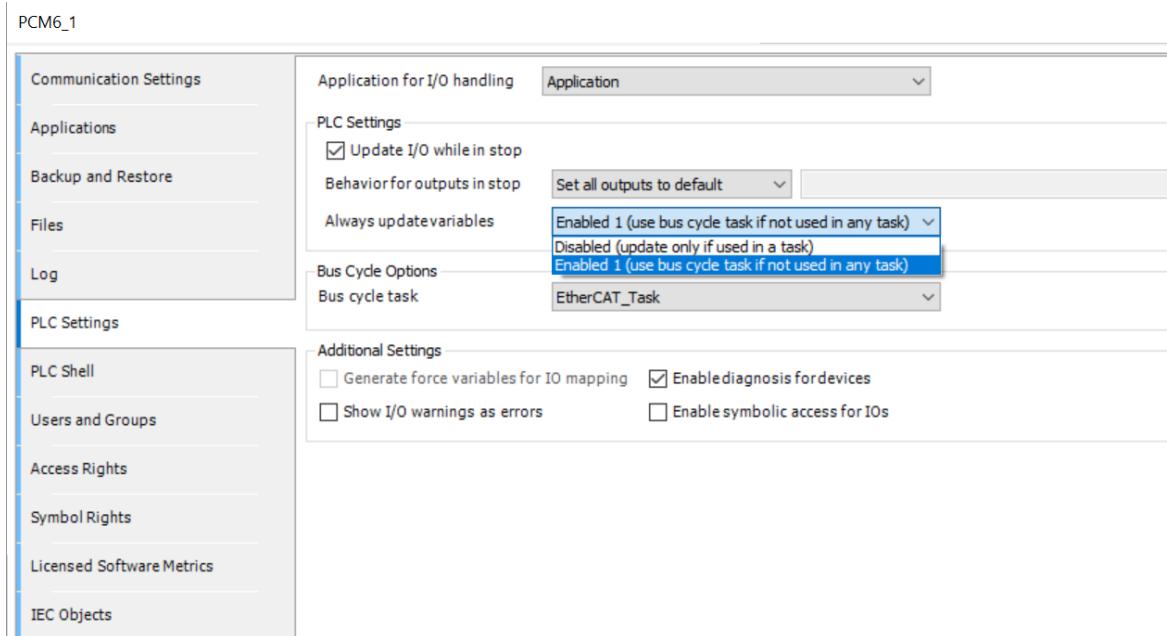
3. Or you can remove boot project and clean all the application files in:

- /app/codesysapp/PlcLogic/Application and
- /app/codesysapp/PlcLogic/visu folders.

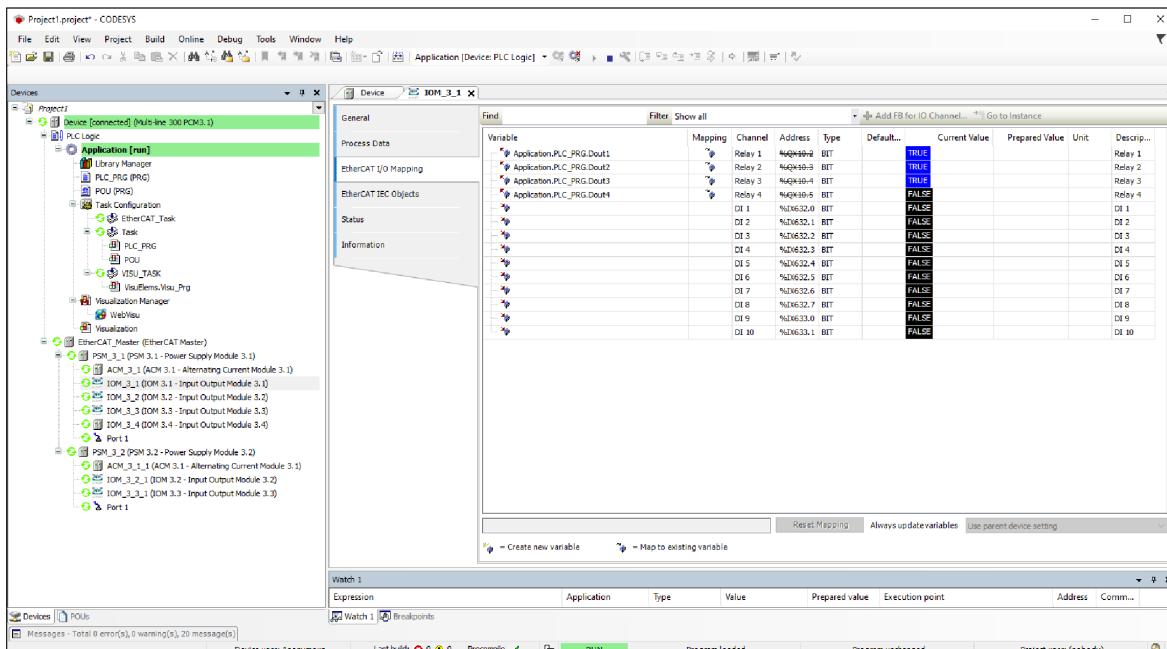
4.15 Manually force digital outputs for system testing

To manually force the digital outputs, for example for system testing, you must create a new empty project (see section **Create a new project**).

1. Scan for devices.
2. Add devices.
3. Select **PCM6_1 > PLC Settings**.
4. Tick the box **Update IO while in stop**.
5. In the **Always update variables** drop-down list, select **Enabled 1 (use bus cycle task if not used in any task)**.



6. In the **Bus cycle task** drop-down list, select **EtherCAT_Task**.
7. Select **PCM6_1 > Application [run]**.
8. Under a module tab, select **EtherCAT I/O Mapping** to see the values of all inputs.
9. Double-click **Prepared value** for the value you want to change.



10. Select **F7** to force the new value.
11. Repeat steps 6 to 8 for other modules.

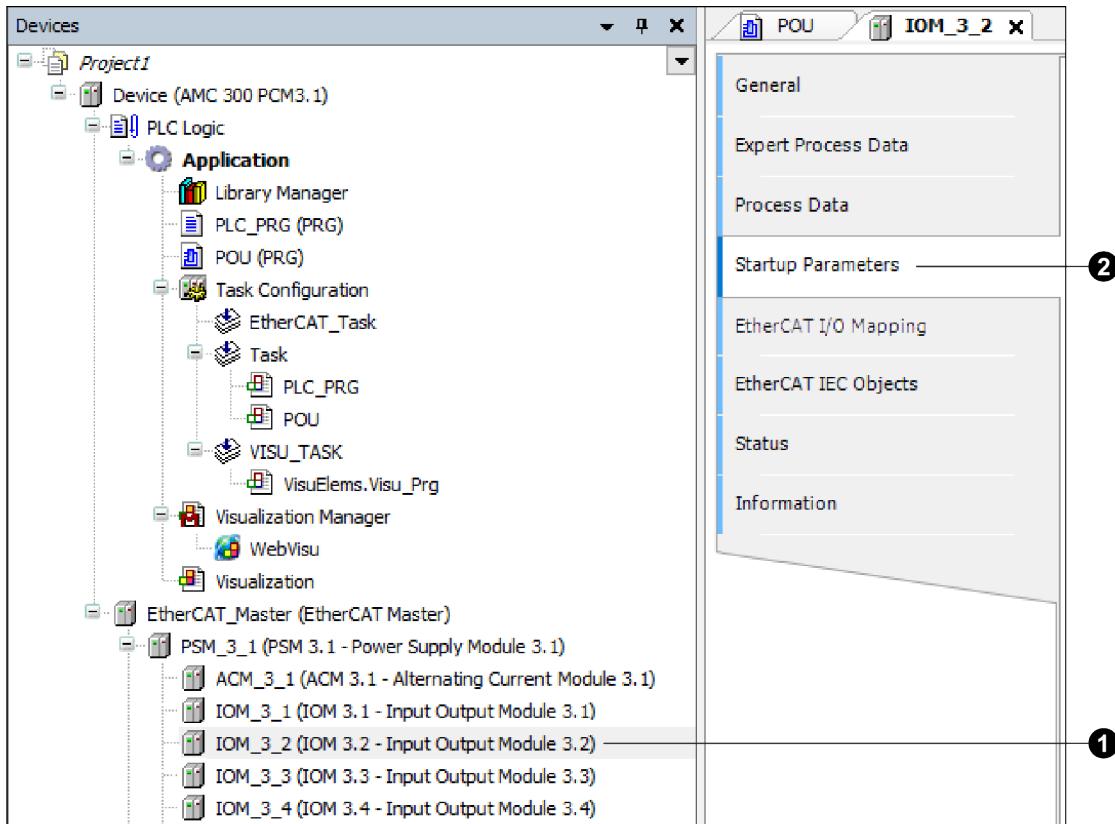
5. AMC 300 I/O configuration

This chapter guides you through the configuration of the AMC 300 I/O modules.

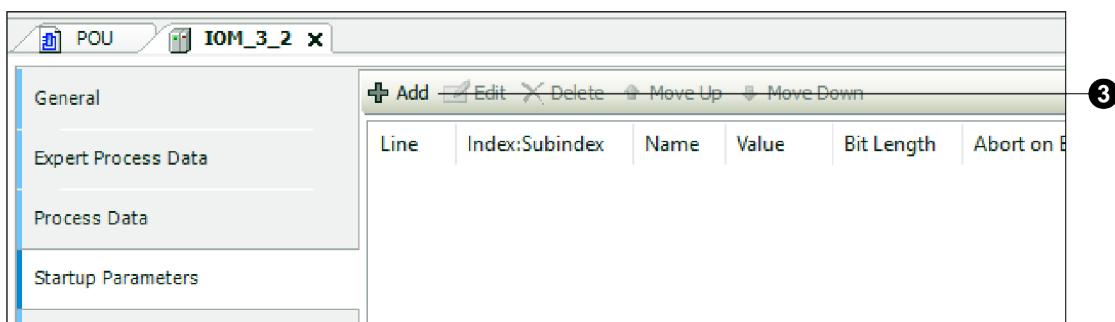
5.1 Configure AMC 300 Multifunctional Inputs/Outputs

5.1.1 Set the startup parameters (EtherCAT SDOs)

1. Select the relevant I/O module (example, IOM3.2).
2. Select *Startup parameters*.



3. Select *Add*.



4. Select the setup parameters for an analogue output (example, MultiOutput_4).

Select Item from Object Directory

Index:Subindex	Name	Flags	Type	Default
+ 16#7202:16#00	MultiOutput_2			
+ 16#7203:16#00	MultiOutput_3			
+ 16#7204:16#00	MultiOutput_4			
+ 16#8201:16#00	MultiOutput_1_Configuration			
+ 16#8202:16#00	MultiOutput_2_Configuration			
+ 16#8203:16#00	MultiOutput_3_Configuration			
+ 16#8204:16#00	MultiOutput_4_Configuration			
:16#01	Output Enable	RW	INT	0
:16#02	Mode	RW	INT	0
:16#03	Frequency	RW	REAL	0
:16#04	Low	RW	REAL	0
:16#05	High	RW	REAL	0
:16#06	PWMVoltageLevel	RW	REAL	6
+ 16#82F1:16#00	MultiOutput_1_Calibration			
+ 16#82F2:16#00	MultiOutput_2_Calibration			
+ 16#82F3:16#00	MultiOutput_3_Calibration			

Name:

Index: 16# Bit length: OK

SubIndex: 16# Value: Cancel

Byte array

- a. Output Enable
- b. Mode
- c. Low
- d. High

5. In the Value field, set the values for the MultiOutput Startup Parameters.

Example: Multi-functional output configured as a 4 to 20 mA analogue current output.

IOM_3_2 x

General																																																																																
Expert Process Data																																																																																
Process Data																																																																																
Startup Parameters																																																																																
EtherCAT I/O Mapping																																																																																
EtherCAT IEC Objects																																																																																
Status																																																																																
Information																																																																																
<table border="1"> <thead> <tr> <th>Line</th> <th>Index:Subindex</th> <th>Name</th> <th>Value</th> <th>Bit Length</th> <th>Abort on Error</th> <th>Jump to Line on Error</th> <th>Next Line</th> <th>Comment</th> </tr> </thead> <tbody> <tr><td>1</td><td>16#8204:16#01</td><td>Output Enable</td><td>1</td><td>16</td><td><input type="checkbox"/></td><td><input type="checkbox"/></td><td>0</td><td></td></tr> <tr><td>2</td><td>16#8204:16#02</td><td>Mode</td><td>2</td><td>16</td><td><input type="checkbox"/></td><td><input type="checkbox"/></td><td>0</td><td></td></tr> <tr><td>3</td><td>16#8204:16#04</td><td>Low</td><td>4.0</td><td>32</td><td><input type="checkbox"/></td><td><input type="checkbox"/></td><td>0</td><td></td></tr> <tr><td>4</td><td>16#8204:16#05</td><td>High</td><td>20.0</td><td>32</td><td><input type="checkbox"/></td><td><input type="checkbox"/></td><td>0</td><td></td></tr> <tr><td>5</td><td>16#8301:16#01</td><td>Mode</td><td>2</td><td>16</td><td><input type="checkbox"/></td><td><input type="checkbox"/></td><td>0</td><td></td></tr> <tr><td>6</td><td>16#8301:16#02</td><td>Low</td><td>4.0</td><td>32</td><td><input type="checkbox"/></td><td><input type="checkbox"/></td><td>0</td><td></td></tr> <tr><td>7</td><td>16#8301:16#03</td><td>High</td><td>20.0</td><td>32</td><td><input type="checkbox"/></td><td><input type="checkbox"/></td><td>0</td><td></td></tr> </tbody> </table>									Line	Index:Subindex	Name	Value	Bit Length	Abort on Error	Jump to Line on Error	Next Line	Comment	1	16#8204:16#01	Output Enable	1	16	<input type="checkbox"/>	<input type="checkbox"/>	0		2	16#8204:16#02	Mode	2	16	<input type="checkbox"/>	<input type="checkbox"/>	0		3	16#8204:16#04	Low	4.0	32	<input type="checkbox"/>	<input type="checkbox"/>	0		4	16#8204:16#05	High	20.0	32	<input type="checkbox"/>	<input type="checkbox"/>	0		5	16#8301:16#01	Mode	2	16	<input type="checkbox"/>	<input type="checkbox"/>	0		6	16#8301:16#02	Low	4.0	32	<input type="checkbox"/>	<input type="checkbox"/>	0		7	16#8301:16#03	High	20.0	32	<input type="checkbox"/>	<input type="checkbox"/>	0	
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3	16#8204:16#04	Low	4.0	32	<input type="checkbox"/>	<input type="checkbox"/>	0																																																																									
4	16#8204:16#05	High	20.0	32	<input type="checkbox"/>	<input type="checkbox"/>	0																																																																									
5	16#8301:16#01	Mode	2	16	<input type="checkbox"/>	<input type="checkbox"/>	0																																																																									
6	16#8301:16#02	Low	4.0	32	<input type="checkbox"/>	<input type="checkbox"/>	0																																																																									
7	16#8301:16#03	High	20.0	32	<input type="checkbox"/>	<input type="checkbox"/>	0																																																																									

- a
- b
- c
- d

Parameter	Value	Note
a. Output Enable	0 = Output not active 1 = Output active	
b. Mode	0 = Unknown 15 = Voltage out mode 16 = Current out mode	
c. Low	4.0 or -10.0	Lower measured limit. Examples: <ul style="list-style-type: none"> • 4 to 20 mA • ± 10 V
d. High	20.0 or 10.0	Upper measured limit.

6. Configure the start parameters for a multi-functional input (example, MultiInput_1).

Select Item from Object Directory

Index:Subindex	Name	Flags	Type	Default
+ 16#8204:16#00	MultiOutput_4_Configuration			
+ 16#82F1:16#00	MultiOutput_1_Calibration			
+ 16#82F2:16#00	MultiOutput_2_Calibration			
+ 16#82F3:16#00	MultiOutput_3_Calibration			
+ 16#82F4:16#00	MultiOutput_4_Calibration			
+ 16#8300:16#00	Multi Input General Configuration			
+ 16#8301:16#00	MultiInput_1_Configuration			
:16#01	Mode	RW	UINT	0
:16#02	Low	RW	REAL	0
:16#03	High	RW	REAL	0
:16#04	Setting Time	RW	UINT	0
:16#05	Sample Rate	RW	UINT	0
+ 16#8302:16#00	MultiInput_2_Configuration			
+ 16#8303:16#00	MultiInput_3_Configuration			
+ 16#8304:16#00	MultiInput_4_Configuration			
+ 16#83F1:16#00	MULTIN CAL 1 Calibration Values			

Name:

Index: 16# **Bit length:** 8

SubIndex: 16# **Value:**

Byte array

e. Mode
f. Low
g. High

7. In the Value field, set the values for the Multiinput Startup Parameters.

Example: Multi-functional output configured as a 4 to 20 mA analogue current output.

IOM_3_2 x

General									
Expert Process Data									
Process Data									
Startup Parameters									
EtherCAT I/O Mapping									
EtherCAT IEC Objects									
Status									
Information									
<input type="button" value="Add"/> <input type="button" value="Edit"/> <input type="button" value="Delete"/> <input type="button" value="Move Up"/> <input type="button" value="Move Down"/>	Line	Index:Subindex	Name	Value	Bit Length	Abort on Error	Jump to Line on Error	Next Line	Comment
	1	16#8204:16#01	Output Enable	1	16	<input type="checkbox"/>	<input type="checkbox"/>	0	
	2	16#8204:16#02	Mode	2	16	<input type="checkbox"/>	<input type="checkbox"/>	0	
	3	16#8204:16#04	Low	4.0	32	<input type="checkbox"/>	<input type="checkbox"/>	0	
	4	16#8204:16#05	High	20.0	32	<input type="checkbox"/>	<input type="checkbox"/>	0	
	5	16#8301:16#01	Mode	2	16	<input type="checkbox"/>	<input type="checkbox"/>	0	
	6	16#8301:16#02	Low	4.0	32	<input type="checkbox"/>	<input type="checkbox"/>	0	
	7	16#8301:16#03	High	20.0	32	<input type="checkbox"/>	<input type="checkbox"/>	0	

e
f
g

Parameter	Value	Note
e. Mode	0 = Unknown 1 = Voltage mode 2 = Current mode 3 = Resistance mode 4 = Temperature mode 5 = Dry Contact mode	
f. Low	4.0 or -10.0	Lower measured limit. Examples: <ul style="list-style-type: none">• 4 to 20 mA• ± 10 V
g. High	20.0 or 10.0	Upper measured limit.

5.1.2 Configuration example for PWM

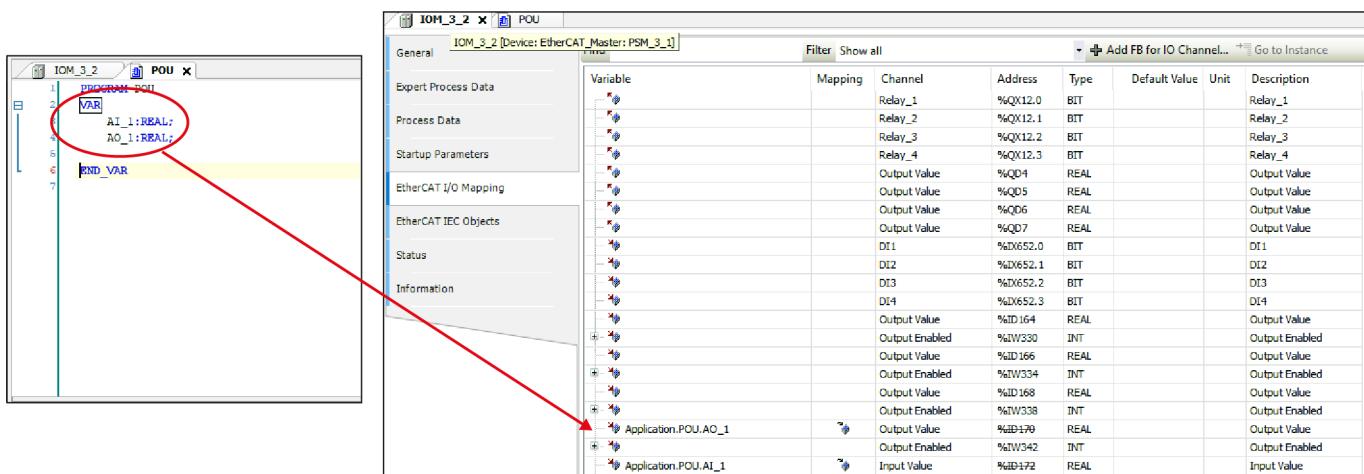
The PWM signals of the IOM3-2 can be configured like this:

A screenshot of a configuration software interface. At the top, there is a toolbar with icons for Add, Edit, Delete, Move Up, and Move Down. Below the toolbar is a table with the following columns: Line, Index:Subindex, Name, Value, Bit Length, Abort on Error, Jump to Line on Error, Next Line, and Comment. The table contains the following data:

Line	Index:Subindex	Name	Value	Bit Length	Abort on Error	Jump to Line on Error	Next Line	Comment
1	16#8201:16#01	Output Enable	1	16	<input type="checkbox"/>	<input type="checkbox"/>	0	
2	16#8201:16#02	Mode	26	16	<input type="checkbox"/>	<input type="checkbox"/>	0	
3	16#8201:16#03	Frequency	490.0	32	<input type="checkbox"/>	<input type="checkbox"/>	0	
4	16#8201:16#04	Low	0	32	<input type="checkbox"/>	<input type="checkbox"/>	0	
5	16#8201:16#05	High	100.0	32	<input type="checkbox"/>	<input type="checkbox"/>	0	
6	16#8201:16#06	PWMVoltageLevel	6	32	<input type="checkbox"/>	<input type="checkbox"/>	0	

5.1.3 Attach I/Os to variables

I/Os can be attached from the POU tab to variables and used in the application logic.



A simple test is to wire the terminals of the MultiOutput as feedback to the MultiInput.

After download of the application, the MultiOutput analogue value can be forced and seen on the MultiInput analogue input.

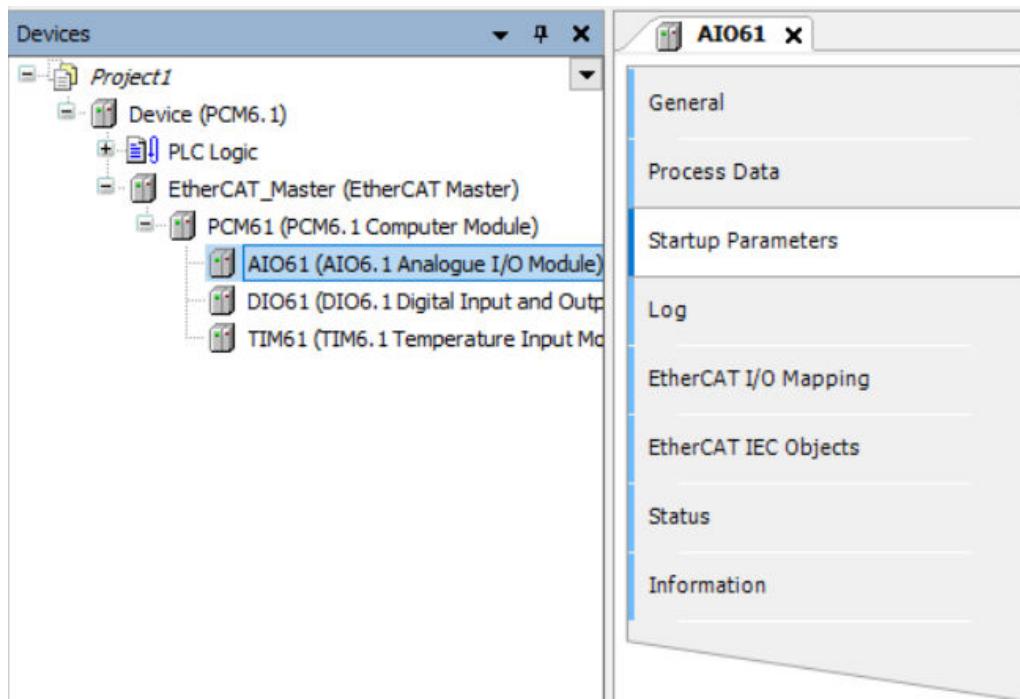
6. AMC 600 I/O configuration

This chapter guides you through the configuration of the AMC 600 modules, usually AIO6.1 and TIM6.1.

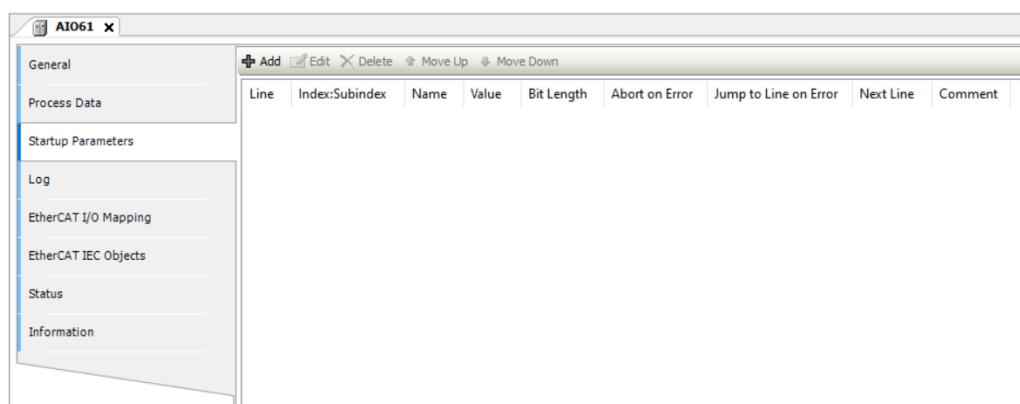
NOTE The DIO6.1 does not need configuration via startup parameters.

6.1 Set startup parameters (EtherCAT SDOs)

1. Select the relevant I/O module, for example, AIO6.1.
2. Select **Startup Parameters**.

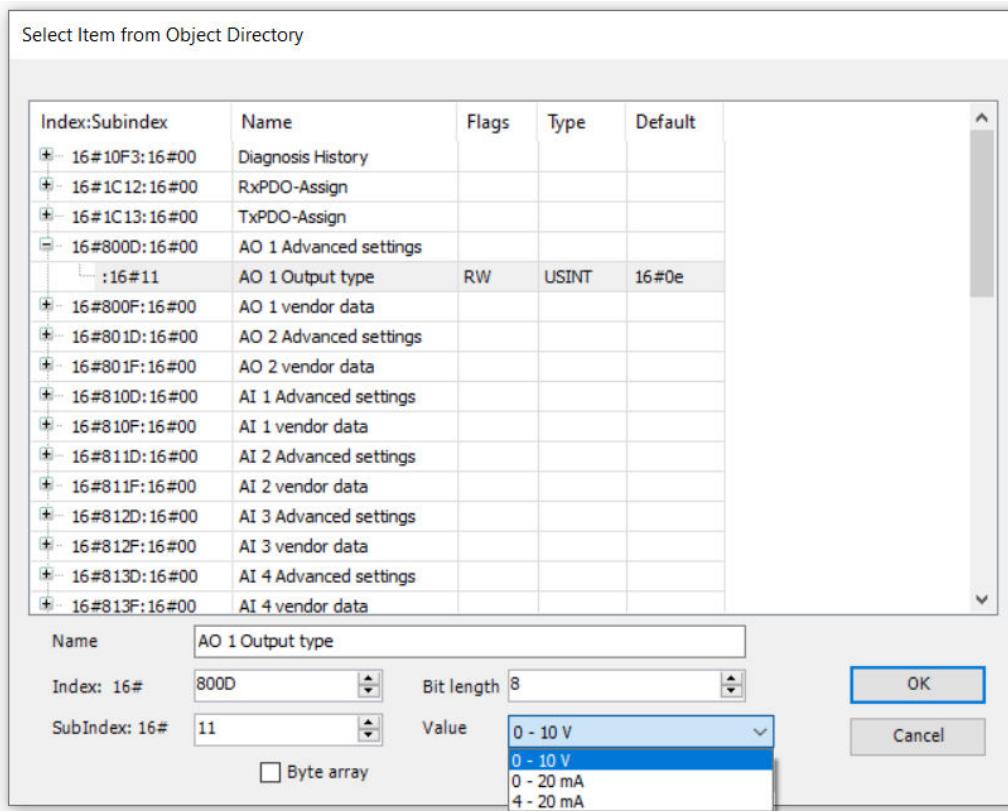


3. Select **Add**.



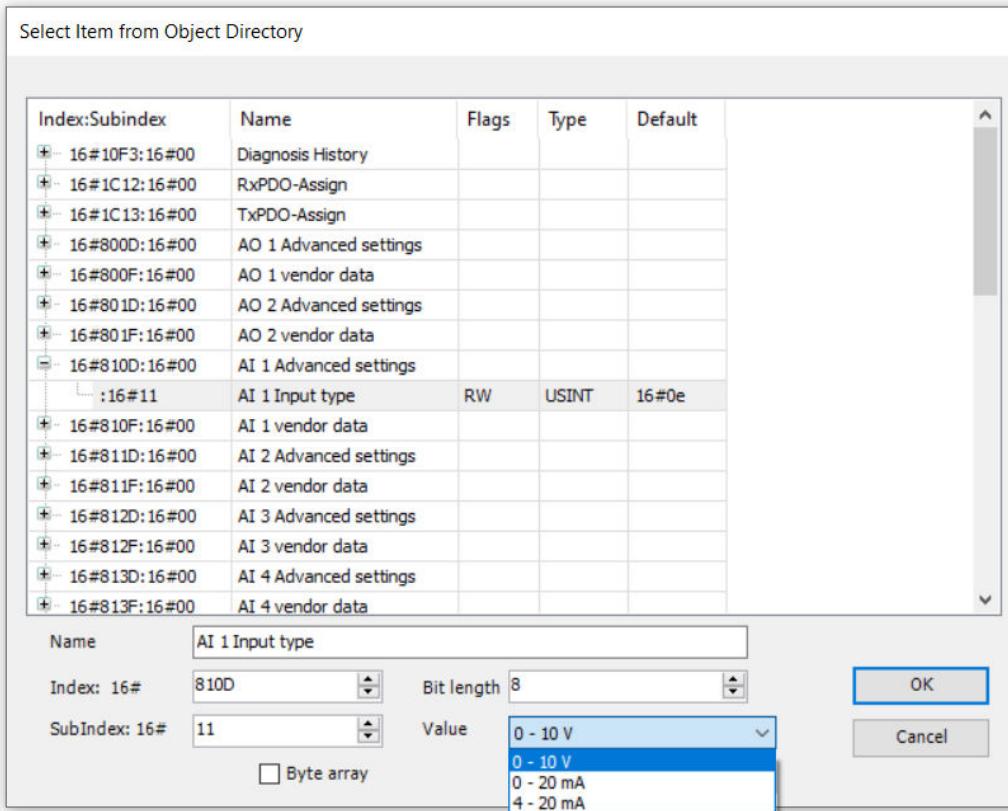
4. Select the setup parameter for an analogue output (for example, AO 1 Advanced settings > AO 1 Output type). Use the drop-down list to select the type supported.

Example: Analogue output configured as a 0 to 10 V analogue voltage output.



5. Same method is used to configure **Analogue input**. Select the setup parameters for an analogue input (for example, AI 1 Advanced settings > AI 1 Input type).

Example: Analogue input configured as a 0 to 10 V analogue voltage input.



6. Once added, the startup parameters are automatically transferred to the EtherCAT I/O modules.

The screenshot shows the AIO61 configuration interface. On the left is a sidebar with tabs: General, Process Data, Startup Parameters, Log, EtherCAT I/O Mapping, EtherCAT IEC Objects, Status, and Information. The main area displays a table titled 'AIO61' with columns: Line, Index:Subindex, Name, Value, Bit Length, Abort on Error, Jump to Line on Error, Next Line, and Comment. Two rows are present:

Line	Index:Subindex	Name	Value	Bit Length	Abort on Error	Jump to Line on Error	Next Line	Comment
1	16#810D:16#11	AI 1 Input type	0 - 10 V	8	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0	
2	16#800D:16#11	AO 1 Output type	0 - 10 V	8	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	0	

6.2 Attach I/Os to variables

You can attach I/Os from the POU tab to variables, and used in the application logic.

The screenshot shows the PLC_PRG editor. On the left, a program code window contains:

```

1 PROGRAM PLC_PRG
2
3 VAR
4   myAO : INT;
5   myAI : INT;
6 END_VAR

```

On the right, the AIO61 configuration window shows the 'General' tab with a table of variable mappings:

Variable	Mapping	Channel	Address	Type	Unit	Description
Application.PLC_PRG.myAO	AO 1 Value	%QW1	INT			AO 1 Value
	AO 2 Value	%QW2	INT			AO 2 Value
	AI 1 Under range	%DX2.0	BIT			AI 1 Under range
	AI 1 Over range	%DX2.1	BIT			AI 1 Over range
Application.PLC_PRG.myAI	AI 1 Error	%DX2.6	BIT			AI 1 Error
	AI 1 TxPDO State	%DX3.6	BIT			AI 1 TxPDO State
	AI 1 TxPDO Toggle	%DX3.7	BIT			AI 1 TxPDO Toggle
	AI 1 Value	%HW2	INT			AI 1 Value
	AI 2 Under range	%DX6.0	BIT			AI 2 Under range
	AI 2 Over range	%DX6.1	BIT			AI 2 Over range
	AI 2 Error	%DX6.6	BIT			AI 2 Error
	AI 2 TxPDO State	%DX7.6	BIT			AI 2 TxPDO State
	AI 2 TxPDO Toggle	%DX7.7	BIT			AI 2 TxPDO Toggle
	AI 2 Value	%IW4	INT			AI 2 Value

A simple test is to wire the terminals of the analogue output as feedback to the analogue input.

After download of the application, the analogue output value can be forced and seen on the analogue input.