MVR-F201

4921240664A

Feeder protection

Data sheet

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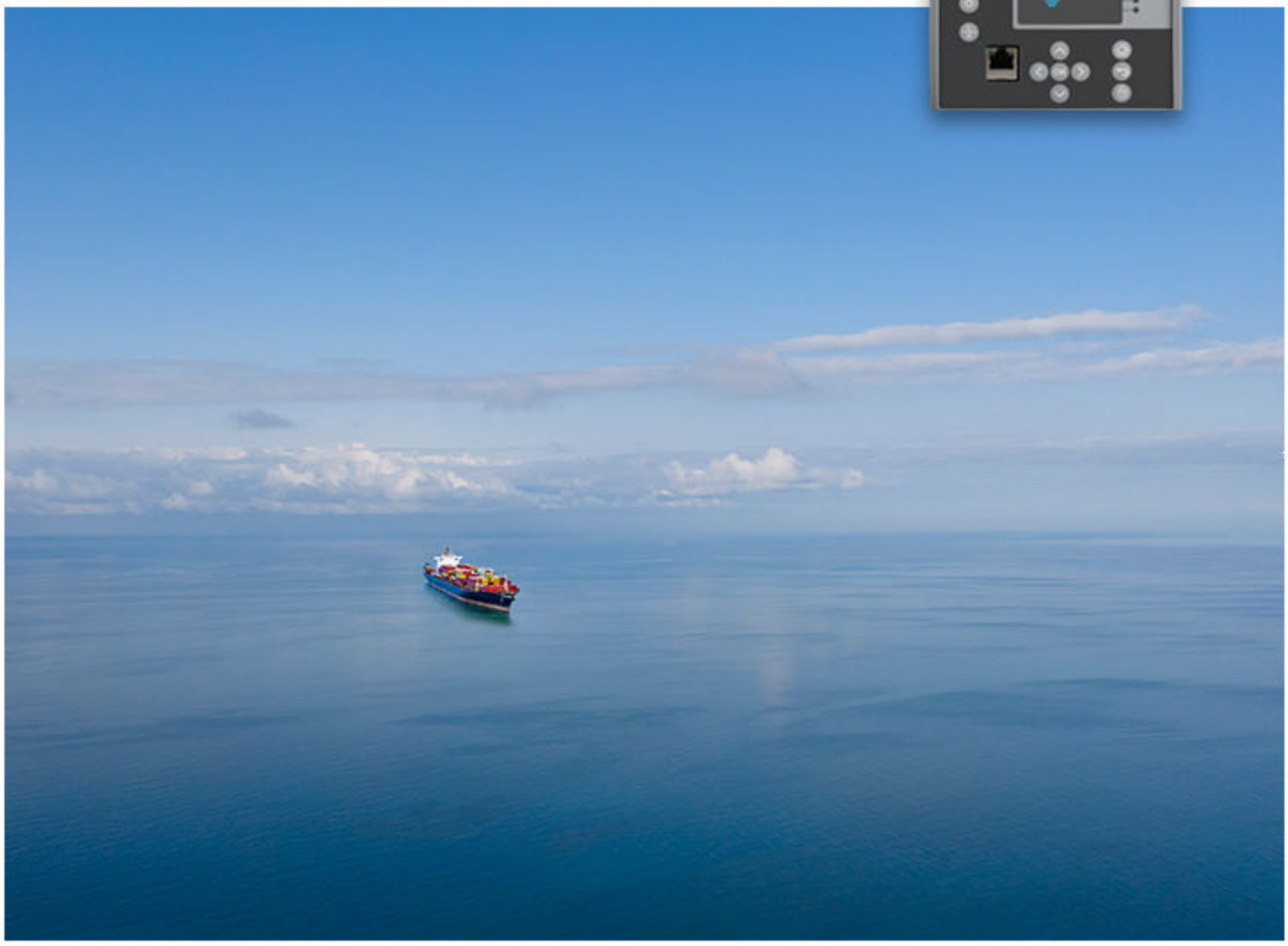

1. Product description

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1. Product description

1.1 About

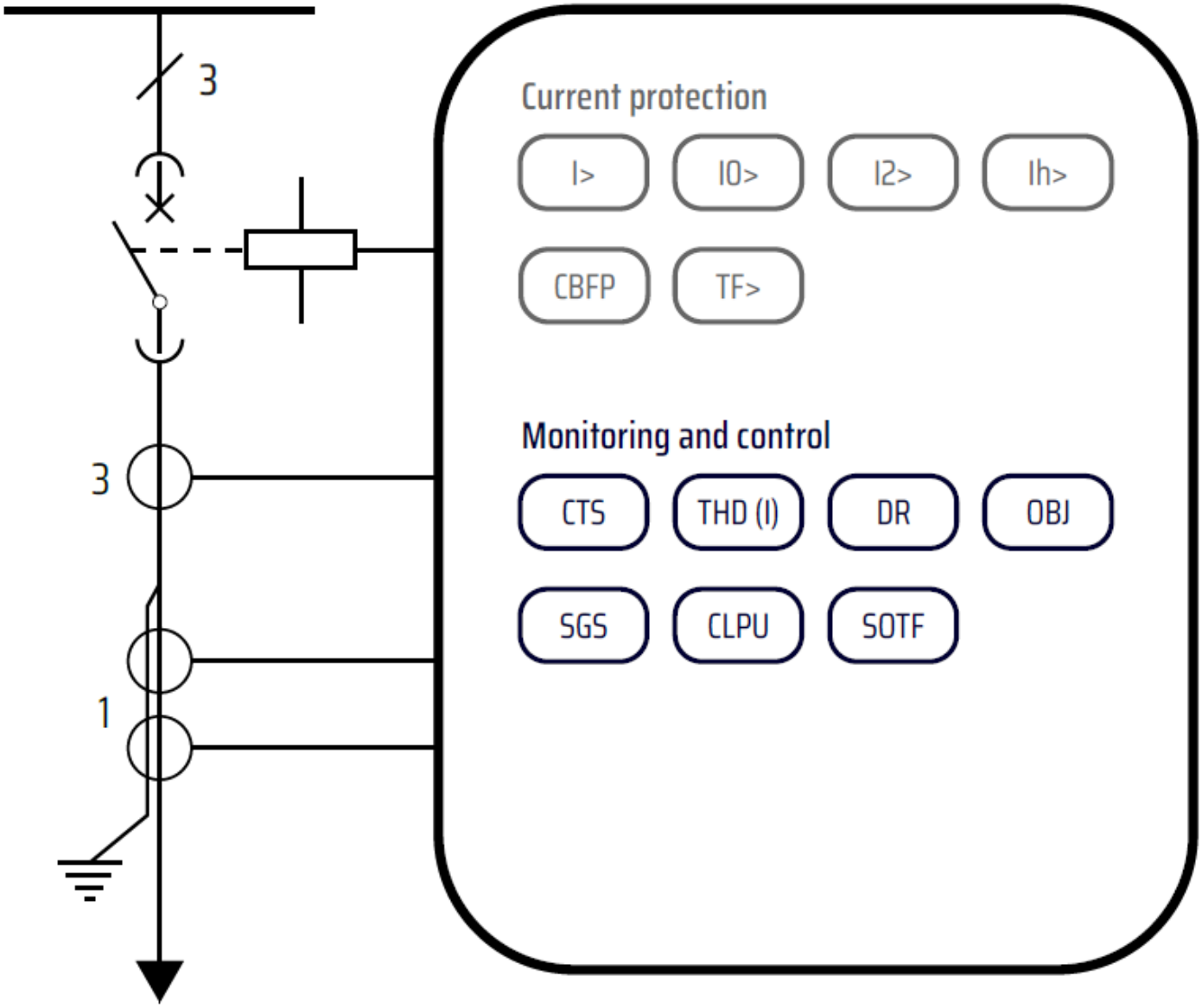
The MVR-F201 feeder protection relay offers a compact solution for any application that requires non-directional overcurrent and earth fault protections. The MVR-F201 has a selection of supportive functions for protection, measurement, monitoring, control, and communication as well as a large and programmable HMI.

1.2 Applications

A wiring example and key ANSI functions are shown below.

More information
See the **Protections** chapter for a full list of the protections.

Feeder protection wiring (F201)



1.3 Features

	Functions
High performance, good usability	• Basic protection for feeders • Bay control, alarm, measurement and monitoring • Large customisable HMI with configurable Mimic diagram • Configurable LEDs • Large flash memory for events, logs, recordings and documentation ◦ 15,000 events and 100 disturbance recordings • Easy-to-use and powerful MVR Utility Software for setting, configuration and analysing • Full set of communication protocols, including IEC 61850
Versatile protection design	• Fast, versatile and dependable protection functions over a wide frequency range (6 to 75 Hz) • Suitable for the most demanding protection applications
Modularity	• Fully modular hardware construction • Plug in more I/O or communication cards to meet the application requirements

Usability	• Sophisticated setting aids
	• Highly customisable HMI
	• Storage of PDF or other supportive documents
	• Extensive user log information
	  ◦ Setting changes
	  ◦ Other operational history

Performance	• Sub-cycle instantaneous trip times • Logics editor for ladder logic functionality • Up to 100 disturbance records, of up to 10 seconds each • 10,000 events stored in non-volatile memory
Savings in engineering time	• MVR Utility Software free-of-charge software suite with an intuitive and easy-to-use human-machine interface • Download all relay settings instantly using native 100 Mb/s Ethernet connection (front port or rear port)
Standardised hardware	• Standardised hardware design, for simpler logistics and stock management • Five CT inputs with configurable secondary currents • Configurable digital input voltage thresholds
Communication	• Native Ethernet communication • A variety of standard protocols

2. Protections

2.1 Current protections

2.1.1 Non-directional overcurrent protection (I>; 50/51)

Table 2.1 Technical data for the non-directional overcurrent function

Measurement inputs	
Current inputs	Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C)
Current input magnitudes	RMS phase currents TRMS phase currents Peak-to-peak phase currents
Pick-up	
Pick-up current setting	0.10...50.00 × I_n, setting step 0.01 × I_n
Inrush 2nd harmonic blocking	0.10...50.00 %I_{fund}, setting step 0.01 %I_{fund}
Inaccuracy: - Current - 2nd harmonic blocking	 ±0.5 %I_{set} or ±15 mA (0.10...4.0 × I_{set}) ±1.0 %-unit of the 2nd harmonic setting
Operation time	
Definite time function operating time setting	0.00...1800.00 s, setting step 0.005 s
Inaccuracy: - Definite time: I_m/I_{set} ratio > 3 - Definite time: I_m/I_{set} ratio = 1.05...3	 ±1.0 % or ±20 ms ±1.0 % or ±30 ms
IDMT setting parameters: - k Time dial setting for IDMT - A IDMT constant - B IDMT constant - C IDMT constant	 0.01...25.00, step 0.01 0...250.0000, step 0.0001 0...5.0000, step 0.0001 0...250.0000, step 0.0001
Inaccuracy: - IDMT operating time - IDMT minimum operating time	 ±1.5 % or ±20 ms ±20 ms
Retardation time (overshoot)	<30 ms
Instant operation time	
Start time and instant operation time (trip): - I_m/I_{set} ratio > 3 - I_m/I_{set} ratio = 1.05...3	 <35 ms (typically 25 ms) <50 ms
Start time and instant operation time (trip): - I_m/I_{set} ratio = 2 - I_m/I_{set} ratio = 5 - I_m/I_{set} ratio = 10	 Typically 25 ms Typically 16 ms Typically 12 ms
Reset	
Reset ratio	97 % of the pick-up current setting
Reset time setting Inaccuracy: Reset time	0.010...10.000 s, step 0.005 s ±1.0 % or ±50 ms
Instant reset time and start-up reset	<50 ms

NOTE The release delay does **not** apply to phase-specific tripping!

2.1.2 Non-directional earth fault protection (I0>; 50N/51N)

Table 2.2 Technical data for the non-directional earth fault function

Measurement inputs	
Current input (selectable)	Residual current channel I_{01} (Coarse) Residual current channel I_{02} (Fine) Calculated residual current: I_{L1} (A), I_{L2} (B), I_{L3} (C)
Current input magnitudes	RMS residual current (I_{01}, I_{02} or calculated I_0) TRMS residual current (I_{01} or I_{02}) Peak-to-peak residual current (I_{01} or I_{02})
Pick-up	
Used magnitude	Measured residual current I01 (1 A) Measured residual current I02 (0.2 A) Calculated residual current I0Calc (5 A)
Pick-up current setting	0.0001...40.00 × I_n, setting step 0.0001 × I_n
Inaccuracy: - Starting I01 (1 A) - Starting I02 (0.2 A) - Starting I0Calc (5 A)	 ±0.5 %$I0_{set}$ or ±3 mA (0.005...10.0 × I_{set}) ±1.5 %$I0_{set}$ or ±1.0 mA (0.005...25.0 × I_{set}) ±1.0 %$I0_{set}$ or ±15 mA (0.005...4.0 × I_{set})
Operating time	
Definite time function operating time setting	0.00...1800.00 s, setting step 0.005 s
Inaccuracy: - Definite time: I_m/I_{set} ratio > 3 - Definite time: I_m/I_{set} ratio = 1.05...3	 ±1.0 % or ±20 ms ±1.0 % or ±30 ms
IDMT setting parameters: - k Time dial setting for IDMT - A IDMT constant - B IDMT constant - C IDMT constant	 0.01...25.00, step 0.01 0...250.0000, step 0.0001 0...5.0000, step 0.0001 0...250.0000, step 0.0001
Inaccuracy: - IDMT operating time - IDMT minimum operating time	 ±1.5 % or ±20 ms ±20 ms
Retardation time (overshoot)	<30 ms
Instant operation time	
Start time and instant operation time (trip): - I_m/I_{set} ratio > 3.5 - I_m/I_{set} ratio = 1.05...3.5	 <50 ms (typically 35 ms) <55 ms
Reset	
Reset ratio	97 % of the pick-up current setting
Reset time setting Inaccuracy: Reset time	0.010...10.000 s, step 0.005 s ±1.0 % or ±50 ms
Instant reset time and start-up reset	<50 ms

NOTE The operation and reset time accuracy does **not** apply when the measured secondary current in I02 is 1...20 mA. The pick-up is tuned to be more sensitive and the operation times vary because of this.

2.1.3 Negative sequence overcurrent/ phase current reversal/ current unbalance protection (I2>; 46/46R/46L)

Table 2.3 Technical data for the current unbalance function

Measurement inputs	
Current inputs	Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C)
Current input calculations	Positive sequence current (I1) Negative sequence current (I2)
Pick-up	
Used magnitude	Negative sequence component I2pu Relative unbalance I2/I1
Pick-up setting	0.01...40.00 × I_n, setting step 0.01 × I_n (I2pu) 1.00...200.00 %, setting step 0.01 % (I2/I1)
Minimum phase current (at least one phase above)	0.01...2.00 × I_n, setting step 0.01 × I_n
Inaccuracy: - Starting I2pu - Starting I2/I1	 ±1.0 %-unit or ±100 mA (0.10...4.0 × I_n) ±1.0 %-unit or ±100 mA (0.10...4.0 × I_n)
Operating time	
Definite time function operating time setting	0.00...1800.00 s, setting step 0.005 s
Inaccuracy: - Definite time (I_m/I_{set} ratio > 1.05)	 ±1.5 % or ±60 ms
IDMT setting parameters: - k Time dial setting for IDMT - A IDMT Constant - B IDMT Constant - C IDMT Constant	 0.01...25.00, step 0.01 0...250.0000, step 0.0001 0...5.0000, step 0.0001 0...250.0000, step 0.0001
Inaccuracy: - IDMT operating time - IDMT minimum operating time	 ±2.0 % or ±30 ms ±20 ms
Retardation time (overshoot)	<5 ms
Instant operation time	
Start time and instant operation time (trip): - I_m/I_{set} ratio > 1.05	 <70 ms
Reset	
Reset ratio	97 % of the pick-up setting
Reset time setting Inaccuracy: Reset time	0.010...10.000 s, step 0.005 s ±1.5 % or ±60 ms
Instant reset time and start-up reset	<55 ms

2.1.4 Circuit breaker failure protection (CBFP; 50BF/52BF)

Table 2.4 Technical data for the circuit breaker failure protection function

Measurement inputs	
Current inputs	Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C) Residual current channel I_{01} (Coarse) Residual current channel I_{02} (Fine)

Current input magnitudes	RMS phase currents RMS residual current (I_{01}, I_{02} or calculated I_0)
Pick-up	
Monitored signals	Digital input status, digital output status, logical signals
Pick-up current setting: - IL1...IL3 - I01, I02, I0Calc	 0.10...40.00 × I_N, setting step 0.01 × I_N 0.005...40.00 × I_N, setting step 0.005 × I_N
Inaccuracy: - Starting phase current (5A) - Starting I01 (1 A) - Starting I02 (0.2 A) - Starting I0Calc (5 A)	 ±0.5 %I_{SET} or ±15 mA (0.10...4.0 × I_{SET}) ±0.5 %$I0_{SET}$ or ±3 mA (0.005...10.0 × I_{SET}) ±1.5 %$I0_{SET}$ or ±1.0 mA (0.005...25.0 × I_{SET}) ±1.0 %$I0_{SET}$ or ±15 mA (0.005...4.0 × I_{SET})
Operation time	
Definite time function operating time setting	0.050...1800.000 s, setting step 0.005 s
Inaccuracy: - Current criteria (I_M/I_{SET} ratio 1.05→) - DO or DI only	 ±1.0 % or ±55 ms ±15 ms
Reset	
Reset ratio	97 % of the pick-up current setting
Reset time	<50 ms

2.1.5 Harmonic overcurrent protection (Ih>; 50H/51H/68H)

Table 2.5 Technical data for the harmonic overcurrent function

Measurement inputs	
Current inputs	Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C) Residual current channel I_{01} (Coarse) Residual current channel I_{02} (Fine)
Pick-up	
Harmonic selection	2^{nd}, 3^{rd}, 4^{th}, 5^{th}, 6^{th} 7^{th}, 9^{th}, 11^{th}, 13^{th}, 15^{th}, 17^{th} or 19^{th}
Used magnitude	Harmonic per unit (× I_N) Harmonic relative (Ih/IL)
Pick-up setting	0.05...2.00 × I_N, setting step 0.01 × I_N (× I_N) 5.00...200.00 %, setting step 0.01 % (Ih/IL)
Inaccuracy: - Starting × I_N - Starting × Ih/IL	 <0.03 × I_N (2^{nd}, 3^{rd}, 5^{th}) <0.03 × I_N tolerance to Ih (2^{nd}, 3^{rd}, 5^{th})
Operation time	
Definite time function operating time setting	0.00...1800.00 s, setting step 0.005 s
Inaccuracy: - Definite time (I_M/I_{SET} ratio >1.05)	 ±1.0 % or ±35 ms
IDMT setting parameters: k Time dial setting for IDMT A IDMT constant B IDMT constant C IDMT constant	 0.01...25.00, step 0.01 0...250.0000, step 0.0001 0...5.0000, step 0.0001 0...250.0000, step 0.0001
Inaccuracy:	

- IDMT operating time - IDMT minimum operating time	±1.5 % or ±20 ms ±20 ms
Instant operation time	
Start time and instant operation time (trip): I_M/I_{SET} ratio >1.05	<50 ms
Reset	
Reset ratio	95 % of the pick-up setting
Reset time setting Inaccuracy: Reset time	0.010...10.000 s, step 0.005 s ±1.0 % or ±35 ms
Instant reset time and start-up reset	<50 ms

NOTE Harmonics generally: The amplitude of the harmonic content **must** be least 0.02 × I_N when the relative mode (Ih/IL) is used!

Blocking: To achieve fast activation for blocking purposes with the harmonic overcurrent stage, note that the harmonic stage may be activated by a rapid load change or fault situation. An intentional activation lasts for approximately 20 ms if a harmonic component is not present. The harmonic stage stays active if the harmonic content is above the pick-up limit.

Tripping: When using the harmonic overcurrent stage for tripping, please ensure that the operation time is set to 20 ms (DT) or longer to avoid nuisance tripping caused by the above-mentioned reasons.

2.2 Feeder protections

2.2.1 Line thermal overload protection (TF>; 49F)

Table 2.6 Technical data for the line thermal overload protection function

Measurement inputs	
Current inputs	Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C)
Current input magnitudes	TRMS phase currents (up to the 31st harmonic)
Settings	
Time constants τ	1
Time constant value	0.0...500.00 min, step 0.1 min
Service factor (maximum overloading)	0.01...5.00 × I_N, step 0.01 × I_N
Thermal model biasing	- Ambient temperature (Set –60.0...500.0 deg, step 0.1 deg) - Negative sequence current
Thermal replica temperature estimates	Selectable between °C and °F
Outputs	
- Alarm 1 - Alarm 2 - Thermal trip - Trip delay - Restart inhibit	0...150 %, step 1 % 0...150 %, step 1 % 0...150 %, step 1 % 0.000...3600.000 s, step 0.005 s 0...150 %, step 1 %
Inaccuracy	
- Starting - Operating time	±0.5 % of the set pick-up value ±5 % or ± 500 ms

2.3 Control functions

2.3.1 Cold load pick-up (68) CLP

Table 2.7 Technical data for the cold load pick-up function

Measurement inputs	
Current inputs	Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C)
Current input magnitudes	RMS phase currents
Pick-up	
Pick-up current setting - $I_{LOW}/I_{HIGH}/I_{OVER}$	0.01...40.00 × I_N, setting step 0.01 × I_N
Reset ratio	97 % of the pick-up current setting
Inaccuracy: - Current	±0.5 %I_{SET} or ±15 mA (0.10...4.0 × I_{SET})
Operation time	
Definite time function operating time settings: - t_{SET} - t_{MAX} - t_{MIN}	 0.000...1800.000 s, setting step 0.005 s 0.000...1800.000 s, setting step 0.005 s 0.000...1800.000 s, setting step 0.005 s
Inaccuracy: - Definite time (I_M/I_{SET} ratio = 1.05/0.95)	±1.0 % or ±45 ms
Instant operation time	
CLPU activation and release	<45 ms (measured from the trip contact)

NOTE A single-phase current (IL1, IL2 or IL3) is enough to prolong or release the blocking during an overcurrent condition.

2.3.2 Switch on to fault (SOTF)

Table 2.8 Technical data for the switch-on-to-fault function

Initialization signals	
SOTF activate input	Any blocking input signal (Object closed signal, etc.)
Pick-up	
SOTF function input	Any blocking input signal (I> or similar)
SOTF activation time	
Activation time	<40 ms (measured from the trip contact)
SOTF release time	
Release time setting	0.000...1800.000 s, setting step 0.005 s
Inaccuracy: - Definite time	±1.0 % or ±30 ms
SOTF instant release time	<40 ms (measured from the trip contact)

2.3.3 Object control and monitoring

Table 2.9 Technical data for the object control and monitoring function

General	
Number of objects	1
Supported object types	Circuit breaker Circuit breaker with withdrawable cart Disconnector (MC) Disconnector (GND)
Signals	
Input signals	Digital inputs Software signals
Output signals	Close command output Open command output
Operation time	
Breaker traverse time setting	0.02...500.00 s, setting step 0.02 s
Max. close/open command pulse length	0.02...500.00 s, setting step 0.02 s
Control termination time out setting	0.02...500.00 s, setting step 0.02 s
Inaccuracy: - Definite time operating time	±0.5 % or ±10 ms
Breaker control operation time	
External object control time	<75 ms
Object control during auto-reclosing	See the technical sheet for the auto-reclosing function.

Table 2.10 Technical data for the circuit breaker wear monitoring function

Pick-up	
Breaker characteristics settings: - Nominal breaking current - Maximum breaking current - Operations with nominal current - Operations with maximum breaking current	 0.00...100.00 kA, setting step 0.001 kA 0.00...100.00 kA, setting step 0.001 kA 0...200 000 operations, setting step 1 operation 0...200 000 operations, setting step 1 operation
Pick-up setting for Alarm 1 and Alarm 2	0...200 000 operations, setting step 1 operation
Inaccuracy	
Inaccuracy for current/operations counter: - Current measurement element - Operation counter	 0.1× I_N > I < 2 × I_N ±0.2 % of the measured current, rest 0.5 % ±0.5 % of operations deducted

2.3.4 Setting group selection

Table 2.11 Technical data for the setting group selection function

Settings and control modes	
Setting groups	8 independent, control-prioritized setting groups
Control scale	Common for all installed functions which support setting groups
Control mode	
Local	Any binary signal available in the device

Remote	Force change overrule of local controls either from the setting tool, HMI or SCADA
Operation time	
Reaction time	<5 ms from receiving the control signal

2.4 Monitoring functions

2.4.1 Circuit breaker wear monitoring

Table 2.12 Technical data for the circuit breaker wear monitoring function

Pick-up	
Breaker characteristics settings: - Nominal breaking current - Maximum breaking current - Operations with nominal current - Operations with maximum breaking current	 0.00...100.00 kA, setting step 0.001 kA 0.00...100.00 kA, setting step 0.001 kA 0...200 000 operations, setting step 1 operation 0...200 000 operations, setting step 1 operation
Pick-up setting for Alarm 1 and Alarm 2	0...200 000 operations, setting step 1 operation
Inaccuracy	
Inaccuracy for current/operations counter: - Current measurement element - Operation counter	 0.1× I_N > I < 2 × I_N ±0.2 % of the measured current, rest 0.5 % ±0.5 % of operations deducted

2.4.2 Disturbance recorder

Table 2.13 Technical data for the disturbance recorder function

Recorded values	
Recorder analog channels	0...20 channels Freely selectable
Recorder digital channels	0...95 channels Freely selectable analog and binary signals 5 ms sample rate (FFT)
Performance	
Sample rate	8, 16, 32 or 64 samples/cycle
Recording length	0.000...1800.000 s, setting step 0.001 s The maximum length is determined by the chosen signals.
Number of recordings	0...100, 60 MB of shared flash memory reserved The maximum number of recordings according to the chosen signals and operation time setting combined

2.4.3 Current transformer supervision

Table 2.14 Technical data for the current transformer supervision function

Measurement inputs	
Current inputs	Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C) Residual current channel I_{01} (Coarse) Residual current channel I_{02} (Fine)
Current input magnitudes	RMS phase currents RMS residual current (I_{01}, I_{02})

Pick-up	
Pick-up current settings: - I_{SET} high limit - I_{SET} low limit - I_{SUM} difference - I_{SET} ratio - I2/I1 ratio	 0.10...40.00 × I_N, setting step 0.01 × I_N 0.10...40.00 × I_N, setting step 0.01 × I_N 0.10...40.00 × I_N, setting step 0.01 × I_N 0.01...100.00 %, setting step 0.01 % 0.01...100.00 %, setting step 0.01 %
Inaccuracy: - Starting IL1, IL2, IL3 - Starting I2/I1 - Starting I01 (1 A) - Starting I02 (0.2 A)	 ±0.5 %I_{SET} or ±15 mA (0.10...4.0 × I_{SET}) ±1.0 %$I2_{SET}$ / $I1_{SET}$ or ±100 mA (0.10...4.0 × I_N) ±0.5 %$I0_{SET}$ or ±3 mA (0.005...10.0 × I_{SET}) ±1.5 %$I0_{SET}$ or ±1.0 mA (0.005...25.0 × I_{SET})
Time delay for alarm	
Definite time function operating time setting	0.00...1800.00 s, setting step 0.005 s
Inaccuracy_ - Definite time (I_M/I_{SET} ratio > 1.05)	 ±2.0 % or ±80 ms
Instant operation time (alarm): - I_M/I_{SET} ratio > 1.05	 <80 ms (<50 ms in differential protection relays)
Reset	
Reset ratio	97/103 % of the pick-up current setting
Instant reset time and start-up reset	<80 ms (<50 ms in differential protection relays)

2.4.4 Current total harmonic distortion

Table 2.15 Technical data for the total harmonic distortion function

Input signals	
Current inputs	Phase current inputs: I_{L1} (A), I_{L2} (B), I_{L3} (C) Residual current channel I_{01} (Coarse) Residual current channel I_{02} (Fine)
Current input magnitudes	Current measurement channels (FFT result) up to the 31st harmonic component.
Pick-up	
Operating modes	Power THD Amplitude THD
Pick-up setting for all comparators	0.10...200.00 % , setting step 0.01 %
Inaccuracy	±3 % of the set pick-up value > 0.5 × I_N setting; 5 mA < 0.5 × I_N setting.
Time delay	
Definite time function operating time setting for all timers	0.00...1800.00 s, setting step 0.005 s
Inaccuracy: - Definite time operating time - Instant operating time, when I_M/I_{SET} ratio > 3 - Instant operating time, when I_M/I_{SET} ratio 1.05 < I_M/I_{SET} < 3	 ±0.5 % or ±10 ms Typically <20ms Typically <25 ms
Reset	
Reset time	Typically <10 ms
Reset ratio	97 %

3. Technical specifications

3.1 Electromagnetic compatibility

Emission	Standard	Class	Value
Conducted Disturbance Emission	IEC 60255-26	A	0.15 to 30 MHz IACS E10 Setup according to CISPR 16. Conducted emission measured from 10kHz
	IEC 61000-6-4	A	
Radiated emission (below 1 GHz)	IEC 60255-26		30 to 1000 MHz
	IEC 61000-6-4	A	IACS E10 Setup according to CISPR 16. Radiated emission measured from 150 kHz to 2000 MHz
Radiated emission (above 1 GHz)	IEC 60255-26		1 to 6 GHz
	IEC 61000-6-4	A	

Immunity	Standard	Level	Value
Electrostatic Discharge	IEC 60255-26		8 kV air discharge
	IEC 61000-4-2 IACS E10	3	6 kV direct discharge
Radiated immunity	IEC 60255-26		10 V/m; 80 MHz to 1 GHz; 1.4 GHz to 2.7 GHz IACS E10 80 MHz to 2 GHz 10 V/m 3 s dwell time
	ENV 50204 (GSM)	3	10 V/m; 2 W at 0.6 m
Fast transient/burst immunity	IEC 60225-26		2 kV
	IEC 61000-4-4 IACS E10	3	2 kV 2 kV
Surge immunity	IEC 60255-26		1 kV symmetrical (line to line)
	IEC 61000-4-5 IACS E10	3	2 kV unsymmetrical (line to earth) 0.5 kV symmetrical (line to line) (only for IACS E10) 1 kV unsymmetrical (line to earth) (only for IACS E10)
Conducted immunity	IEC 60255-26		0.15 to 80 MHz; 10 V
	IEC 61000-4-6	3	IACS E10 3 s dwell time.
Power frequency magnetic field immunity	IEC 60255-26		30 A/m continuous
	IEC 61000-4-8	4	300 A/m; 1 s to 3 s
Pulse magnetic field immunity	IEC 61000-4-9	5	1000 A/m
Damped oscillatory magnetic field immunity	IEC 61000-4-10	4	30 A/m
Oscillatory transient immunity – Ring wave	IEC 61000-4-12	4	100 kHz 4 kV common mode
			2 kV differential mode
Oscillatory transient immunity – Slow damped oscillatory wave	IEC 61000-4-18 ANSI/IEEE Std C37.90.1	3	100 kHz 1 kV differential mode 2.5 kV common mode
Oscillatory transient immunity – Slow damped oscillatory wave	IEC 60255-26 IEC 61000-4-18	3	1.0 MHz 2.5 kV common mode
	ANSI/IEEE Std C37.90.1		2.5 kV differential mode

Immunity	Standard	Level	Value
Voltage dips	IEC 60255-26		0 %
	IEC 61000-4-11		DC 10 ms
	IEC 61000-4-29		AC 0.5 cycle (10 ms)
Voltage dips	IEC 60255-26		40 %
	IEC 61000-4-11		DC 200 ms
	IEC 61000-4-29		AC 10/12 cycles (10 ms) Tested both 50/60 Hz
Voltage dips	IEC 60255-26		70 %
	IEC 61000-4-11		DC 500 ms
	IEC 61000-4-29		AC 25/30 cycles (10 ms)
Voltage interruptions	IEC 60255-26		0 %
	IEC 61000-4-11 IACS E10		DC 5 s (3 interruptions w. 10 s interval) DC 30 s/60 s (3 interruptions w. 60 s interval)
	IEC 61000-4-29 IACS E10		AC 250 cycles (5 s) (3 interruptions w. 10 s interval) AC 30 s (3 interruptions w. 90 s interval) 1 additional interruption during booting
Voltage variations permanent	IACS E10		DC +30 % 24H DC -15 % 15 min AC +6 % V AC/+5 % Hz 15 min AC +6 % V AC/-5 % Hz 15 min AC -10 % V AC/-5 % Hz 15min AC -10 % V AC/+5 % Hz 15 min
Voltage variations transient	IACS E10		AC +20 % V AC 1.5 s/+10 % Hz 5 s AC -20 % V AC 1.5 s/-10 % Hz 5 s
Ripple	IEC 60255-26		15 % of DC; 100 Hz
	IEC 61000-4-17		
Power Frequency Immunity	IEC 60255-26		150 V, 50 Hz, common mode
	IEC 61000-4-16		300 V, 50 Hz, differential mode

3.2 Mechanical durability

Energised	Standard	Class	Value
Vibration response	IEC 60255-27 IEC 60255-21-1	2	10 to 58.1 Hz: 0.15 mmpp 58.1 to 150 Hz: 1 g 1 cycle in each axis
Vibration	IACS E10		3 to 13.2 Hz 2 mmpp 13.2 to 100 Hz 0.7 g
Shock response	IEC 60255-27 IEC 60255-21-2	2	10 g; 11 ms

De-energised	Standard	Class	Value
Vibration endurance	IEC 60255-27 IEC 60255-21-1	2	10 to 150 Hz; 2 g acceleration; 20 sweep cycles
Shock withstand	IEC 60255-27	2	30 g; 11 ms

De-energised	Standard	Class	Value
	IEC 60255-21-2		
Bump	IEC 60255-27 IEC 60255-21-2	2	20 g; 16 ms

3.3 Environment

General	Standard	Value
Cold non-operation	I EC 60255-27 IEC 60255-1 IACS E10	-25 °C; 16 h
Dry heat operation	IEC 60255-27 IEC 60255-1 IACS E10	60 °C; 16 h
Damp heat (static)	IEC 60255-27 IEC 60255-1	55 °C; 93 % RH; 10 days
Cyclic temperature with humidity (damp heat cyclic)	IEC 60255-27 IEC 60255-1 IACS E10	55 °C @ 93 % RH; 25 °C @ 97 % RH, 12 h + 12 h; 6 cycles 55 °C @ 95 % RH; 12 h + 12 h; 2 cycles
Change of temperature	IEC 60255-1	5 cycles; -25 °C to 70 °C

Storage	Standard	Value
Low temperature storage	IEC 60255-27 IEC 60255-1	-40 °C; 16 h
High temperature storage	IEC 60255-27 IEC 60255-1	70 °C; 16 h

3.4 Safety

Electrical	Standard	Value
Insulation resistance	IEC 60255-27 IACS E10	Before environmental tests: >100 MΩ at DC 500 V >100 MΩ at DC 500 V (Uw >65 V) >10 MΩ at DC 50 V (Uw <65 V) After environmental tests: >10 MΩ at DC 500 V (Uw >65 V) >1 MΩ at DC 50 V (Uw <65 V)
Reverse polarity	IEC 60255-27	
Gradual shut down/start-up tests	IEC 60255-27	
Impulse voltage	IEC 60255-27	5 kV; 1.2/50 µs; 0.5 J
Power frequency dielectric withstand	IEC 60255-27	3.5 kV; 50 Hz; 1 min (PS, DI, DO, I, RS485 AO) 4.35 kV; 50 Hz; 1 min (U)
Protective bonding impedance	IEC 60255-27	<0.1 Ω at 20 A 60 s
Insulation class		Class I
Over-voltage CAT	IEC 60255-27	III

Enclosure	Standard	Value
Dust/water ingress	IEC 60255-27 IEC 60529	IP 54 (front), IP 20 (back)

4. Hardware

4.1 Processor and power supply

Table 4.1 General information for the CPU module

Terminal block connection	
Screw connection terminal block (standard)	Phoenix Contact MSTB 2,5/5-ST-5,08
Spring cage terminal block (option)	Phoenix Contact FKC 2,5/20-STF-5,08
Solid or stranded wire Nominal cross section	2.5 mm^2
RS-485 serial terminal block connection	
Screw connection terminal block (standard)	Phoenix Contact MC 1,5/ 5-ST-3,81
Spring cage terminal block (option)	Phoenix Contact FK-MCP 1,5/ 5-ST-3,81
Solid or stranded wire Nominal cross section	1.5 mm^2

4.1.1 Auxiliary supply

Table 4.2 Power supply model H

Rated values	
Rated auxiliary voltage	100...120 V DC
Power consumption	< 7 W (no option cards)
Maximum permitted interrupt time	< 60 ms with 110 VDC
DC ripple	< 15 %
Other	
Minimum recommended fuse rating	MCB C2

Table 4.3 Power supply model L

Rated values	
Rated auxiliary voltage	24...48 VDC
Power consumption	< 7 W (no option cards)
Maximum permitted interrupt time	< 90 ms with 24 VDC
DC ripple	< 15 %
Other	
Minimum recommended fuse rating	MCB C2

4.1.2 Isolated digital inputs

Table 4.4 CPU model-isolated digital inputs, with thresholds defined by order code

Number of digital inputs	3
Rated values	
Rated auxiliary voltage	265 V (AC/DC)

Nominal voltage	Order code defined: 24, 110, 220 V (AC/DC) **Caution:** When the working voltage is above 150 V AC, do not mix AC and DC voltage inside any relay groups or digital input groups.
Pick-up threshold Release threshold	Order code defined: 19, 90,170 V Order code defined: 14, 65, 132 V
Scanning rate	5 ms
Settings	
Pick-up delay	Software settable: 0...1800 s
Polarity	Software settable: Normally On/Normally Off
Current drain	2 mA

4.1.3 Digital outputs

Table 4.5 Digital outputs (Normally Open)

Number of digital outputs	4
Rated values	
Rated auxiliary voltage	265 V (AC/DC) **Caution:** When the working voltage is above 150 V AC, do not mix AC and DC voltage inside any relay groups or digital input groups.
Continuous carry	5 A
Make and carry 0.5 s Make and carry 3 s	30 A 15 A
Breaking capacity, DC (L/R = 40 ms) at 48 VDC at 110 VDC at 220 VDC	 1 A 0.4 A 0.2 A
Control rate	5 ms
Settings	
Polarity	Software settable: Normally Open / Normally Closed

Table 4.6 Digital outputs (Change-Over)

Number of digital outputs	1 configurable (plus 1 for fault signaling)
Rated values	
Rated auxiliary voltage	265 V (AC/DC) **Caution:** When the working voltage is above 150 V AC, do not mix AC and DC voltage inside any relay groups or digital input groups.
Continuous carry	2.5 A
Make and carry 0.5 s Make and carry 3 s	30 A 15 A
Breaking capacity, DC (L/R = 40 ms) at 48 VDC at 110 VDC at 220 VDC	 1 A 0.3 A 0.15 A
Control rate	5 ms
Settings	
Polarity	Software settable: Normally Open / Normally Closed

4.1.4 Communication ports

Front panel local communication port	
Port, media	Ethernet RJ-45, Copper
Number of ports	1
Port protocols	PC-protocols, FTP, Telnet
Data transfer rate	100 MB
System integration	Cannot be used for system protocols, only for local programming
Rear panel system communication port A	
Port, media	Ethernet RJ-45, Copper
Number of ports	1
Port protocols	Modbus TCP, DNP 3.0, FTP, Telnet, IEC 61850, IEC-104
Data transfer rate	100 MB
System integration	Can be used for system protocols and for local programming
Rear panel system communication port B	
Port, media	RS-485, Copper
Number of ports	1
Port protocols	Modbus RTU, DNP 3.0, IEC-103, IEC-101, SPA
Data transfer rate	65580 kB/s
System integration	Can be used for system protocols

4.2 Current measurement module

Table 4.7 Technical data for the current measurement module

Connections	
Measurement channels/CT inputs	Three phase current inputs: IL1 (A), IL2 (B), IL3 (C) Two residual current inputs: Coarse residual current input I01, Fine residual current input I02
Phase current inputs (A, B, C)	
Sample rate	64 samples per cycle in frequency range 6...75Hz
Rated current I_N	5 A (configurable 0.2...10 A) 5 A (configurable 0.2...20 A)
Thermal withstand	20 A (continuous) 100 A (for 10 s) 500 A (for 1 s) 1250 A (for 0.01 s)
Frequency measurement range	From 6...75Hz fundamental, up to the 31st harmonic current
Current measurement range	25 mA...250 A (RMS)
Current measurement inaccuracy	0.005...4.000 × I_N < ±0.5 % or < ±15 mA 4...20 × I_N < ±0.5 % 20...50 × I_N < ±1.0 %
Temperature-dependent current measurement inaccuracy	Reference temperature: 25 °C Operation temperature range: -25 to 55 °C Inaccuracy: An additional ±15 mA per 10 °C
Angle measurement inaccuracy	< ±0.2° (I> 0.1 A)

	< ±1.0° (I≤ 0.1 A)
Burden (50/60 Hz)	<0.1 VA
Transient overreach	<8 %
Coarse residual current input (I01)	
Rated current I_N	1 A (configurable 0.1...10 A)
Thermal withstand	25 A (continuous) 100 A (for 10 s) 500 A (for 1 s) 1250 A (for 0.01 s)
Frequency measurement range	From 6...75 Hz fundamental, up to the 31st harmonic current
Current measurement range	5 mA...150 A (RMS)
Current measurement inaccuracy	0.002...10.000 × I_N < ±0.5 % or < ±3 mA 10...150 × I_N < ±0.5 %
Temperature-dependent current measurement inaccuracy	Reference temperature: 25 °C Operation temperature range: -25 to 55 °C Inaccuracy: An additional ±0.8 mA per 10 °C
Angle measurement inaccuracy	< ±0.2° (I> 0.05 A) < ±1.0° (I≤ 0.05 A)
Burden (50/60Hz)	<0.1 VA
Transient overreach	<5 %
Fine residual current input (I02)	
Rated current I_N	0.2 A (configurable 0.001...10 A)
Thermal withstand	25 A (continuous) 100 A (for 10 s) 500 A (for 1 s) 1250 A (for 0.01 s)
Frequency measurement range	From 6...75 Hz fundamental, up to the 31st harmonic current
Current measurement range	1 mA...75 A (RMS)
Current measurement inaccuracy	0.002...25.000 × I_N < ±0.5 % or < ±0.6 mA 25...375 × I_N < ±1.0 %
Temperature-dependent current measurement inaccuracy	Reference temperature: 25 °C Operation temperature range: -25 to 55 °C Inaccuracy: An additional ±0.4 mA per 10 °C
Angle measurement inaccuracy	< ±0.2° (I> 0.01 A) < ±1.0° (I≤ 0.01 A)
Burden (50/60Hz)	<0.1 VA
Transient overreach	<5 %
Screw connection terminal block (standard)	
Terminal block	Phoenix Contact FRONT 4-H-6,35
Solid or stranded wire Nominal cross section	4 mm^2
Ring lug terminal block connection (option)	
Ring terminal dimensions	Max 8mm diameter, with minimum 3,5mm screw hole

NOTE Current measurement accuracy has been verified with 50/60 Hz.

The amplitude difference is 0.2 % and the angle difference is 0.5 degrees higher at 16.67 Hz and other frequencies.

4.3 Frequency measurement

Table 4.8 Frequency measurement accuracy.

Frequency measurement performance	
Frequency measuring range	6...75 Hz fundamental, up to the 31st harmonic current
Inaccuracy	20 mHz*

NOTE If one of these conditions is met, the frequency inaccuracy is ±30 mHz:

- f ≠ 50 Hz or 60 Hz.
- Frequency tracking via voltages is applied.
- U < 15 V.

4.4 MVR-21x display

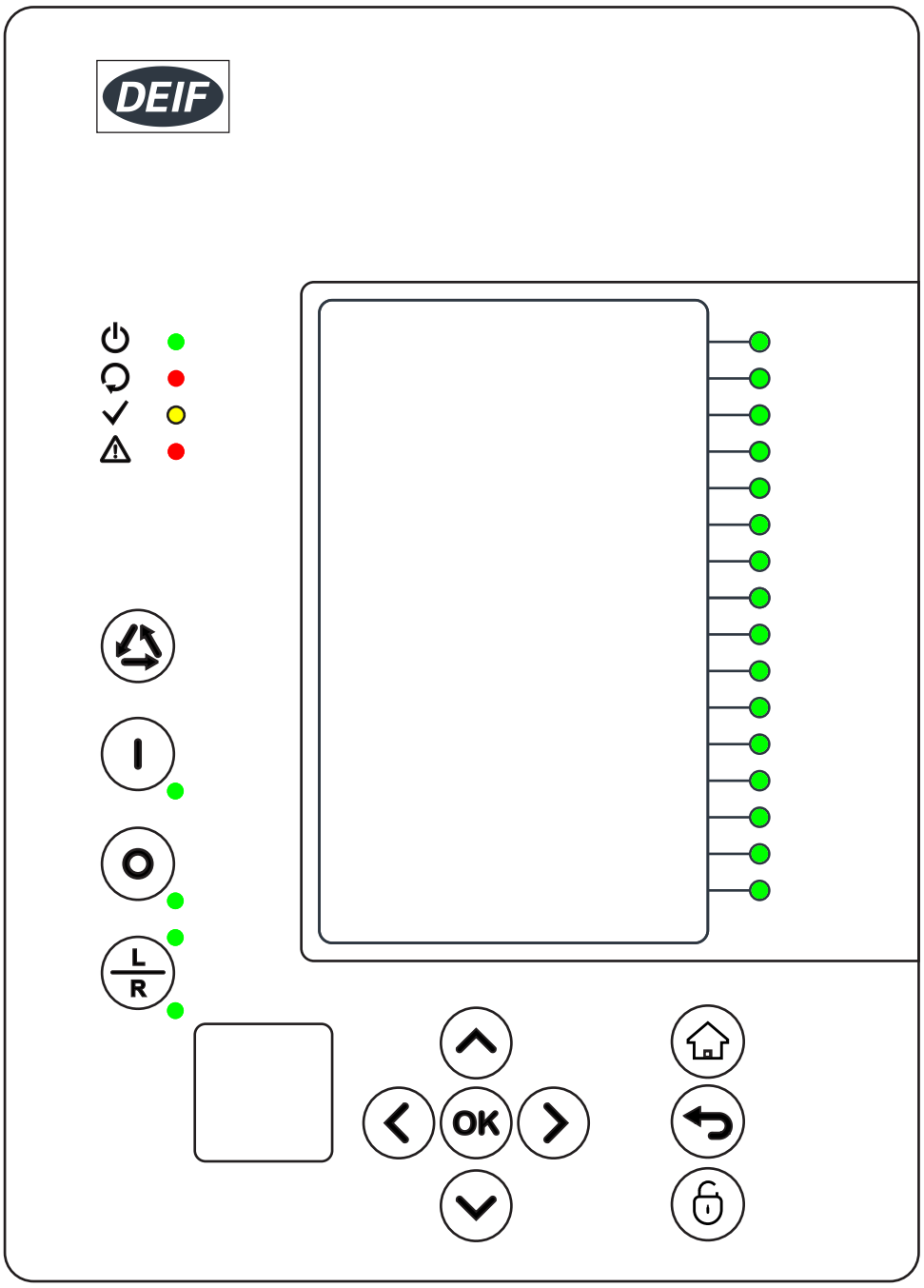
4.4.1 Display

Table 4.9 Technical data for the HMI LCD display

Dimensions and resolution	
Number of dots/resolution	320 x 160
Size	84.78 × 49.90 mm (3.34 × 1.96 in)
Display	
Type of display	LCD
Color	Monochrome

4.5 Folios and configuration

MVR-21x folio



To meet marine class society requirements:

- The MVR must be configured so that the **Trip LED** (⚠ ●) is lit whenever a protection activates a breaker trip.
- For each trip protection, select *Trip ON* in the NOC EventMask. In this way, the cause of any trip is shown on the main screen and immediately visible to the operator.

4.6 Mechanical specifications

Device dimensions	210 series casing height	¼ rack 4U, depth 210 mm
Package dimensions (W x H x D)	210 series	230 x 120 x 210 mm
Weight	Device	1.5 kg
	In package	2.0 kg

Material	Housing	Metal
IP protection level	Front	IP54
	Rear	IP20
Tightening torque - M4 nuts	Front	1.3 N·m for 210 series

4.7 Environment

IEC 60255-27 degree of pollution	2
Maximum altitude above sea level	2000 m (6561.68 ft)
Operation temperature range	-25 °C to +60 °C

4.8 Safety

Wiring specification

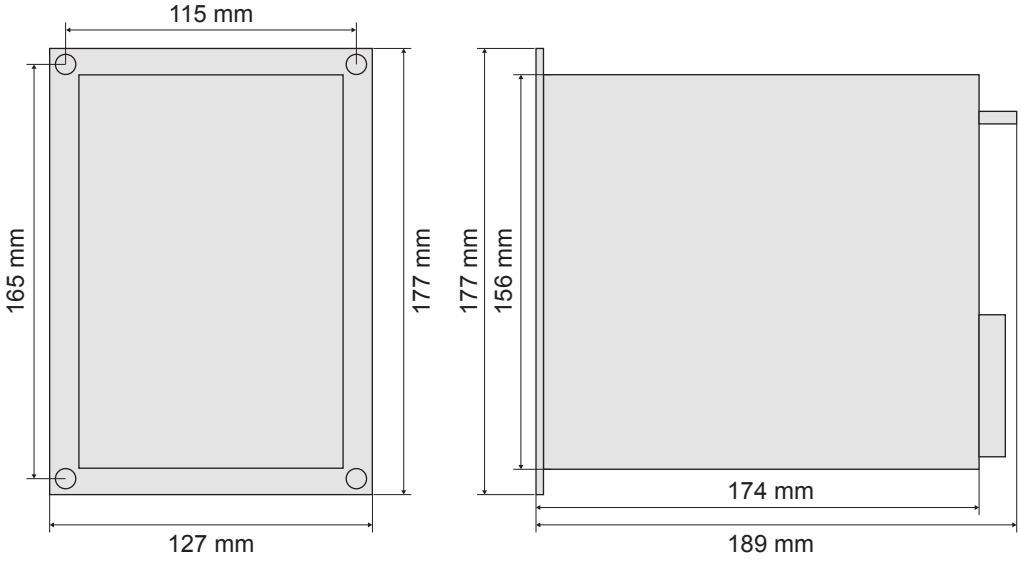
Wiring must be multi-stranded, minimum 90 °C copper conductors only.

Galvanic isolation

Ethernet: 550 V, 50 Hz, 1 minute
COM ports: 550 V, 50 Hz, 1 minute
Between Option I (mA I/O) and other I/O ports: 550 V, 50 Hz, 1 minute
Between CT and other I/O ports: 2200 V, 50 Hz, 1 minute
Between Relay and other I/O ports: 2200 V, 50 Hz, 1 minute
Between DI and other I/O ports: 2200 V, 50 Hz, 1 minute
Between PSU and other I/O ports: 2200 V, 50 Hz, 1 minute

4.9 Dimensions

MVR-210 dimensions



5. Ordering information

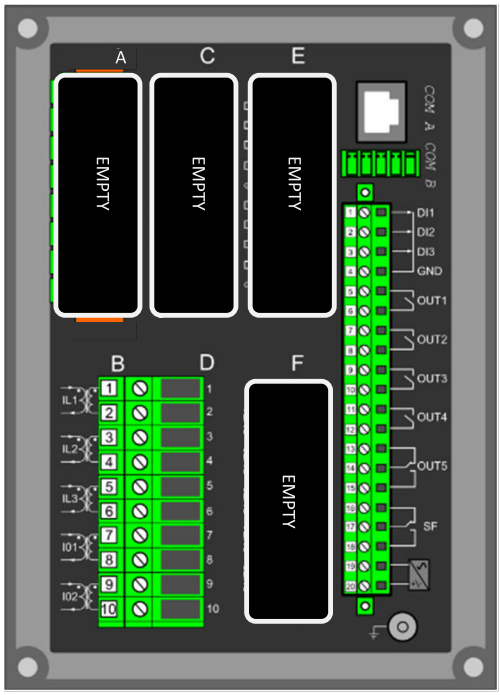
5.1 MVR Ordering

The drawings show the rear view of the MVR without hardware options.

MVR Feeder relay MVR-F201

MVR-F201 -P□8□A□A

- A: 3 DI 24 V on processor module
- B: 3 DI 110 V on processor module
- C: 3 DI 220 V on processor module
- A: Standard AC current terminal block
- B: Ring lug AC current terminal block
- H: 100-125 V DC Aux. Voltage
- L: 24-48 V DC Aux. Voltage



Additional features

- 5-year extended warranty
- Conformal coating of printed circuit boards

NOTE These features have to be ordered separately.

5.2.1 Disclaimer

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