

iE 150

Generator marine Core

Data sheet



Improve
Tomorrow



1. iE 150 Core marine

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1. iE 150 Core marine

1.1 About the controller

1.1.1 About

The iE 150 Core marine (Genset) controller provides flexible protection and control for one genset in non-synchronising applications. The controller contains all the functions needed to protect and control the genset, the genset breaker, and also a tie/mains breaker.

The iE 150 is a compact, all-in-one controller. Each iE 150 contains all necessary 3-phase measuring circuits.

The values and alarms are shown on the LCD display screen, which is sunlight-readable. Operators can easily control the genset and breakers from the display unit. Alternatively, use the communication options to connect to an HMI/SCADA system.

1.1.2 Software versions

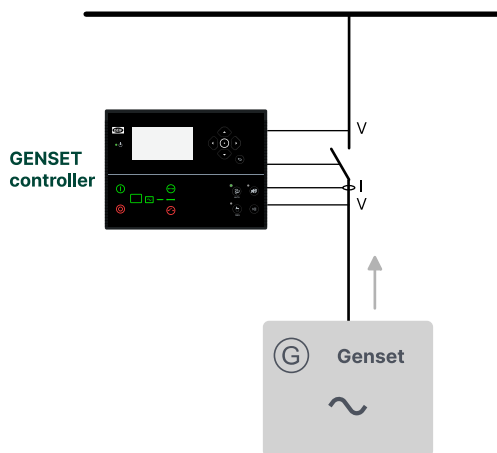
The information in this document relates to software version:

| Software | Details | Version |
|----------|------------------------|---------|
| iE 150 | Controller application | 1.32.0 |

NOTE iE 150 Core marine applications use the Core (S1) software package.

1.1.3 Stand-alone (island mode)

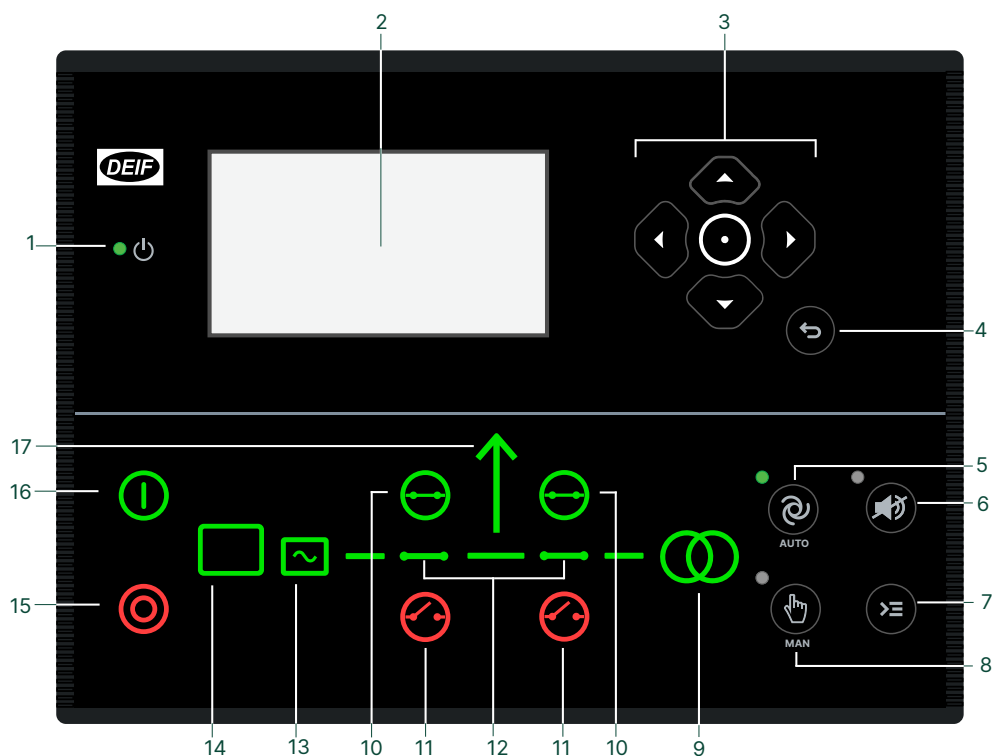
Stand-alone (island mode)













Stand-alone (island mode operation) is typically used in power plants that are isolated from other power generation systems.

NOTE You can disable breaker control.

1.1.3.1 Display layout

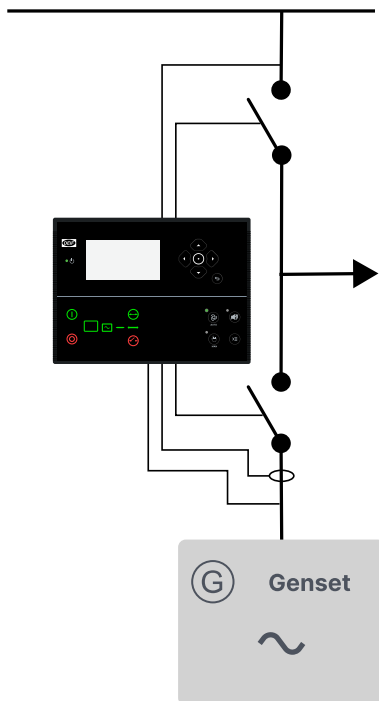


| No. | Name | Function |
|-----|---|---|
| 1 | Power | Green: The controller power is ON. OFF: The controller power is OFF. |
| 2 | Display screen | Resolution: 240 x 128 px. Viewing area: 88.50 x 51.40 mm. Six lines, each with 25 characters. |
| 3 | Navigation | Move the selector up, down, left and right on the screen. |
| |  Enter button | Go to the Menu system. Confirm the selection on the screen. |
| 4 |  Back button | Go to the previous page. |
| 5 |  Remote mode | Remote equipment (digital inputs, Modbus commands, AOP-2 commands) controls the iE 150. |
| 6 |  Silence horn | Turns off an alarm horn (if configured) and enters the Alarm menu. |
| 7 |  Shortcut menu | Access the Jump menu, Mode selection, Test, Lamp test. |
| 8 |  Local mode | The operator can use the display buttons to start, stop, connect or disconnect the genset. |
| 9 | Mains symbol | This controller does not use this. It is only lit during a lamp test. |
| 10 |  Close breaker | Push to close the breaker. |
| 11 |  Open breaker | Push to open the breaker. |
| 12 | Breaker symbols | Green: Breaker is closed. Red: Breaker failure. OFF: The breaker is open. |

| No. | Name | Function |
|-----|---|---|
| 13 | Generator | Green: Generator voltage and frequency are OK. The controller can close the breaker. Green flashing: The generator voltage and frequency are OK, but the V&Hz OK timer is still running. The controller cannot close the breaker. Red: The generator voltage is too low to measure. |
| 14 | Engine | Green: There is running feedback. Green flashing: The engine is getting ready. Red: The engine is not running, or there is no running feedback. |
| 15 |  Stop | Stops the genset if Local mode is selected. |
| 16 |  Start | Starts the genset if Local mode is selected. |
| 17 | Load symbol | Green: The supply voltage and frequency are OK. Red: Supply voltage/frequency failure. |

1.1.4 Emergency genset

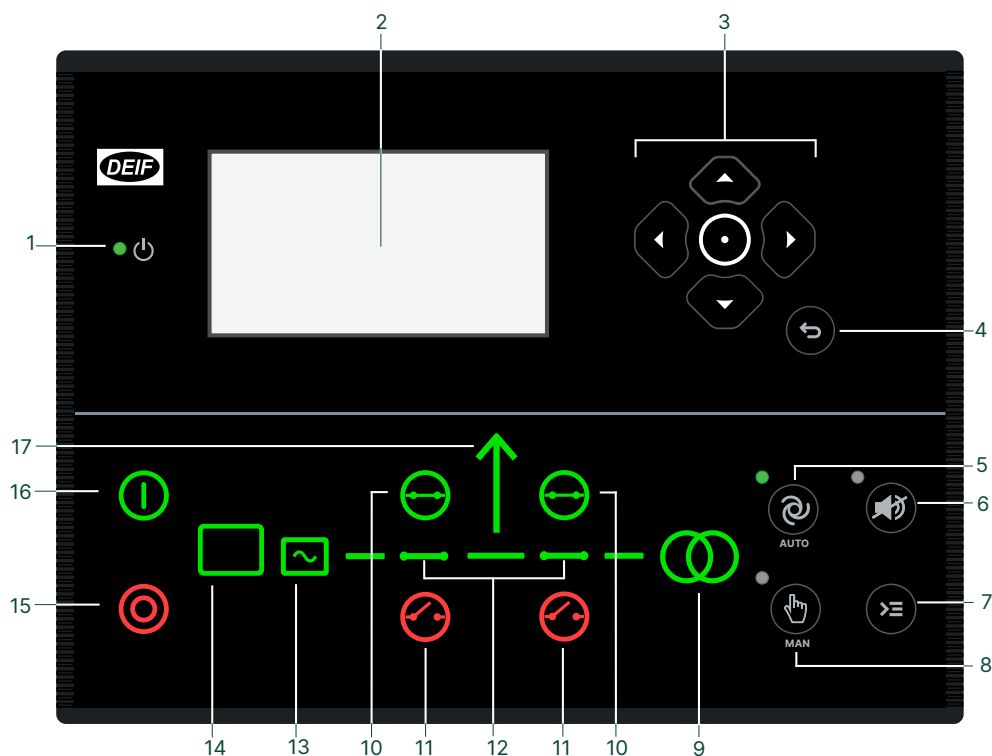
Emergency genset













If there is a significant loss of power or a total blackout in the main power generation system, the controller automatically changes the supply to the emergency generator. This makes sure that there is power during a failure and prevents damage to electrical equipment.

NOTE Alternatively, the breaker to the busbar can be externally controlled.

1.1.4.1 Display layout



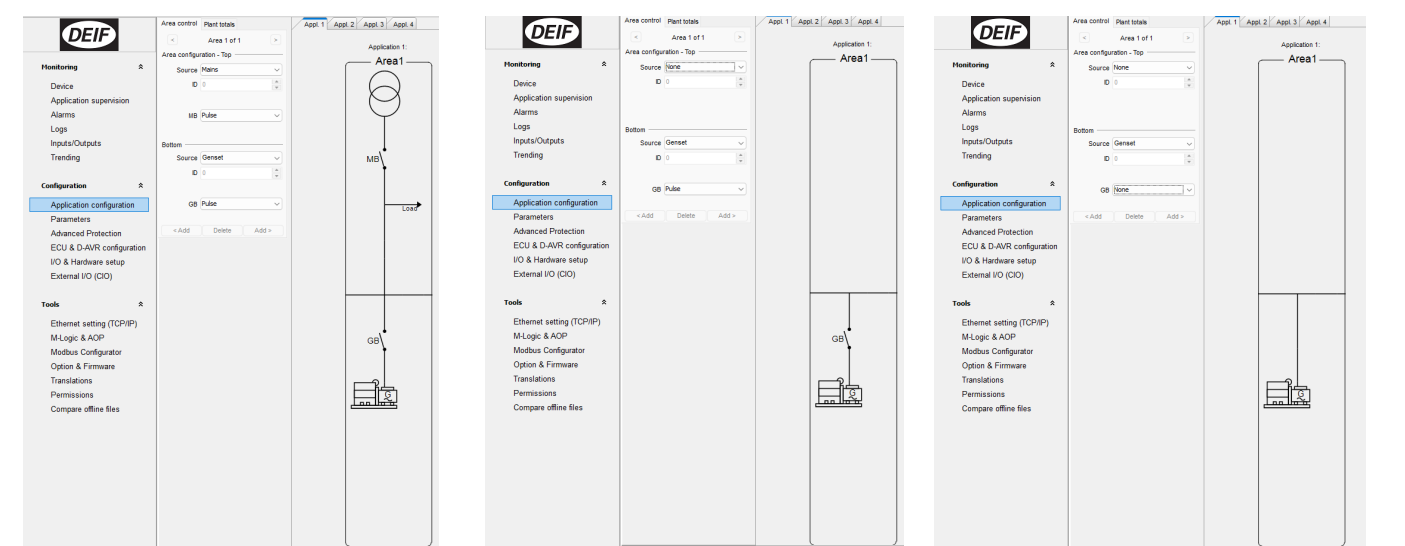
| No. | Name | Function |
|-----|---|--|
| 1 | Power | Green: The controller power is ON. OFF: The controller power is OFF. |
| 2 | Display screen | Resolution: 240 x 128 px. Viewing area: 88.50 x 51.40 mm. Six lines, each with 25 characters. |
| 3 | Navigation | Move the selector up, down, left and right on the screen. |
| |  Enter button | Go to the Menu system. Confirm the selection on the screen. |
| 4 |  Back button | Go to the previous page. |
| 5 |  Local mode | If there is a blackout, the controller automatically starts and connects the genset. No operator actions are needed. The controller also automatically opens and closes the tie breaker (open transitions, since there is no synchronisation). |
| 6 |  Silence horn | Turns off an alarm horn (if configured) and enters the Alarm menu. |
| 7 |  Shortcut menu | Access the Jump menu, Mode selection, Test, Lamp test. |
| 8 |  Remote mode | Remote equipment (digital inputs, Modbus commands, AOP-2 commands) controls the controller. The operator can also use the display buttons. |
| 9 | Mains symbol | This controller does not use this. It is only lit during a lamp test. |
| 10 |  Close breaker | Push to close the breaker. |
| 11 |  Open breaker | Push to open the breaker. |
| 12 | Breaker symbols | Green: Breaker is closed. Red: Breaker failure. |

| No. | Name | Function |
|-----|---|---|
| | | OFF: The breaker is open. |
| 13 | Generator | Green: Generator voltage and frequency are OK. The controller can close the breaker. Green flashing: The generator voltage and frequency are OK, but the V&Hz OK timer is still running. The controller cannot close the breaker. Red: The generator voltage is too low to measure. |
| 14 | Engine | Green: There is running feedback. Green flashing: The engine is getting ready. Red: The engine is not running, or there is no running feedback. |
| 15 |  Stop | Stops the genset if Remote mode is selected. |
| 16 |  Start | Starts the genset if Remote mode is selected. |
| 17 | Load symbol | Green: The supply voltage and frequency are OK. Red: Supply voltage/frequency failure. |

1.1.5 Easy configuration with the utility software

Set up an application easily with a PC and the utility software.

You can also use the utility software to quickly configure the inputs, outputs, and parameters.



Application with two breakers

Application with one breaker

Application with no breakers

1.2 Functions and features

1.2.1 Controller functions

| Engine features |
|---|
| Start and stop sequences |
| Engine communication |
| Speed sensing using CAN, MPU or frequency |
| Tier 4 final support |
| Temperature-dependent cooling down |
| Time-based cooling down |

Engine features

Fuel usage monitoring

Fuel pump logics

Maintenance alarms

Configurable crank and run coil

Other engine functions

Fuel usage monitoring

Fuel pump logic and refill

Diesel exhaust fluid monitoring

Diesel exhaust fluid logic and refill

Generic fluid monitoring

Generic fluid logic and refill

Protection packages

Engine protection

Communication with KWG ISO5 isolation monitor (CAN bus)

Operation modes

Stand-alone (island mode)

Emergency genset

AC functions

4 sets of nominal settings

Select the AC configuration:

- 3-phase/3-wire
- 3-phase/4-wire
- 2-phase/3wire (L1/L2/N or L1/L3/N)
- 1-phase/2-wire L1

100 to 690 V AC (selectable)

CT -/1 or -/5 (selectable)

4th current measurement (select one)

- Mains current (and power)
- Neutral current (1 × true RMS)
- Ground current (with 3rd harmonic filter)

Ground relay

General functions

Built-in test sequences
(Simple test, Load test, Full test, and Battery test)

20 lines of PLC logic (M-Logic)

Counters, including:

- Breaker operations
- kWh meter (day, week, month, total)

General functions

- kvarh meter (day, week, month, total)

Setting and parameter functions

Quick setup

User-defined permission level

Password-protected setup

Trending on USW

Event logs with password, up to 500 entries

Display and language functions

Supports multiple languages
(including Chinese, Russian, and other languages with special characters)

20 configurable graphical screens

Graphical display with six lines

Parameters can be changed on the display unit

3 engine function shortcuts

20 configurable shortcut buttons

5 configurable display screen "LED lamps" (on/off/blink)

Modbus functions

Modbus RS-485

Modbus TCP/IP

Configurable Modbus area

1.2.2 Supported controllers and engines

The iE 150 can communicate with the following ECUs and engines.

| Manufacturer | ECU | Engines | Tier 4/Stage V | iE 150 parameter 7561 |
|---------------|-------------------------|---|----------------|-----------------------|
| Generic J1939 | Any ECU that uses J1939 | Any engine that uses J1939 | ● | Generic J1939 |
| ANGLE | | | - | ANGLE |
| Baudouin | | | - | Baudouin CPCB IV |
| Baudouin | WOODWARD PG+ | - | - | Baudouin Gas |
| Baudouin | Wise 10B | - | - | Baudouin Wise10B |
| Baudouin | Wise 15 | - | ● | Baudouin Wise15 |
| Bosch | EDC17 | | | Bosch EDC17CV54TMTL |
| Caterpillar | ADEM3 | C4.4, C6.6, C9, C15, C18, C32, 3500, 3600 | - | Caterpillar ADEM3 |
| Caterpillar | ADEM4 | | - | Caterpillar ADEM4 |
| Caterpillar | ADEM5 | | - | Caterpillar ADEM5 |

| Manufacturer | ECU | Engines | Tier 4/Stage V | iE 150 parameter 7561 |
|----------------|---|--|----------------|----------------------------|
| Caterpillar | ADEM6 | | - | Caterpillar ADEM6 |
| Caterpillar | ADEM3, ADEM4 | C4.4, C6.6, C9, C15, C18, C32, 3500, 3600 | - | Caterpillar Generic* |
| Caterpillar | | | - | Caterpillar with C7.1 AT |
| Cummins | CM 500 | QSL, QSB5, QSX15 and 7, QSM11, QSK 19/23/50/60 | - | Cummins CM500 |
| Cummins | CM 558 | QSL, QSB5, QSX15 and 7, QSM11, QSK 19/23/50/60 | - | Cummins CM558 |
| Cummins | CM 570 | QSL, QSB5, QSX15 and 7, QSM11, QSK 19/23/50/60 | - | Cummins CM570 |
| Cummins | Cummins CM 570 Industrial | | ● | Cummins CM570 Industrial |
| Cummins | CM 850 | QSL, QSB5, QSX15 and 7, QSM11, QSK 19/23/50/60 | - | Cummins CM850 |
| Cummins | CM 2150 | QSL, QSB5, QSX15 and 7, QSM11, QSK 19/23/50/60 | ● | Cummins CM2150 |
| Cummins | CM 2250 | QSL, QSB5, QSX15 and 7, QSM11, QSK 19/23/50/60 | ● | Cummins CM2250 |
| Cummins | CM 500, CM 558, CM 570, CM 850, CM 2150 and CM 2250 | - | ECU-dependent | Cummins Generic* |
| Cummins | | | | Cummins Generic Industrial |
| Cummins | CM 2350 | | ● | Cummins CM2350 |
| Cummins | CM 2350 Industrial | | ● | Cummins CM2350 Industrial |
| Cummins | CM 2358 | | ● | Cummins CM2358 |
| Cummins | CM 2850 | | ● | Cummins CM2850 |
| Cummins | CM 2880 | | ● | Cummins CM2880 |
| Cummins | CM 2880 Industrial | | ● | Cummins CM2880 Industrial |
| Cummins | - | KTA19 | - | Cummins KTA19 |
| Cummins | PGI | | ● | Cummins PGI |
| Detroit Diesel | DDEC III | Series 50, 60 and 2000 | - | DDEC III |
| Detroit Diesel | DDEC IV | Series 50, 60 and 2000 | - | DDEC IV |
| Detroit Diesel | DDEC III, DDEC IV | Series 50, 60 and 2000 | - | DDEC Generic* |
| Deutz | EMR2 | - | - | Deutz EMR 2 |
| Deutz | EMR3 | - | - | Deutz EMR 3 |
| Deutz | EMR 2, EMR 3 | - | - | Deutz EMR Generic* |
| Deutz | EMR4 | - | - | Deutz EMR 4 |
| Deutz | EMR5 | - | - | Deutz EMR 5 |
| Deutz | EMR4 Stage V | - | ● | Deutz EMR 4 Stage V |
| Deutz | EMR5 Stage V | | ● | Deutz EMR 5 Stage V |
| Doosan | EDC17 | - | - | Doosan G2 EDC17 |
| Doosan | MD1 | - | ● | Doosan MD1 |
| Doosan | G2 EDC17 | | ● | Doosan stage 5 |

| Manufacturer | ECU | Engines | Tier 4/Stage V | iE 150 parameter 7561 |
|----------------|---|--|----------------|-----------------------|
| FPT Industrial | EDC17 | - | - | FPT EDC17CV41 |
| FPT Industrial | Bosch MD1 | - | ● | FPT stage V |
| Hatz Diesel | - | 3/4H50 TICD | ● | Hatz |
| Hatz Diesel | EDC17 | - | - | Hatz EDC17 |
| Isuzu | ECM | 4JJ1X, 4JJ1T, 6WG1X FT-4 | - | Isuzu |
| Iveco | CURS0R | - | - | Iveco CURS0R |
| Iveco | EDC7 (Bosch MS6.2), | - | - | Iveco EDC7 |
| Iveco | NEF | - | - | Iveco NEF |
| Iveco | Iveco NEF67 | | ● | Iveco Stage V NEF67 |
| Iveco | VECTOR 8 | - | - | Iveco Vector8 |
| Iveco | CURS0R, NEF, EDC7, VECTOR 8 | | ●** | Iveco Generic* |
| Iveco | Bosch MD1 | - | ● | Iveco Stage V |
| JCB | - | ECOMAX DCM3.3+ | ● | JCB |
| JCB | | P745 & P740 DieselMax Stage V Version 7 | ● | JCB 430/448 Stage V |
| Jichai | JC15D-ECU22 | - | - | JC15D Weifu*** |
| Jichai | JC15D WYS | | - | JC15D WYS |
| Jichai | JC190 | | - | JC190 |
| Jichai | JC15T JG | | - | Jichai JC15T JG |
| Jing Guan | | Gas | - | Jing Guan |
| John Deere | JDEC | PowerTech M, E and Plus | ● | John Deere |
| John Deere | FOCUS controls (version 2.1) | - | ● | John Deere Stage V |
| Kohler | ECU2-HD | KD62V12 | ● | Kohler KD62V12 |
| Kohler | - | KDI 3404 | - | Kohler KDI 3404 |
| Kubota | KORD3 | | ● | Kubota Stage V |
| MAN | EDC17 | - | | MAN EDC17 |
| MAN | EMC 2.0 | - | - | MAN EMC Step 2.0 |
| MAN | EMC 2.5 | - | - | MAN EMC Step 2.5 |
| MAN | EMC 2.0 and 2.5 | - | - | MAN Generic* |
| MTU | MDEC, module M.201 | - | | MDEC 2000/4000 M.201 |
| MTU | MDEC module M.302 | Series 2000 and 4000 | - | MDEC 2000/4000 M.302 |
| MTU | MDEC module M.303 | Series 2000 and 4000 | - | MDEC 2000/4000 M.303 |
| MTU | MDEC, module M.304 | - | | MDEC 2000/4000 M.304 |
| MTU | ADEC | Series 2000 and 4000 (ECU7), MTU PX | - | MTU ADEC |
| MTU | ADEC, ECU7 without SAM module (software module 501) | Series 2000 and 4000 | - | MTU ADEC module 501 |

| Manufacturer | ECU | Engines | Tier 4/Stage V | iE 150 parameter 7561 |
|---------------------|---------------------------------|---|-------------------|---------------------------|
| MTU | ECU7 with SAM module | - | - | MTU ECU7 with SAM |
| MTU | ECU8 | - | - | MTU ECU8 |
| MTU | ECU9 | - | ● | MTU ECU9 |
| MTU | J1939 Smart Connect, ECU8, ECU9 | Series 1600 | ● (ECU9 or later) | MTU J1939 Smart Connect |
| Perkins | ADEM3 | - | - | Perkins ADEM3 |
| Perkins | ADEM4 | - | - | Perkins ADEM4 |
| Perkins | ADEM3 and ADEM4 | Series 850, 1100, 1200, 1300, 2300, 2500 and 2800 | - | Perkins Generic* |
| Perkins | EDC17 | - | - | Perkins EDC17C49 |
| Perkins | - | Series 400 and 1200 | ● | Perkins Stage V |
| Perkins | - | Series 400 Model IQ IR IW IY IF | ● | Perkins StV 400 |
| Perkins | - | Series 1200F Model MT, MU, MV, MW, BM and BN | ● | Perkins StV 1200 |
| Perkins | - | Series 1200J Model SU, VM | ● | Perkins StV 120xJ (SU/VM) |
| PSI/Power Solutions | - | PSI/Power Solutions | ● | PSI/Power Solutions |
| QiYao | | | - | QiYao Gas |
| Scania | EMS | - | - | Scania EMS |
| Scania | EMS S6 (KWP2000) | Dx9x, Dx12x, Dx16x | - | Scania EMS 2 S6 |
| Scania | EMS S6 (KWP2000) | Dx9x, Dx12x, Dx16x | - | Scania S6 Industrial |
| Scania | EMS 2 S8 | DC9, DC13, DC16 | ● | Scania EMS 2 S8 |
| Scania | EMS 2 S8 | DC9, DC13, DC16 | ● | Scania S8 Industrial |
| SDEC | F20 | | - | SDEC F20 |
| SDEC | F45 | | - | SDEC F45 |
| Steyr | EDC17 | - | - | Steyr EDC17 |
| Volvo Penta | D12 | | | Volvo Penta D12 |
| Volvo Penta | EDC3 | - | - | Volvo Penta EDC3 |
| Volvo Penta | EDC4 | - | - | Volvo Penta EDC4 |
| Volvo Penta | EDC3, EDC4 | TAD4x, TAD5x, TAD6x, TAD7x | - | Volvo Penta Generic* |
| Volvo Penta | EMS, EMS 2.0 to EMS2.3 | D6, D7, D9, D12, D16 (GE and AUX variants only) | ● | Volvo Penta EMS2 |
| Volvo Penta | EMS2.3 | | ● | Volvo Penta EMS2.3 |
| Volvo Penta | EMS2.4 | - | ● | Volvo Penta EMS2.4 |
| Weichai | WOODWARD PG+ | Diesel | ● | Weichai Diesel |
| Weichai | WOODWARD PG+ | Gas | ● | Weichai Gas |
| Weichai | Wise 10B | - | ● | Weichai Wise10B |
| Weichai | Wise 13 | | | Weichai Wise13 |

| Manufacturer | ECU | Engines | Tier 4/Stage V | iE 150 parameter 7561 |
|---------------|---------------------|---------|----------------|-------------------------|
| Weichai | Wise 15 | - | ● | Weichai Wise15 |
| Weichai | | | - | Weichai Baudouin E6 Gas |
| Xichai | | | | Xichai Gas |
| YANMAR | EDC17 | - | - | YANMAR EDC17 |
| YANMAR | | | | YANMAR Gas 4G |
| YANMAR | - | TN, TNV | - | YANMAR Stage V |
| Yuchai United | YCGCU (Version 4.2) | Diesel | ● | Yuchai United Diesel |
| Yuchai United | YCGCU (Version 4.2) | Gas | ● | Yuchai United Gas |
| Yuchai United | YC-BCR | - | - | Yuchai YC-BCR |
| Yuchai United | YC-ECU | - | - | Yuchai YC-ECU |
| Yuchai United | YC-EDU-A | | | Yuchai YC-ECU-A |

NOTE * Generic protocols are included for backward compatibility.

NOTE ** If supported by the ECU and engine.

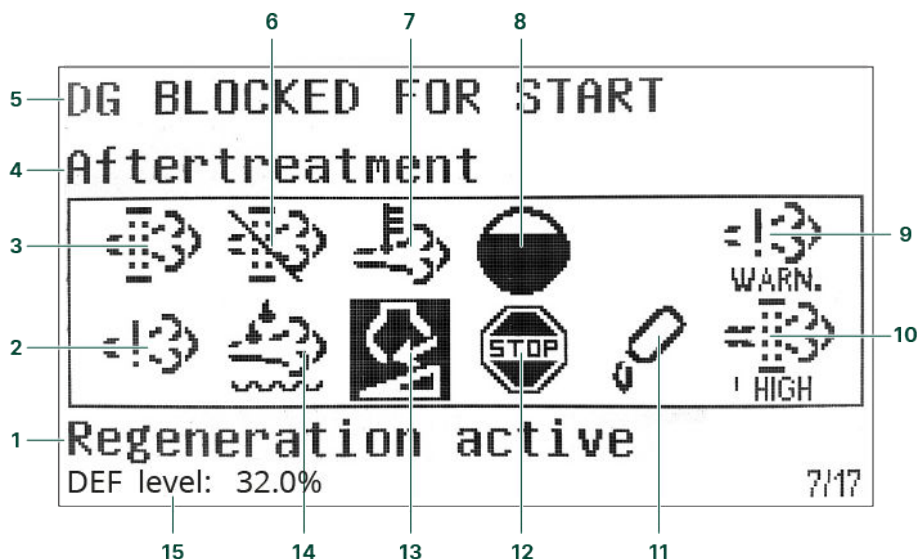
NOTE *** Previously *Jichai*

Other EIC protocols: Contact DEIF.

1.2.3 Exhaust after-treatment (Tier 4/Stage V)

iE 150 meets the Tier 4 (Final)/Stage V requirements. The user can use the display to monitor (and control) both the engine, and the exhaust after-treatment system.

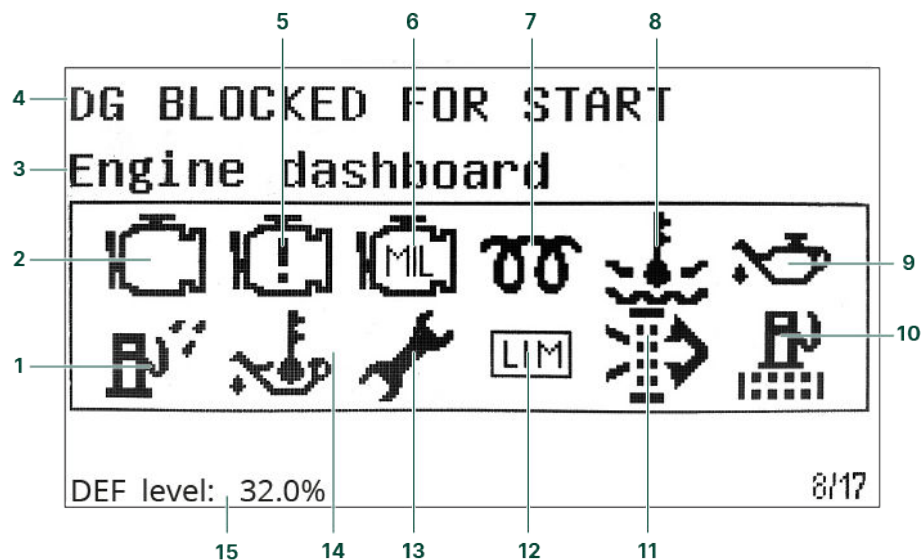
After-treatment page




| No. | Referent | Symbol | Description |
|-----|--------------------------------|--------|----------------------------------|
| 1 | After-treatment status | - | |
| 2 | Engine emission system failure | | Emission failure or malfunction. |
| 3 | Diesel Particle Filter (DPF) | | Regeneration is needed. |

| No. | Referent | Symbol | Description |
|-----|--------------------------------------|----------|---|
| 4 | Page name | - | |
| 5 | Controller status | - | |
| 6 | Diesel Particle Filter (DPF) Inhibit | | Regeneration is inhibited. |
| 7 | High temperature - Regeneration | | There is a high temperature and regeneration is in process. |
| 8 | HC burn-off | | Hydrocarbon accumulation that requires burn-off. |
| 9 | Engine emission system failure level | | Emission failure or malfunction, with the severity. |
| 10 | Diesel Particle Filter (DPF) level | | Regeneration needed, with the severity. |
| 11 | DEF level warning | | Low DEF level. |
| 12 | DEF shutdown | | DEF problem stops normal operation. |
| 13 | DEF level inducement | | Mid-level inducement. Severe inducement. |
| 14 | Diesel Exhaust Fluid (DEF) | | DEF quality is low. |
| 15 | DEF level | | DEF level. |

Engine dashboard



| No. | Referent | Symbol | Description |
|-----|---------------------------------|--------|---|
| 1 | Water in fuel | | There is water in the fuel. |
| 2 | Engine interface status | | An engine warning. |
| 3 | Page name | - | - |
| 4 | Controller status | - | - |
| 5 | Engine interface status | | An engine shutdown. |
| 6 | Engine interface status | | An engine malfunction. |
| 7 | Cold start | | The engine is cold. |
| 8 | High engine coolant temperature | | The engine coolant temperature is high. |
| 9 | Low engine oil pressure | | The engine oil pressure is low. |
| 10 | Fuel filter clogging | | The fuel filter is blocked. |
| 11 | Air filter clogging | | The air filter is blocked. |
| 12 | LIMIT lamp | | Only for MTU engines. |
| 13 | Oil change | | The engine needs an oil change. |

| No. | Referent | Symbol | Description |
|-----|-----------------------------|---|-------------------------------------|
| 14 | High engine oil temperature |  | The engine oil temperature is high. |
| 15 | DEF level | | DEF level. |

NOTE Grey symbols show that communication is available for the referent. An engine type might not support all of the referents.

1.3 Alarms and protections

| AC protections | Alarms | ANSI | Operate time |
|---|-----------|------|--------------|
| Reverse power | 2 | 32R | <200 ms |
| Fast over-current | 2 | 50P | <40 ms |
| Over-current | 4 | 50TD | <200 ms |
| Voltage dependent over-current | 1 | 50V | |
| Over-voltage | 2 | 59 | <200 ms |
| Under-voltage | 3 | 27P | <200 ms |
| Over-frequency | 3 | 81O | <300 ms |
| Under-frequency | 3 | 81U | <300 ms |
| Unbalanced voltage | 1 | 47 | <200 ms |
| Unbalanced current | 1 | 46 | <200 ms |
| Under-excitation or reactive power import | 1 | 32RV | <200 ms |
| Over-excitation or reactive power export | 1 | 32FV | <200 ms |
| Overload | 5 | 32F | <200 ms |
| Inverse time earth over-current | 1 | 50G | <100 ms |
| Inverse time neutral over-current | 1 | 50N | <100 ms |
| Busbar over-voltage | 3 | 59P | <50 ms |
| Busbar under-voltage | 4 | 27P | <50 ms |
| Busbar over-frequency | 3 | 81O | <50 ms |
| Busbar under-frequency | 3 | 81U | <50 ms |
| Emergency stop | 1 | | <200 ms |
| Low auxiliary supply | 1 | 27DC | |
| High auxiliary supply | 1 | 59DC | |
| Generator breaker external trip | 1 | | |
| Tie breaker external trip | 1 | | |
| Breaker open failure | 1/breaker | 52BF | |
| Breaker close failure | 1/breaker | 52BF | |
| Breaker position failure | 1/breaker | 52BF | |
| Phase sequence error | 1 | 47 | |
| Hz/V failure | 1 | | |
| Not in remote | 1 | | |

| Engine protections | Alarms | ANSI | Operate time |
|-------------------------------|--------|------|--------------|
| Overspeed | 2 | 12 | <400 ms |
| Crank failure | 1 | 48 | |
| Running feedback error | 1 | 34 | |
| MPU wire break | 1 | - | |
| Start failure | 1 | 48 | |
| Stop failure | 1 | - | |
| Stop coil, wire break alarm | 1 | - | |
| Engine heater | 1 | 26 | |
| Max. ventilation/radiator fan | 1 | - | |
| Fuel fill check | 1 | - | |

1.4 Compatible products

1.4.1 Additional inputs and outputs

iE 150 uses CAN bus communication with these:

- **CIO 116** is a remote input expansion module. See www.deif.com/products/cio-116
- **CIO 208** is a remote output expansion module. See www.deif.com/products/cio-208
- **CIO 308** is a remote I/O module. See www.deif.com/products/cio-308
- **IOM 220** and **IOM 230** each have two analogue outputs. These can be used for governor and AVR regulation, or general PID control. See www.deif.com/products/iom-200230

1.4.2 Additional operator panel, AOP-2

The controller uses CAN bus communication to the additional operator panel (AOP-2). Configure the controller using M-Logic. On the AOP-2, the operator can then:

- Use the buttons to send commands to the controller.
- See LEDs light up to show statuses and/or alarms.

You can configure and connect two AOP-2s if the controller has the premium software package.

1.4.3 Remote display: iE 150

The remote display is an iE 150 that only has a power supply and an Ethernet connection to an iE 150 controller. The remote display allows the operator to see the controller's operating data, as well as operate the controller remotely.

1.4.4 Shutdown unit, SDU 104

The SDU 104 is a safety device for the protection of engines. The unit keeps the engine running if the main controller fails. The unit can also safely shut down the engine.

See www.deif.com/products/sdu-104

1.4.5 Other equipment

DEIF has a wide variety of other equipment that is compatible. Here are some examples:

- **Synchrosopes**
 - **CSQ-3** (www.deif.com/products/csq-3)

- **Battery chargers/power supplies**
 - **DBC-1** (www.deif.com/products/dbc-1)
- **Current transformers**
 - **ASK** (www.deif.com/products/ask-asr)
 - **KBU** (www.deif.com/products/kbu)
- **Transducers**
 - **MTR-4** (www.deif.com/products/mtr-4)

1.4.6 Controller types

LAND variants

| Parameter | Setting | Controller type | Minimum software |
|-----------|----------------------|---|------------------|
| 9101 | Genset unit | Generator Stand-alone controller | S1 |
| | Genset unit | Generator controller | S2 |
| | Mains unit | Mains controller | S2 |
| | Bus Tie Breaker unit | BTB controller | S2 |
| | Genset Hybrid unit | Genset-Solar hybrid controller | S2 |
| | Engine Drive unit | Engine drive controller | S1 |
| | Remote display unit | Remote display | None |
| | Battery unit | Battery storage controller | S4 + S10 |
| | Solar unit | Solar controller | S4 + S10 |
| | ATS unit | Automatic transfer switch (open transition) | S1 |
| | ATS unit | Automatic transfer switch (closed transition) | S2 |
| | Genset PMS lite unit | PMS lite controller | S2 |

MARINE variants

| Parameter | Setting | Controller type | Minimum software |
|-----------|--------------------------|---|------------------|
| 9101 | Engine Drive Marine unit | Engine drive controller for marine use | S1 |
| | Genset Marine unit | Core (stand-alone) genset controller for marine use | S1 |
| | Genset Marine unit | Genset controller for marine use | S2 |
| | Shore Marine unit | Shore controller for marine use | S2 |
| | BTB Marine unit | BTB controller for marine use | S2 |
| | Battery Marine unit | Battery controller for marine use | S4 + S10 |
| | Solar Marine unit | Solar controller for marine use | S4 + S10 |

Software packages and controller types

The controller software package determines which functions the controller can use.

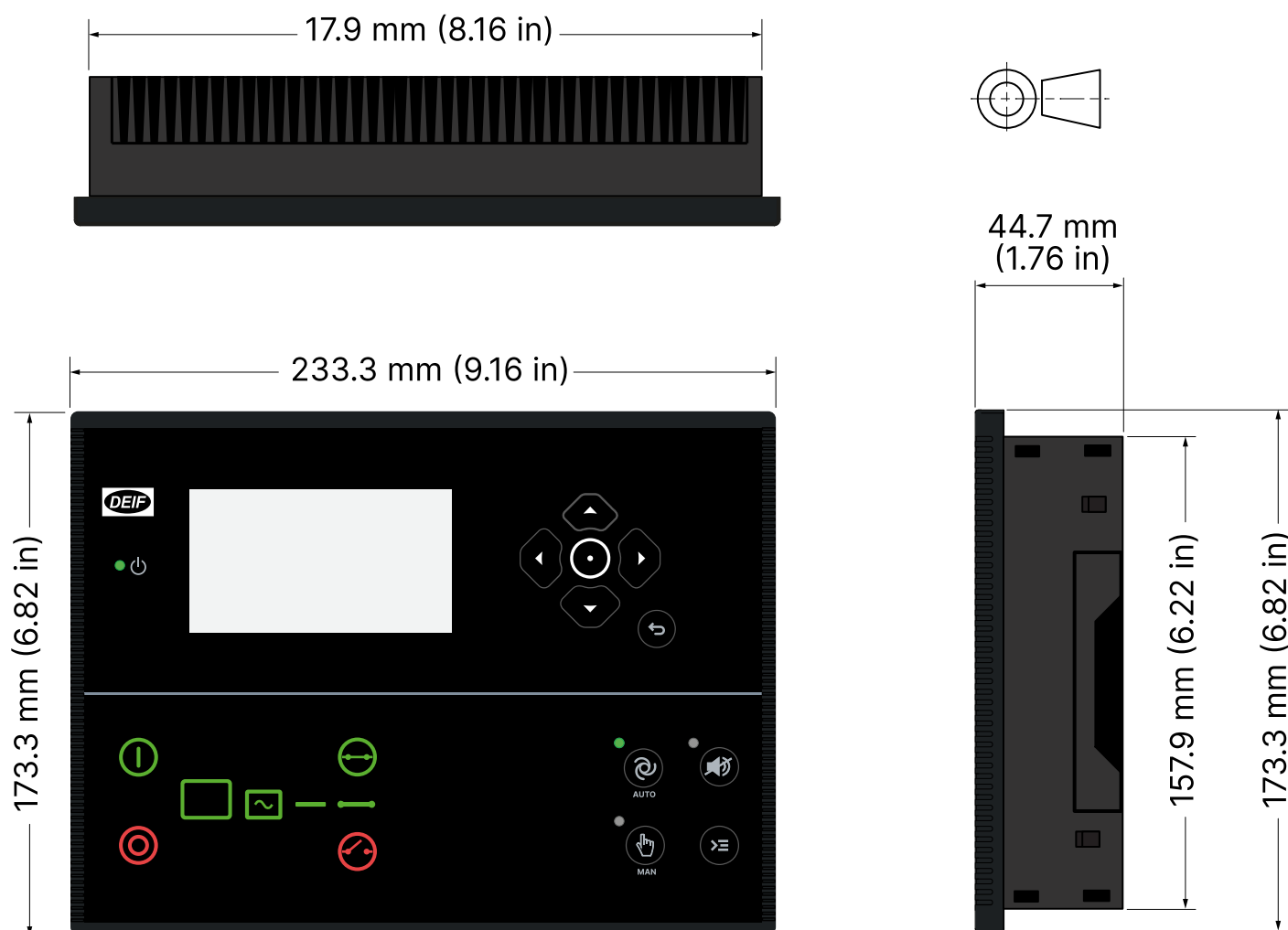
- S1 = Core
 - You can change the controller type to any other controller that uses S1.
- S2 = Sync
 - You cannot change the controller type.
- S4 = PM (power management)

- You cannot change the controller type.
- S4 + S10 = Premium
 - You can change the controller type to any other controller type.
 - All functions are supported.

You can select the controller type under `Basic settings > Controller settings > Type`.

2. Technical specifications

2.1 Dimensions



Dimensions and weight

| | |
|----------------------|--|
| Dimensions | Length: 233.3 mm (9.16 in) Height: 173.3 mm (6.82 in) Depth: 44.7 mm (1.76 in) |
| Panel cutout | Length: 218.5 mm (8.60 in) Height: 158.5 mm (6.24 in) Tolerance: ± 0.3 mm (0.01 in) |
| Max. panel thickness | 4.5 mm (0.18 in) |
| Mounting | UL/cUL Listed: Type complete device, open type 1 UL/cUL Listed: For use on a flat surface of a type 1 enclosure |
| Weight | 0.79 kg |

2.2 Mechanical specifications

Operation conditions

| | |
|-----------|--|
| Vibration | Response: <ul style="list-style-type: none"> 10 to 58.1 Hz, 0.15 mmpp |
|-----------|--|

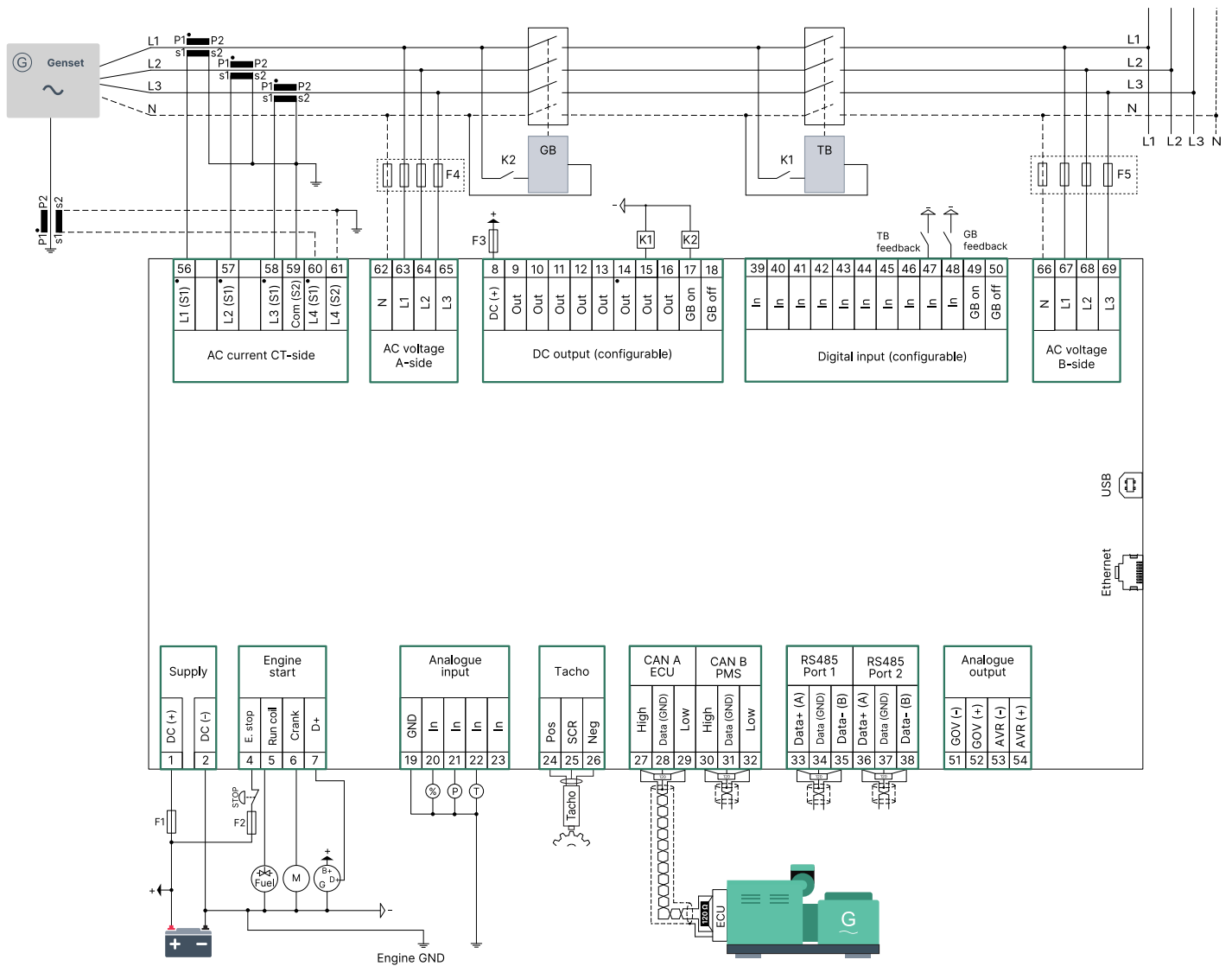
| Operation conditions | |
|----------------------|--|
| | <ul style="list-style-type: none"> 58.1 to 150 Hz, 1 g. To IEC 60255-21-1 (Class 2) <p>Endurance:</p> <ul style="list-style-type: none"> 10 to 150 Hz, 2 g. To IEC 60255-21-1 (Class 2) <p>Seismic vibration:</p> <ul style="list-style-type: none"> 3 to 8.15 Hz, 15 mmpp 8.15 to 35 Hz, 2 g. To IEC 60255-21-3 (Class 2) |
| Shock | <p>10 g, 11 ms, half sine. To IEC 60255-21-2 Response (Class 2)</p> <p>30 g, 11 ms, half sine. To IEC 60255-21-2 Withstand (Class 2)</p> <p>50 g, 11 ms, half sine. To IEC 60068-2-27, test Ea</p> <p>Tested with three impacts in each direction in three axes (total of 18 impacts per test)</p> |
| Bump | <p>20 g, 16 ms, half sine IEC 60255-21-2 (Class 2)</p> <p>Tested with 1000 impacts in each direction on three axes (total of 6000 impacts per test)</p> |
| Galvanic separation | <p>CAN port 2 (CAN B): 550 V, 50 Hz, 1 minute</p> <p>RS-485 port 1: 550 V, 50 Hz, 1 minute</p> <p>Ethernet: 550 V, 50 Hz, 1 minute</p> <p>Analogue output 51-52 (GOV): 550 V, 50 Hz, 1 minute</p> <p>Analogue output 54-55 (AVR): 3000 V, 50 Hz, 1 minute</p> <p>Note: No galvanic separation on CAN port 1 (CAN A) and RS-485 port 2</p> |
| Safety | <p>Installation CAT. III 600 V</p> <p>Pollution degree 2</p> <p>IEC/EN 60255-27</p> |
| Flammability | All plastic parts are self-extinguishing to UL94-V0 |
| EMC | IEC/EN 60255-26 |

2.3 Environmental specifications

| Operation conditions | |
|--|--|
| Operating temperature (incl. display screen) | -40 to +70 °C (-40 to +158 °F) |
| Storage temperature (incl. display screen) | -40 to +85 °C (-40 to +185 °F) |
| Accuracy and temperature | Temperature coefficient: 0.2 % of full scale per 10 °C |
| Operating altitude | 0 to 4000 m with derating |
| Operating humidity | <p>Damp Heat Cyclic, 20/55 °C at 97 % relative humidity, 144 hours. To IEC 60255-1</p> <p>Damp Heat Steady State, 40 °C at 93 % relative humidity, 240 hours. To IEC 60255-1</p> |
| Change of temperature | 70 to -40 °C, 1 °C / minute, 5 cycles. To IEC 60255-1 |
| Protection degree | <p>IEC/EN 60529</p> <ul style="list-style-type: none"> IP65 (front of module when installed into the control panel with the supplied sealing gasket) IP20 on terminal side |

2.4 Controller

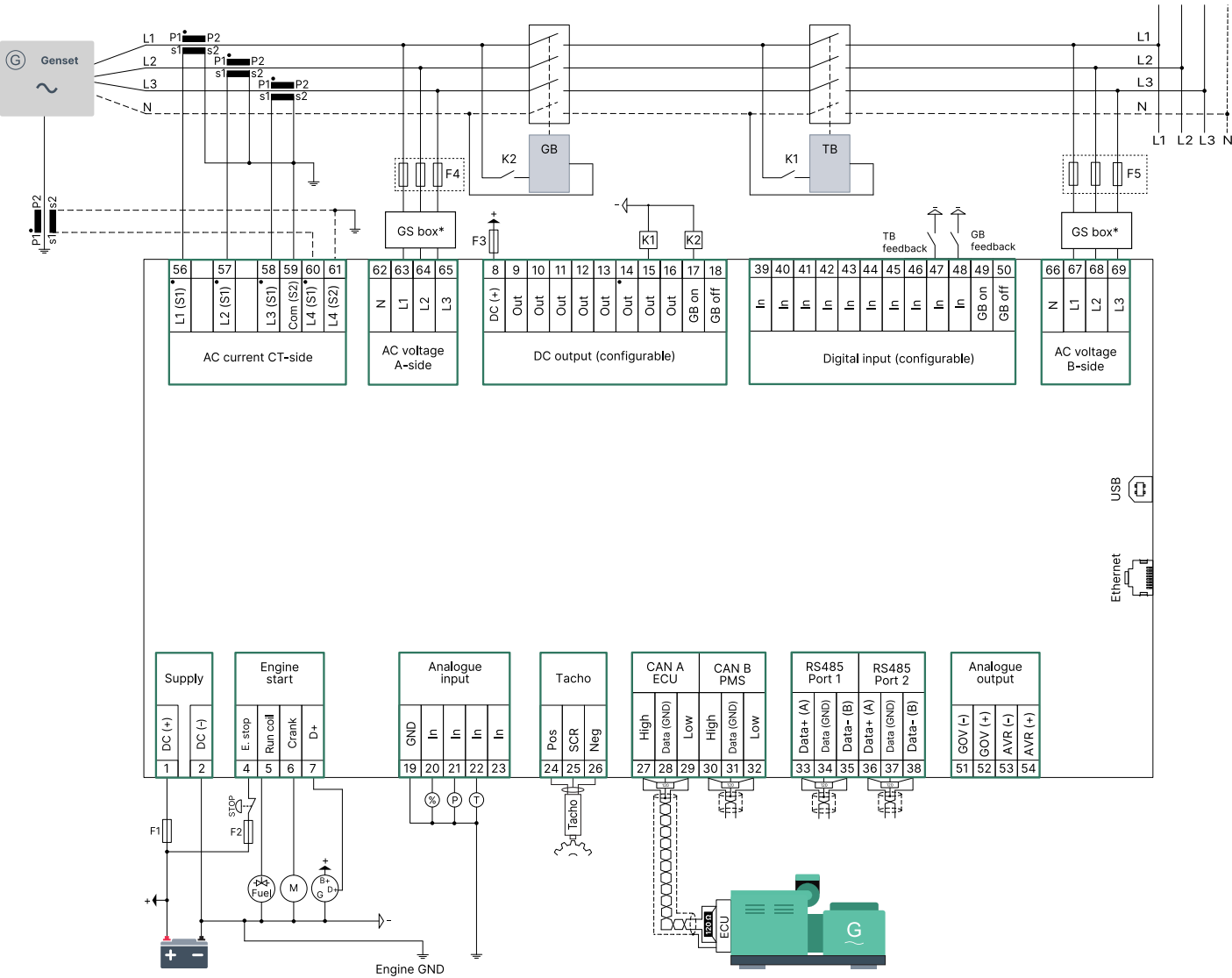
2.4.1 Typical wiring for stand-alone marine controller



Fuses

- F1: 2 A DC max. time-delay fuse/MCB, c-curve
- F2: 6 A DC max. time-delay fuse/MCB, c-curve
- F3: 4 A DC max. time-delay fuse/MCB, b-curve
- F4, F5: 2 A AC max. time-delay fuse/MCB, c-curve

Typical wiring for stand-alone marine controller with GS-box for galvanic separation



NOTE * One GS-box provides galvanic separation for both sets of voltage measurements.

See previous diagram for fuse information.

2.4.2 Electrical specifications

| Power supply | |
|-----------------------------------|--|
| Power supply range | Nominal voltage: 12 V DC or 24 V DC Operating range: 6.5 to 36 V DC |
| Voltage withstand | Reverse polarity |
| Power supply drop-out immunity | 0 V DC for 50 ms (coming from min. 6 V DC) |
| Power supply load dump protection | Load dump protected according to ISO16750-2 test A |
| Power consumption | 5 W typical 12 W max. |
| RTC clock | Time and date backup |

| Supply voltage monitoring | |
|---------------------------|----------------|
| Measuring range | 0 V to 36 V DC |

| Supply voltage monitoring | |
|---------------------------|--|
| | Max. continuous operating voltage: 36 V DC |
| Resolution | 0.1 V |
| Accuracy | ± 0.35 V |

| Voltage measurement | |
|---------------------|--|
| Voltage range | Nominal range: 100 to 690 V phase-to-phase (above 2000 m derate to max. 480 V) |
| Voltage withstand | $U_n + 35$ % continuously, $U_n + 45$ % for 10 seconds Measuring range of nominal: 10 to 135 % Low range, nominal 100 to 260 V: 10 to 351 V AC phase-to-phase High range, nominal 261 to 690 V: 26 to 932 V AC phase-to-phase |
| Voltage accuracy | ± 1 % of nominal within 10 to 75 Hz $+1/-4$ % of nominal within 3.5 to 10 Hz |
| Frequency range | 3.5 to 75 Hz |
| Frequency accuracy | ± 0.01 Hz within 60 to 135 % of nominal voltage ± 0.05 Hz within 10 to 60 % of nominal voltage |
| Input impedance | 4 M Ω /phase-to-ground, and 600 k Ω phase/neutral |

| Current measurement | |
|-----------------------|---|
| Current range | Nominal: -/1 A and -/5 A Range: 2 to 300 % |
| Number of CT input | 4 |
| Max. measured current | 3 A (-/1 A) 15 A (-/5 A) |
| Current withstand | 7 A continuous 20 A for 10 seconds 40 A for 1 second |
| Current accuracy | From 10 to 75 Hz: <ul style="list-style-type: none"> ± 1 % of nominal from 2 to 100% current ± 1 % of measured current from 100 to 300 % current From 3.5 to 10 Hz: <ul style="list-style-type: none"> $+1/-4$ % of nominal from 2 to 100 % current $+1/-4$ % of measured current from 100 to 300 % current |
| Burden | Max. 0.5 VA |

| Power measurement | |
|-----------------------|---|
| Accuracy power | ± 1 % of nominal within 35 to 75 Hz |
| Accuracy power factor | ± 1 % of nominal within 35 to 75 Hz |

| D+ | |
|-------------------------|------------------------------|
| Excitation current | 210 mA, 12 V 105 mA, 24 V |
| Charging fail threshold | 6 V |

| Tacho input | |
|---------------------------------|---|
| Voltage input range | +/- 1 V _{peak} to 70 V _{peak} |
| W | 8 to 36 V |
| Frequency input range | 10 to 10 kHz (max.) |
| Frequency measurement tolerance | 1 % of reading |

| Digital inputs | |
|-----------------------------------|--|
| Number of inputs | 12 x digital inputs Negative switching |
| Maximum input voltage | +36 V DC with respect to plant supply negative |
| Minimum input voltage | -24 V DC with respect to plant supply negative |
| Current source (contact cleaning) | Initial 10 mA, continuous 2 mA |

| DC outputs | |
|-------------------------|--|
| Number of 3 A outputs | 2 x outputs (for fuel and crank) 15 A DC inrush and 3 A continuous, supply voltage 0 to 36 V DC Endurance tested according to UL/ULC6200:2019 1.ed: 24 V, 3 A, 100000 cycles (with an external freewheeling diode) |
| Number of 0.5 A outputs | 10 x outputs 2 A DC inrush and 0.5 A continuous, supply voltage 4.5 to 36 V DC |
| Common | 12/24 V DC |

| Analogue inputs | |
|------------------|--|
| Number of inputs | 4 x analogue inputs |
| Electrical range | Configurable as: <ul style="list-style-type: none"> Negative switching digital input 0 V to 10 V sensor 4 mA to 20 mA sensor 0 Ω to 2.5 kΩ sensor |
| Accuracy | Current: <ul style="list-style-type: none"> Accuracy: ±20 uA ±1.00 % rdg Voltage: <ul style="list-style-type: none"> Range: 0 to 10 V DC Accuracy: ±20 mV ±1.00 % rdg RMI 2-wire LOW: <ul style="list-style-type: none"> Range: 0 to 800 Ω Accuracy: ±2 Ω ±1.00 % rdg RMI 2-wire HIGH: <ul style="list-style-type: none"> Range: 0 to 2500 Ω Accuracy: ±5 Ω ±1.00 % rdg |

| Voltage regulator output | |
|----------------------------|----------------------------|
| Output types | Isolated DC voltage output |
| Voltage range | -10 to +10 V DC |
| Resolution in voltage mode | Less than 1 mV |

| Voltage regulator output | |
|------------------------------|-----------------------|
| Maximum common mode voltage | ±3 kV |
| Minimum load in voltage mode | 500 Ω |
| Accuracy | ±1 % of setting value |

| Speed governor output | |
|------------------------------------|---|
| Output types | Isolated DC voltage output Isolated PWM output |
| Voltage range | -10 to +10 V DC |
| Resolution in voltage mode | Less than 1 mV |
| Maximum common mode voltage | ±550 V |
| Minimum load in voltage mode | 500 Ω |
| PWM frequency range | 1 to 2500 Hz ±25 Hz |
| PWM duty cycle resolution (0-100%) | 12 bits (4096 steps) |
| PWM voltage range | 1 to 10.5 V |
| Voltage accuracy | ±1% of setting value |

| Display unit | |
|--------------|---------------------------------------|
| Type | Graphical display screen (monochrome) |
| Resolution | 240 x 128 pixels |
| Navigation | Five-key menu navigation |
| Log book | Data log and trending function |
| Language | Multi-language display |

2.4.3 Communication

| Communication | |
|---------------|---|
| CAN A | <p>You can connect these in a daisy chain (and operate them at the same time):</p> <ul style="list-style-type: none"> • Engine CAN Port • CIO 116, CIO 208, and CIO 308 <p>Data connection 2-wire + common, or 3-wire Not isolated External termination required (120 Ω + matching cable) DEIF engine specification (J1939 + CANopen)</p> |
| CAN B | <p>Used for: AOP-2 Data connection 2-wire + common, or 3-wire Isolated External termination required (120 Ω + matching cable) PMS 125 kbit and 250 kbit</p> |
| RS-485 Port 1 | <p>Used for: Modbus RTU, PLC, SCADA, Remote monitoring (Insight) Data connection 2-wire + common, or 3-wire Isolated External termination required (120 Ω + matching cable) 9600 to 115200</p> |
| RS-485 Port 2 | <p>Used for: Modbus RTU, PLC, SCADA, Remote monitoring (Insight) Data connection 2-wire + common, or 3-wire Not isolated</p> |

| Communication | |
|---------------|--|
| | External termination required (120 Ω + matching cable) 9600 to 115200 |
| RJ45 Ethernet | Used for: <ul style="list-style-type: none"> • Modbus to PLC, SCADA, and so on • NTP time synchronisation with NTP servers • PC utility software Isolated Auto detecting 10/100 Mbit Ethernet port |
| USB | Service port (USB-B) |

2.5 Approvals

| Standards |
|--|
| CE |
| UL/cUL Listed to - UL/ULC6200:2019 1.ed. Controllers for Use in Power Production |

NOTE Refer to www.deif.com for the most recent approvals.

2.5.1 UL/cUL Listed

| Requirements | |
|------------------------|--|
| Installation | To be installed in accordance with the NEC (US) or the CEC (Canada) |
| Enclosure | A suitable type 1 (flat surface) enclosure is required Unventilated/ventilated with filters for controlled/pollution degree 2 environment |
| Mounting | Flat surface mounting |
| Connections | Use 90 °C copper conductors only |
| Wire size | AWG 30-12 |
| Terminals | Tightening torque: 5-7 lb-in. |
| Current transformers | Use Listed or Recognized isolating current transformers |
| Communication circuits | Only connect to communication circuits of a listed system/equipment |

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